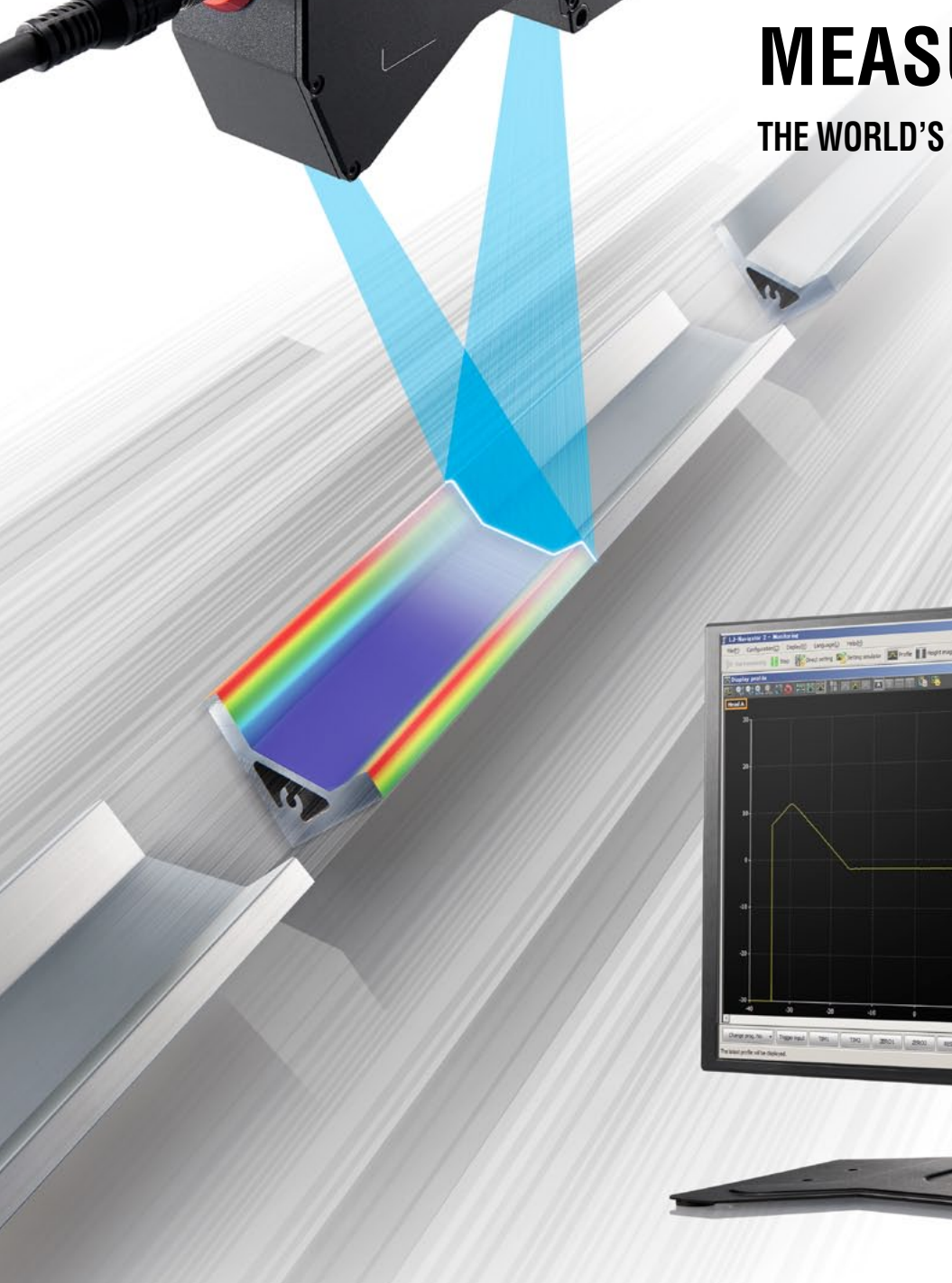




INLINE PROFILE MEASUREMENT

THE WORLD'S FASTEST AT 64000 PROFILES/SEC.



OFFERING A SOLUTION TO ANY PROBLEM

2D/3D Laser Scanner

LJ-V Series

CONTACT-TYPE MEASURING SENSORS

With contact-type sensors, **scratches** are an inevitable concern. In addition, **soft objects** can sometimes be troublesome and unmeasurable. User-caused **variations in the inspection results** also prove difficult to improve.



Workpiece contact and
human errors



NON-CONTACT MEASUREMENT

Direct measurement using a laser

No damage to workpieces

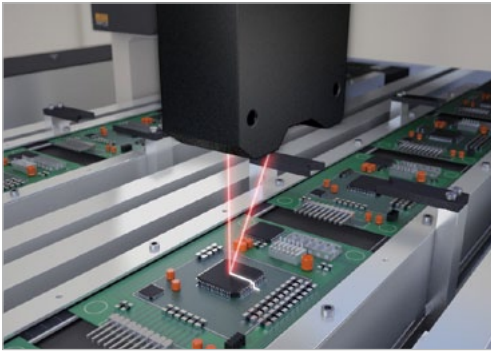
No variation in results from person to person

No need to stop the line



1D LASER DISPLACEMENT SENSORS

For measurements such as height difference and warpage, **installing multiple sensors** or **moving the sensor** is necessary. **Securing sufficient space** is also difficult, and measurements are **time-consuming**.



Multiple units
required



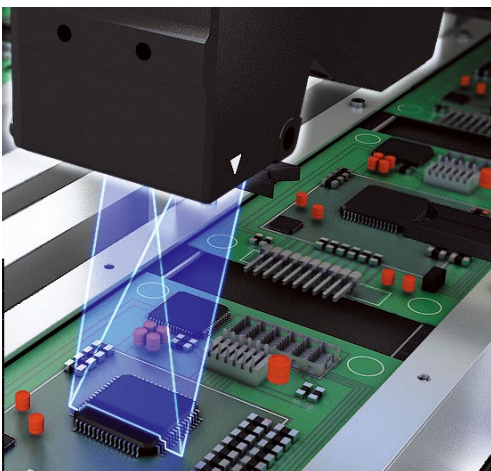
ONE DEVICE FOR MULTIPLE SOLUTIONS

Measure once with a 2D laser

Various measurement modes

Compact, space-saving design

No need to move the sensor



CAMERA INSPECTION MACHINES

Installing lighting can be troublesome, in although area cameras and line cameras can be used to inspect aspects such as width or position; inspecting **height and height difference** is not possible.



