## Ball Plunger Switch

Machine Components with a Built-in Switch series
www.metrol.co.jp/en
BP
1 signal plunger type (Contacting ball type)
Indexing check / sliding touch type

## Features

## Two functions in one, a touch switch built into the ball plunger.

Able to provide identifying and positioning functions using notches on index rotating or sliding objects as well as output a confirmation signal.

Reduces the number of components and design man-hours, allowing miniaturization of the machine.

For customers selecting contact force of $1 \mathbf{N}(-F)$


Please select CS-Touch Switch (refer to P4-3) in case of position or presence detection by straight travel contact and not for sliding.

## OCS-Touch Switch provides long stroke with small

 pre-travel making signal setting easy.Standard specification

| Indexing check |  | unit: mm |
| :--- | :---: | :--- |
| Product name | Contact force(N) (axial direction) | with LED |
| BP060A | min.6 max.13 | BP060A -L |


| Sliding touch |  | unit: mm |
| :--- | :---: | :--- |
| Product name | Contact force(N) (axial direction) | with LED |
| BP060A -F | 1 | BP060A -LF |

[^0]OThe edge surface has not been tempered. Do NOT use it as a stopper.

Common specification

| Switch structure | Dry contact |
| :--- | :--- |
| Output mode | A : Normally open |
| Signal point | 0.5 from surface |
| Stroke | 0.8 |
| Repeatability | Both On $\rightarrow$ Off, Off $\rightarrow$ On/ 0.01 <br> $(\text { At operating speed } 50-200 \mathrm{~mm} / \mathrm{min})^{*}$ |
| Movement differential | 0 |
| Protective structure | IP40 |
| Contact life time(Spring) | 3 million |
| Contact material | SUS 440 HRC 50- |
| Case material | SUS 303 |

*Operating speed slower than $10 \mathrm{~mm} / \mathrm{min}$ is not recommended.
unit: mm

| Cable <br> (Refer to P2-9) | Standard length 2m Oil resistant $\phi 2.8 / 2$ cores, <br> Tensile strength 30N, minimum bending R7 <br> Cable protector (Detachable) |
| :--- | :--- |
| Operating temperature range | $0^{\circ} \mathrm{C}-80^{\circ} \mathrm{C}$ (Ice-free) |$\quad$| Temperature drift | 0 (because of no amplifier) |
| :--- | :--- |
| Oscillation | $10-55 \mathrm{~Hz}$ total amplitude 1.5 for X,Y,Z each direction |
| Impact | $300 \mathrm{~m} / \mathrm{s}^{2}$ for X,Y,Z each direction |
| Contact rating <br> (Refer to P7-3) | DC5V-DC24V Steady current : 10 mA or less <br> (rush current: 20 mA or less) <br> When using the switch with LED, limit the |
| current below 10mA. |  |

## Caution

Use the lower torque (i.e. torque corresponding to L1 and L3) while tightening the bolt between lengths L1 and L2 or L2 and L3 in the picture. Please make sure to use a locknut if the bolt is likely to shift in position due to the vibrational impacts.


1 signal seating check, plunger type
BP060A (A: NO)

## Options

| Product name |
| :--- |
| BP060A |
|  |

> e.g.) BP060A-L


## Contact force <br> Blank: Standard

F: 1 N

L: Tubular type


## How to use

Suitable for angled touch


When using for rotation indexing, adjust the position in consideration of eccentricity and core blurring accuracy of rotating objects.
According to the operating circumstance, the signal point varies due to wear of the contacting part.
Carefully calculate the angle and roughness of chamfer so that the contacting part is not easily worn off.
Try not to bend the threaded part during installation. It will cause malfunction.

Circuit diagram

| without LED | with LED |
| :---: | :---: |
|  | Normally open (NO) |
| Normally open (NO) | OBrown |
| OBlue | LED Normally Off |

Electrical specification / circuit diagram. (Refer to P2-1)
When using the switches with LED option, limit the current below 10mA. (Refer to P7-3 "Confirmation of switch operation")


[^0]:    -F: Contact force 1N
    -L: LED indicator ( 120 mm from the sensor)