X and Y planes
only



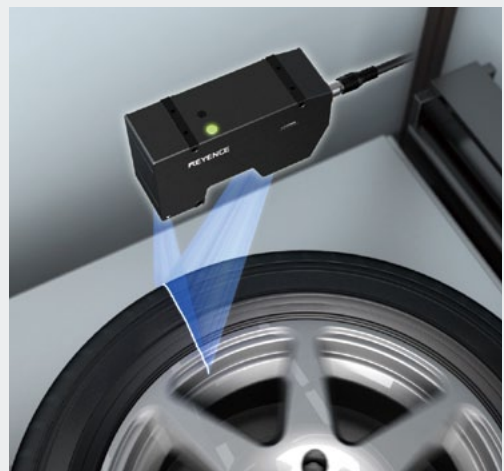
X, Y, AND Z PLANES WITH A SINGLE DEVICE

3D imaging with
additional image processing

No lights necessary

Height measurement

No color errors caused by color irregularity

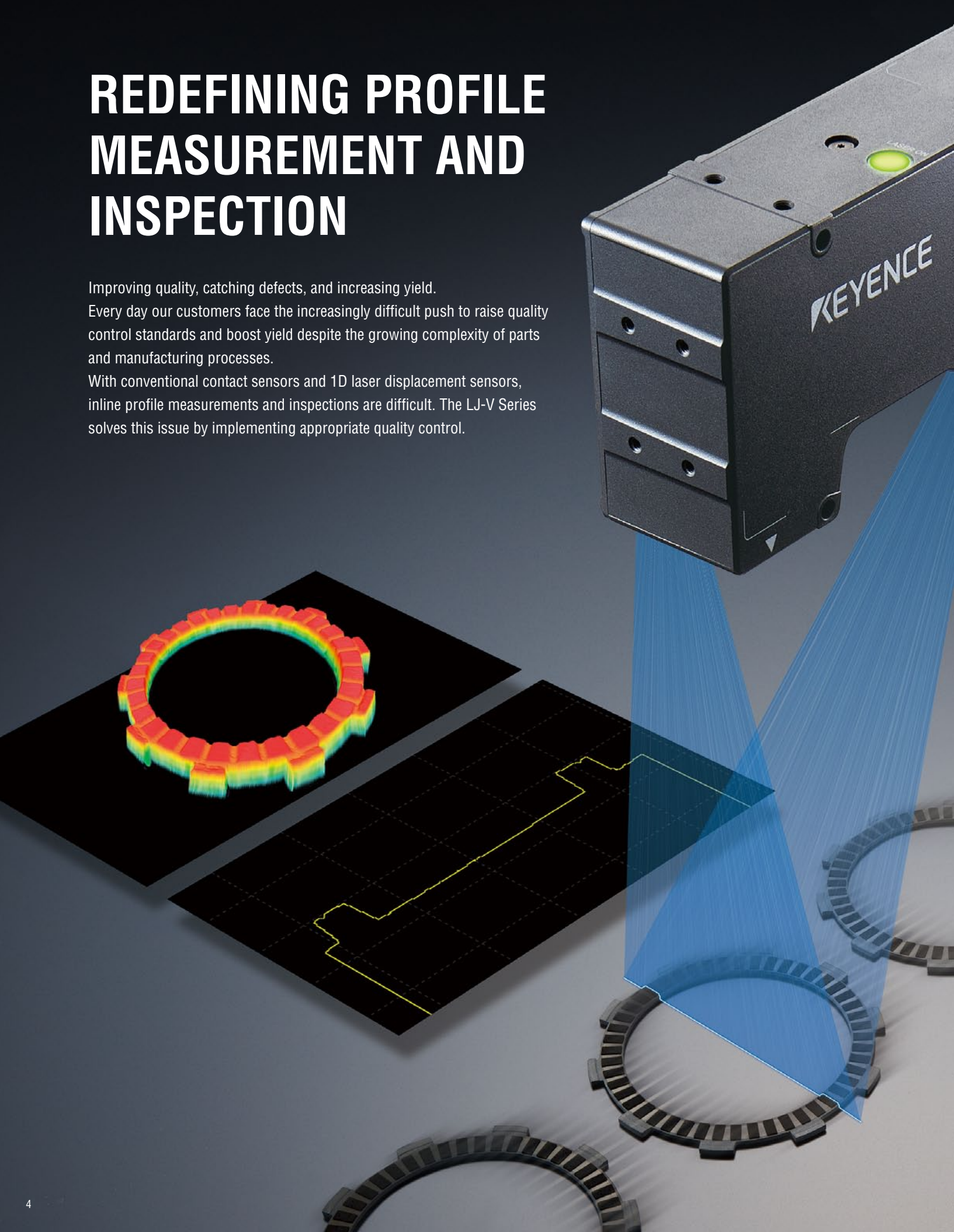


REDEFINING PROFILE MEASUREMENT AND INSPECTION

Improving quality, catching defects, and increasing yield.

Every day our customers face the increasingly difficult push to raise quality control standards and boost yield despite the growing complexity of parts and manufacturing processes.

With conventional contact sensors and 1D laser displacement sensors, inline profile measurements and inspections are difficult. The LJ-V Series solves this issue by implementing appropriate quality control.





WORLD'S FASTEST!

01

ULTRA-HIGH-SPEED SAMPLING

The LJ-V Series is the fastest 2D laser measuring instrument in the world.* This makes it possible to measure parts moving at extremely high speeds, in high definition, without missing a single one.

* According to KEYENCE's investigation (as of June 2013)

INDUSTRY'S VARIETY!

02

OVERWHELMING WORKPIECE RESPONSE CAPABILITIES AND DETECTION STABILITY

Profiles are accurately measured even in cases where black surfaces, inclines with low reflectivity and metallic surfaces with high reflectivity are mixed together under the same optical axis.

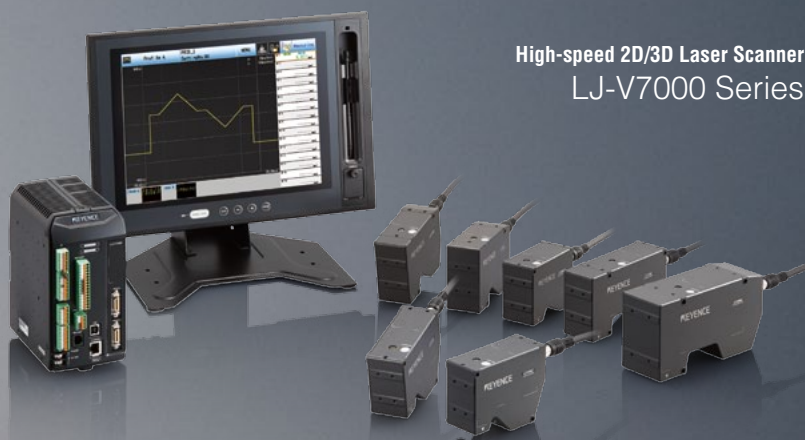
Our newly developed HSE³-CMOS wide dynamic range has provided the LJ-V Series with improvements in both speed and detection stability.

INDUSTRY FIRST

03

ALL TYPES OF MEASUREMENTS ARE POSSIBLE WITH THIS SINGLE DEVICE

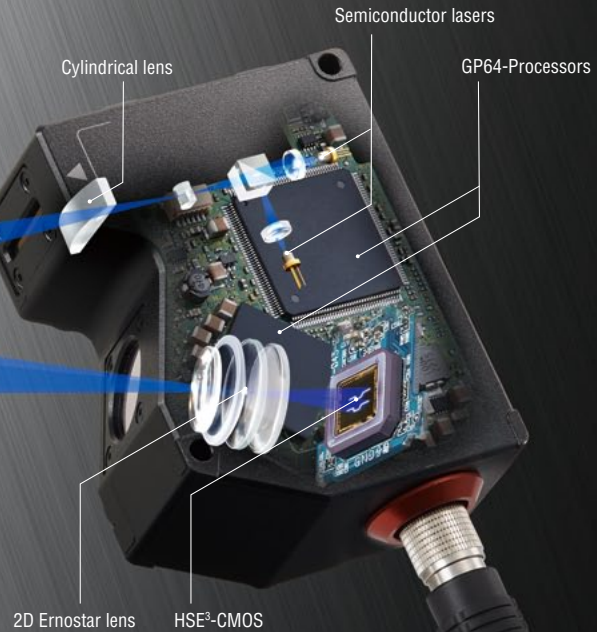
The LJ-V Series is able to perform any measurement thanks to a variety of head variations and measurement modes, as well as 3D inspection when connected to an image processing system. In addition, the automatic setting optimization function makes operation easy for any user.



High-speed 2D/3D Laser Scanner
LJ-V7000 Series

MEASUREMENT PRINCIPLE

The laser light is projected in a horizontal line by the cylindrical lens and diffusely reflects on the target object. This reflected light is formed on the HSE³-CMOS and by detecting changes in position and shape, displacement and shapes are measured.



01

ULTRA-HIGH-SPEED SAMPLING

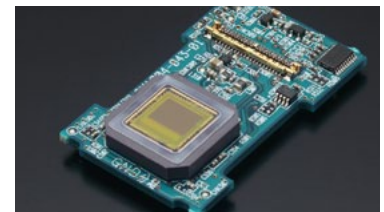
NEWLY DEVELOPED

WORLD'S GREATEST

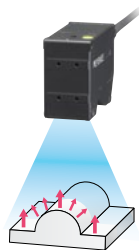
MAKING STABLE MEASUREMENTS OF ANY TARGET POSSIBLE EVEN AT ULTRA HIGH SPEED

▷ HSE³-CMOS * HS = High Speed, E³ = Enhanced Eye Emulation

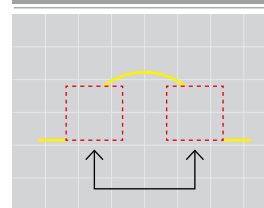
The LJ-V7000 Series is equipped with the newly developed HSE³-CMOS. In addition to improved speed, the dynamic range has been further improved over the established and conventional E³-CMOS. Even with the extremely short exposure time of 64 kHz (15.6 μs) it has achieved sensitivity that allows it to reliably measure a range of surfaces from black (small amount of reflection) surfaces to those with luster (large amount of reflection) due to its wide dynamic range.



STOPPED TARGET

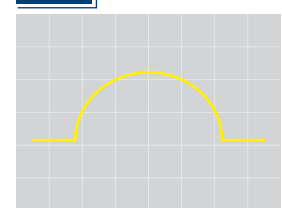


Conventional model



Measurement is impossible due to insufficient light intensity.

LJ-V HSE³-CMOS

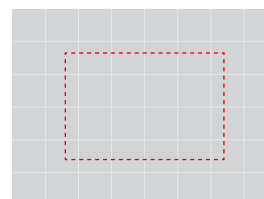
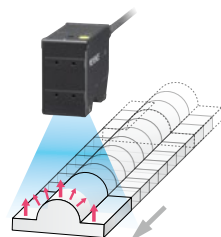


All ranges could be measured.

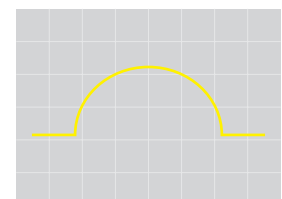
MOVING TARGET

DYNAMIC RANGE

2400×



Because there is even less light intensity, the measurement could not be performed at all.



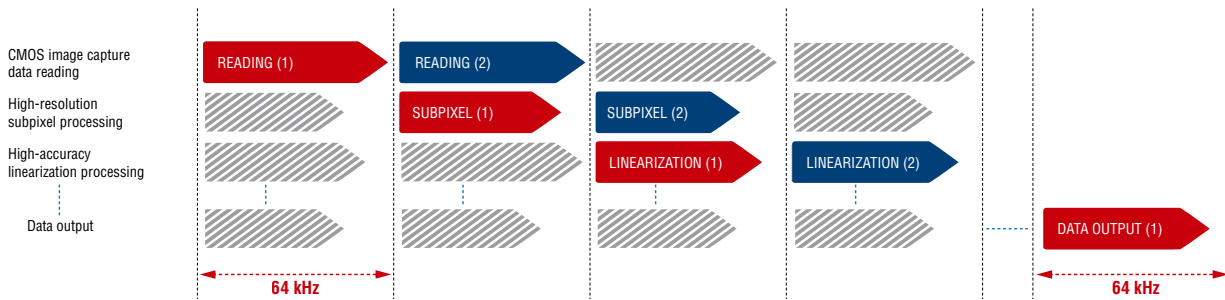
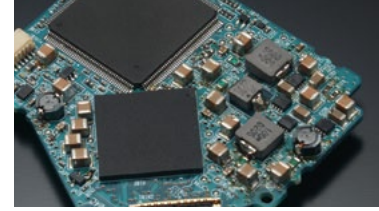
Even though the exposure time is short, all ranges could be measured without issue.

ACHIEVING ULTRA HIGH-SPEED MEASUREMENTS AT 64 kHz

▷ GP64-Processor*

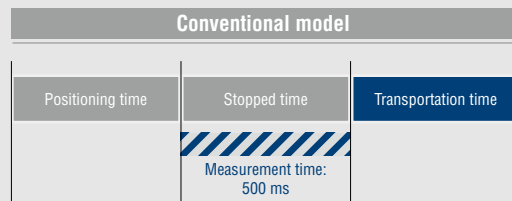
* G = Generating, P = Profiles

We have developed a new custom IC that can perform ultra-high-speed pipeline processing that in addition to reading CMOS image capture data and performing high-resolution subpixel processing, also performs high-precision linearization and data output. This allows for the measurement of objects moving at high-speeds with room to spare.

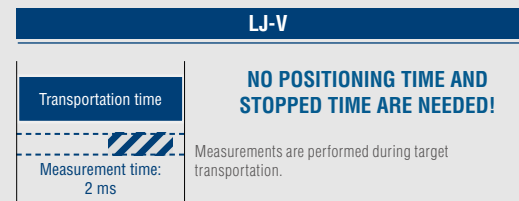


MERITS PROVIDED BY ULTRA HIGH-SPEED SAMPLING

REDUCED INSPECTION CYCLE TIME!

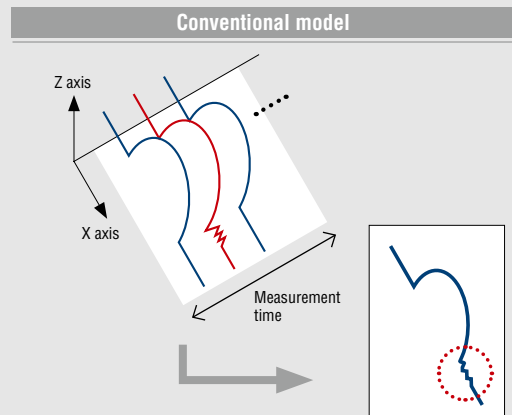


With the conventional method, it takes time to perform the three processes of product positioning, stopping, and transportation and ejection in order to perform an accurate inspection.



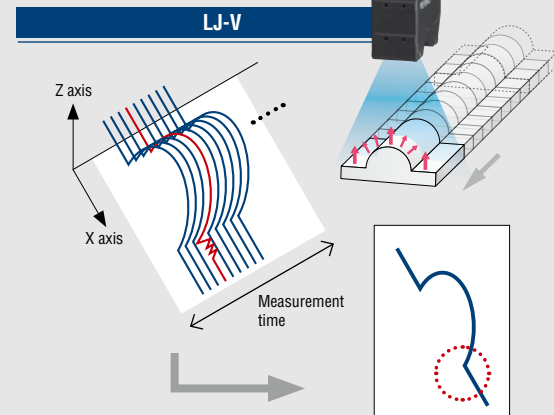
With the LJ-V Series, the measurement time is 240 times shorter than that of the conventional method, which makes it possible to finish inspections within the product transportation time, which leads to improved cycle time.

STABILIZED MEASURED VALUES!



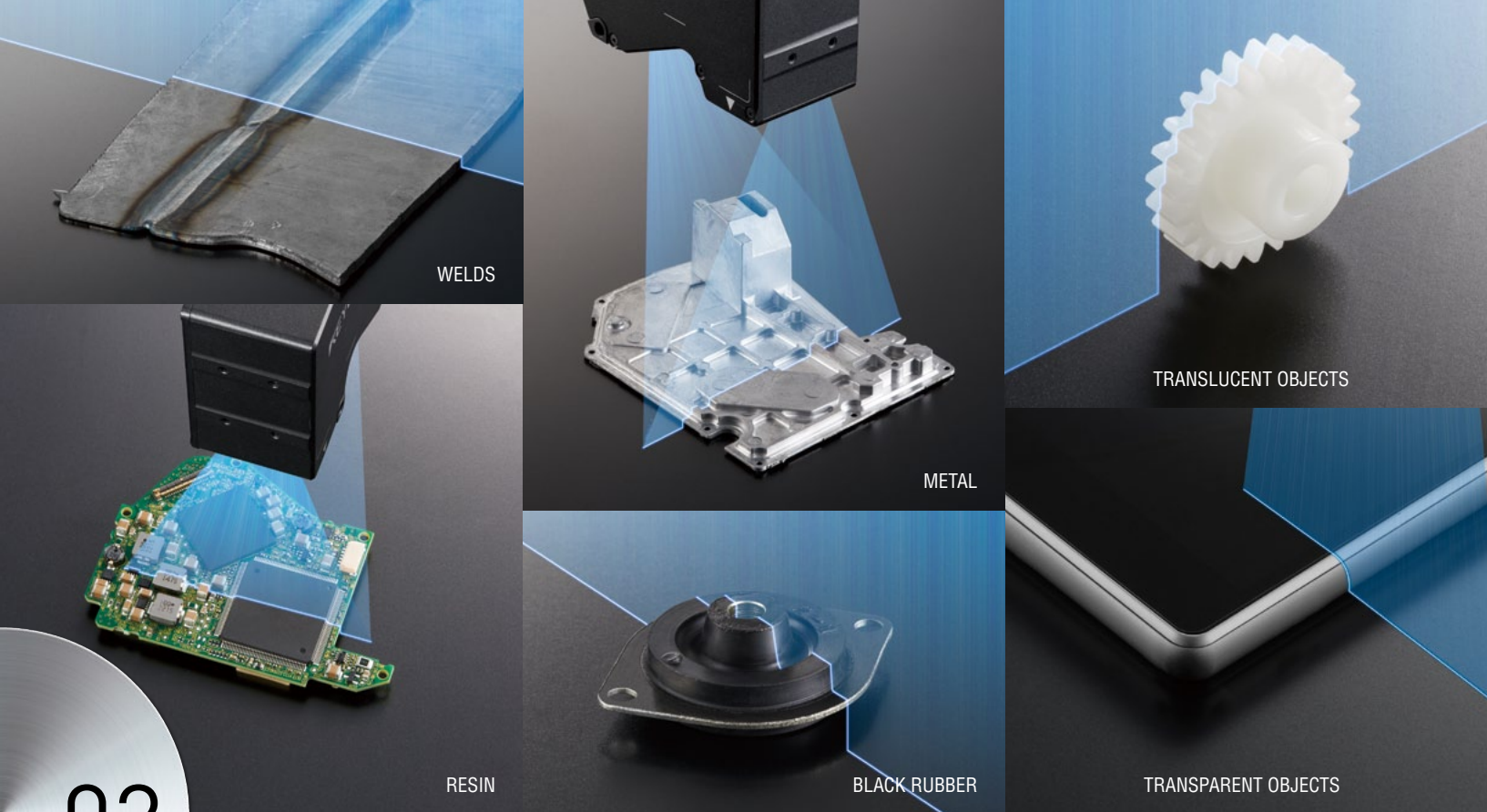
RESULT OF AVERAGING 3 PROFILES

With conventional models, measurement stability was limited due to insufficient sampling speeds necessary to hit the required cycle times.



RESULT OF AVERAGING 720 PROFILES

The LJ-V Series provides significantly higher profile stability by utilizing ultra-high-sampling at as high as 240 times that of conventional models to allow for profile averaging as well as abnormal value elimination using median filters.



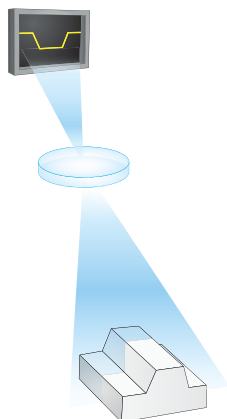
OVERWHELMING WORKPIECE RESPONSE CAPABILITIES AND DETECTION STABILITY

WORLD'S FIRST

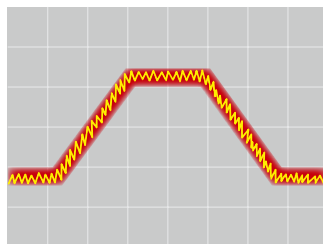
FORMS ULTRA-STABLE AND HIGHLY ACCURATE PROFILE IMAGES

▷ Blue laser optical system

The LJ-V7000 Series is the first 2D laser displacement sensor in the world to adopt a blue laser. A sharp line beam is formed on the light-receiving element by focusing a short wavelength (405 nm) laser to its maximum limit with a 2D Ernstar lens. This generates a stabilized high-precision profile. Also, the received light density for the laser has been increased to successfully secure a greater level of received light intensity. This achieves ultra-stable and highly accurate measurement with all types of targets that are typically difficult to detect.

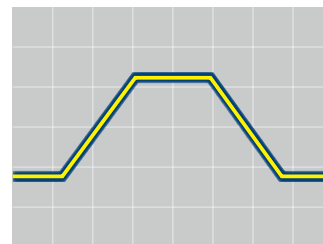


RED LASER (CONVENTIONAL)



With a conventional red laser, the beam that formed the image is thick, resulting in the generation of variation in the profile.

BLUE LASER (LJ-V)



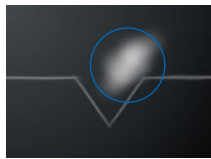
With a blue laser, the image forming beam becomes sharp to enable the measurement of shapes with excellent accuracy.

IDENTIFIES UNNECESSARY LIGHT REFLECTIONS

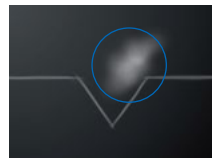
▷ Double polarization function

We have developed the world's first double polarization function, which distinguishes and cancels multiple reflection light that acts as an obstacle to measurement. Light is shined on the intersection between the X-polarization and Y-polarization to calculate differences in the amount of received light for each unit of image capture data. Multiple reflection light has the characteristic of generating differences in the amount of received light for X-polarization and Y-polarization, and this characteristic is used to cancel data for areas that have large differences. The power of this function is demonstrated in the measurement of metals with complex shapes and complicated areas.

1. X POLARIZATION



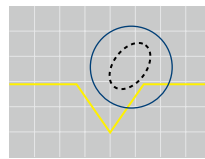
2. Y POLARIZATION



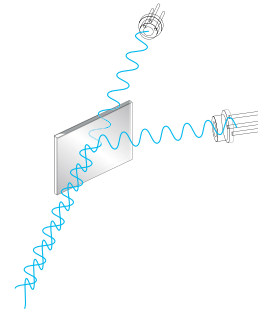
MULTIPLE REFLECTION LIGHT

A large difference in light intensity is generated between 1. and 2.

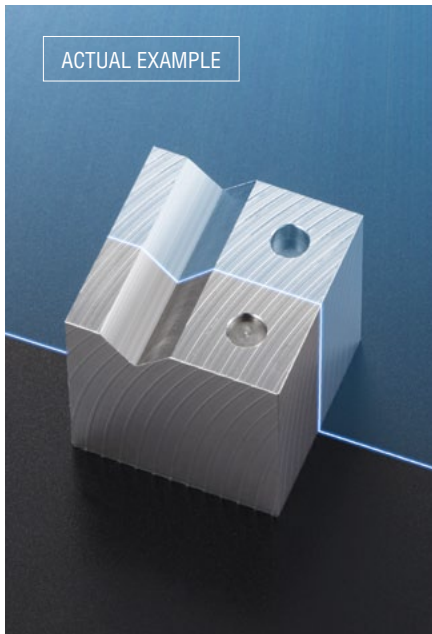
GENERATOR PROFILE



Data with areas that contain large differences is canceled.

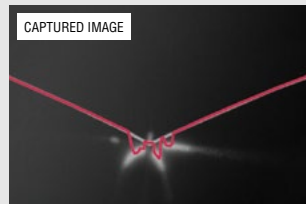


ACTUAL EXAMPLE

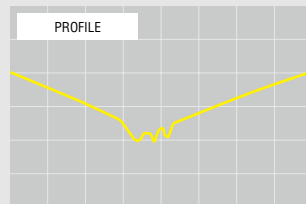


Conventional model

CAPTURED IMAGE



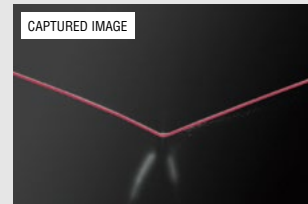
PROFILE



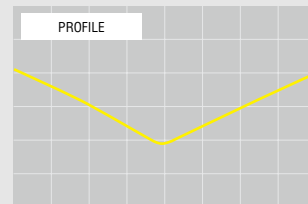
The strong influence of the diffuse reflected light causes errors in the data.

LJ-V

CAPTURED IMAGE



PROFILE



LJ-V Series cancels the diffuse reflected light to perform stable measurements.



03

ALL TYPES OF MEASUREMENTS ARE POSSIBLE WITH THIS SINGLE DEVICE



STEP 1

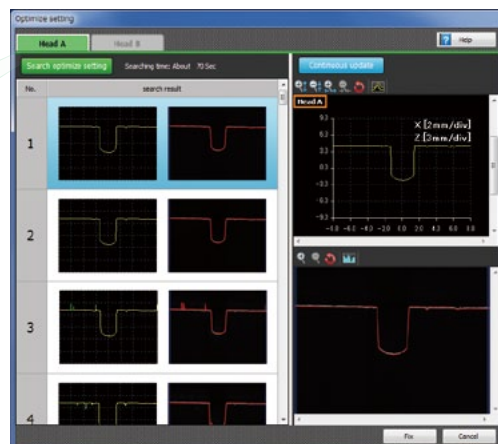
IMAGING CAPTURE SETTINGS — One-click optimization for easy use by anyone —

▷ Automatic setting optimization function

In order to obtain a stable and clean waveform, adjusting parameters like laser power, light sensitivity, and exposure time is necessary. By incorporating an automatic setting optimization function, conventional adjustment operations can be done with just one click.

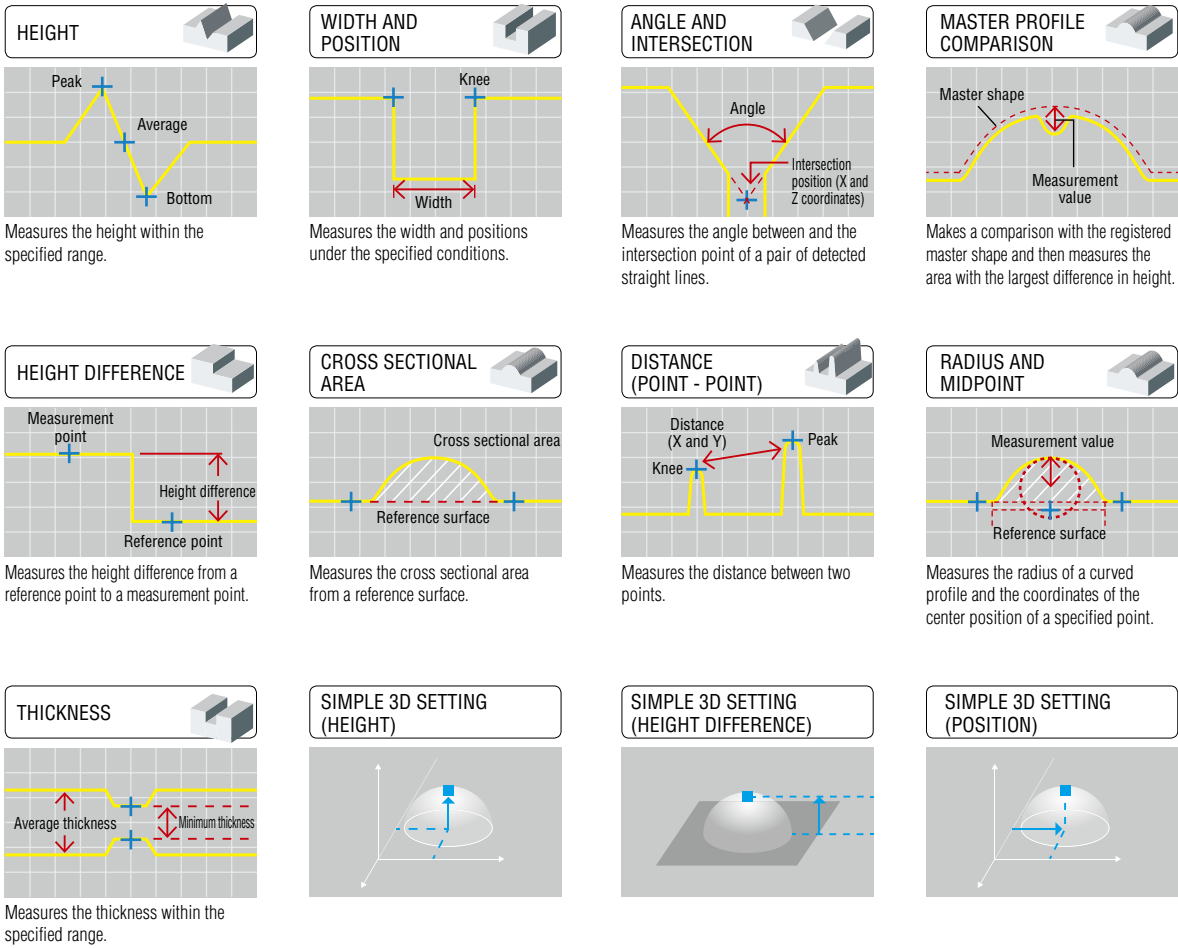
Search optimize setting

JUST
CLICK
THIS
BUTTON!



STEP 2

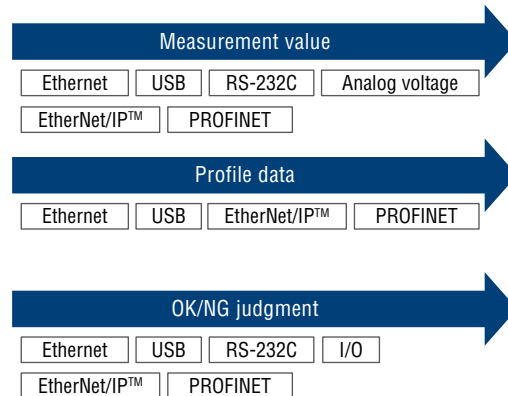
MEASUREMENT SETTINGS — 74 different measurement modes for a wide variety of inspections —



STEP 3

OUTPUT SETTINGS — Output modes available for a variety of uses —

▷ OUTPUT METHOD



PC



PLC, etc.

Ethernet and USB can also be used with DLLs.

OUR AIM IS ON-SITE EASE OF USE

SELECTABLE 3-WAY OPERATION

A touch panel has been prepared so that it is possible to perform on-site monitoring or setting operations during measurement. It is also possible to perform operation using a PC or a LCD color monitor.



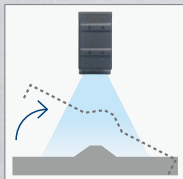
Touch panel HMI
CA-MP120T

AN EMPHASIS ON INLINE MEASUREMENT

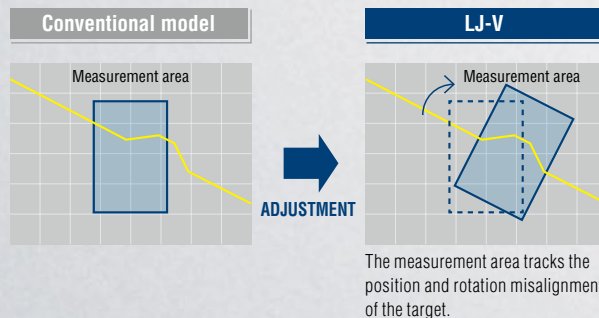
IN-LINE POSITION ADJUSTMENT FUNCTION (X, Y, AND Z)

Corrects positional misalignment of the target, which is directly connected to errors in the measurement results. Accurate measurements are possible even in cases where the target is moving at random or when it is difficult to perform positioning.

$\theta \rightarrow X$ adjustment
(angle then x position)



If the position of the workpiece becomes misaligned...





VARIOUS SPECIFICATIONS THAT INCLUDE ALL ON-SITE NEEDS

SUPPORTS ENCODER INPUT

Can perform encoder synchronized measurement up to a top speed of 64 kHz. Can measure shapes in the direction of movement with high-speed and with an accurate pitch.

HIGH-FLEX CABLE

Has adopted a high flex cable as standard. Can be installed on robots and other movable parts without worry.

IP67 RATED SENSOR HEAD AND CONNECTION CABLE

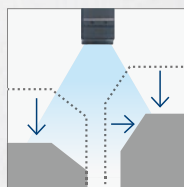
In addition to the sensor head, the connection cable also supports an IP67 enclosure rating. There are no problems even in environments like processing plants where spray easily comes on to the product.

PASSES IMPACT RESISTANCE TEST IEC 60068-2-27

Equipped with high shock resistance that is necessary for industrial robots.

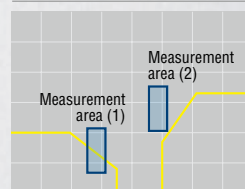
DOUBLE XZ θ ADJUSTMENT FUNCTION

The LJ-V7000 Series is equipped with a new function that makes it possible to individually set various adjustments in 2 areas. This is effective when measuring gaps, angles, or height differences of two targets that move independently.



If the position of individual workpieces becomes misaligned...

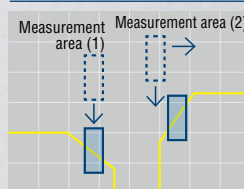
Conventional model



Because position adjustment was applied to a single side as a reference, measurement could not be properly performed.



LJ-V

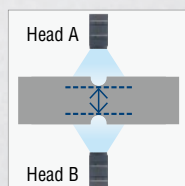


Because original adjustment is applied individually to measurement areas (1) and (2), measurement can be properly performed.

DUAL-HEAD ADJUSTMENT FUNCTION

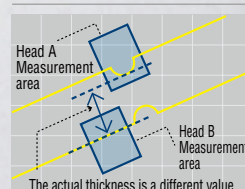
By understanding the positional relationship of both heads, it is possible to match the θ adjustment center of rotation for both heads. Even when measuring targets with variation or incline changes, it is possible to measure the correct points.

Ex. Minimum thickness measurement



If the workpiece tilts...

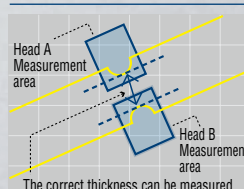
Conventional model



The θ adjustment center of rotation for each head differs, so the measurement area for head B becomes misaligned.



LJ-V

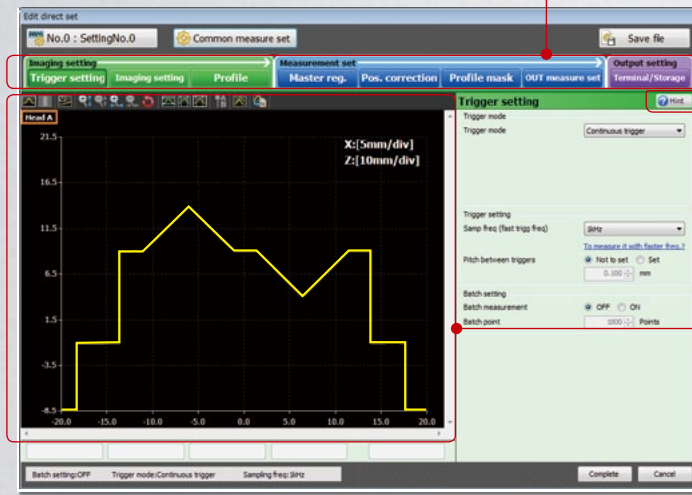


The θ adjustment center of rotation for both heads match, so the measurement area is not misaligned.

SIMPLE PROGRAMING — LJ-Navigator2 —

View measurement results, configure settings, and transfer data all from one easy to use software package.

EASY SETTINGS

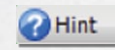


EASY NAVIGATION SETTINGS

Anyone can perform setting intuitively by following the navigation in the order of image capture settings, measurement settings, and output settings.

HINT FUNCTIONS THAT DON'T REQUIRE THE MANUAL

"Hint" icons have been prepared for each screen.



SETTINGS APPLIED IN REAL-TIME

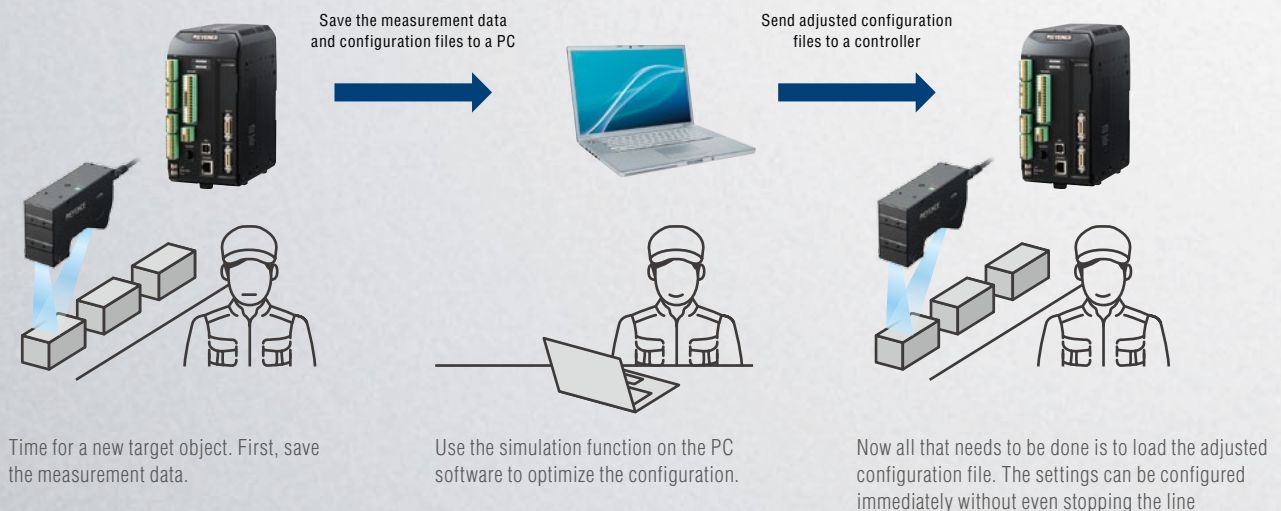
The measurement conditions are applied to the settings screen profile in realtime.

There is no need to return to the measurement screen for confirmation, making it possible to greatly reduce the time and effort spent on set up.

SIMULATION FUNCTION

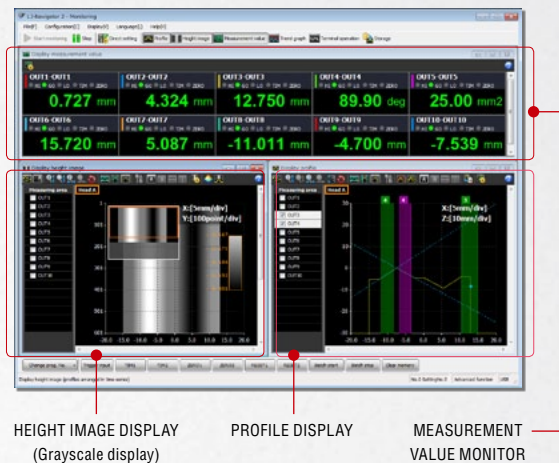
Saved measurement data or data obtained in real time can be used to change measurement settings and position adjustments before re-measuring. This feature helps solve problems in as little time as possible, such as when settings must be changed or when optimization is necessary due to the addition of a new target object.

USEFUL APPLICATIONS



MULTI-SCREEN FUNCTION

It is possible to simultaneously check your favorite screens, including measurement values, measurement profiles, height image displays (grayscale displays), and measurement value trend graphs. It is possible to freely determine the screen size and placement to construct your own custom screen.



PROFILE STORAGE FUNCTION

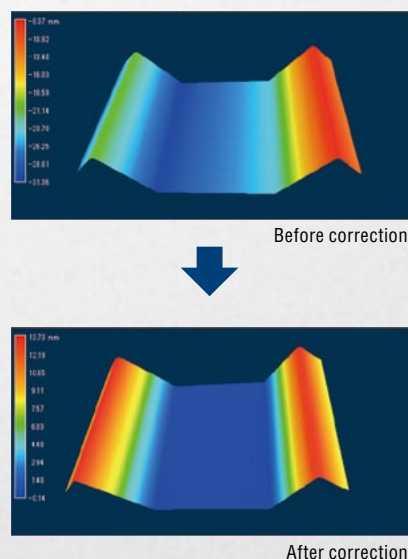
It is possible to store approx. 160000 profiles. You can also store measurement values for 16 outputs at the same time. The LJ-V7000 Series is equipped with various analysis functions, which is useful for the verification of defects and for research and development.



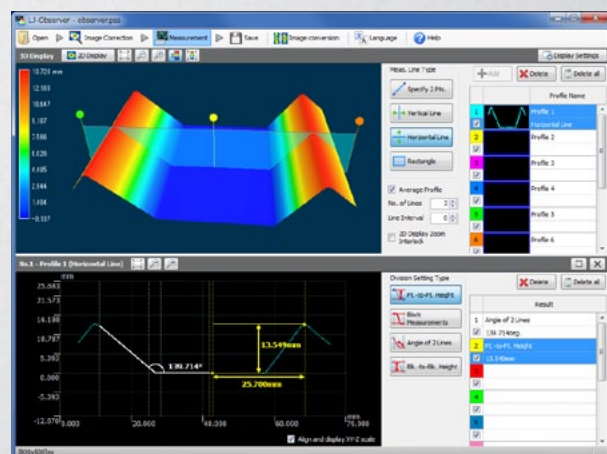
OFFLINE PROFILE OBSERVATION — LJ-Observer —

This tool uses saved measurement data to provide a 3D view and allows for simple profile measurement.

3D VIEWER AND SURFACE SLANT ADJUSTMENT



SIMPLE PROFILE MEASUREMENT FUNCTION



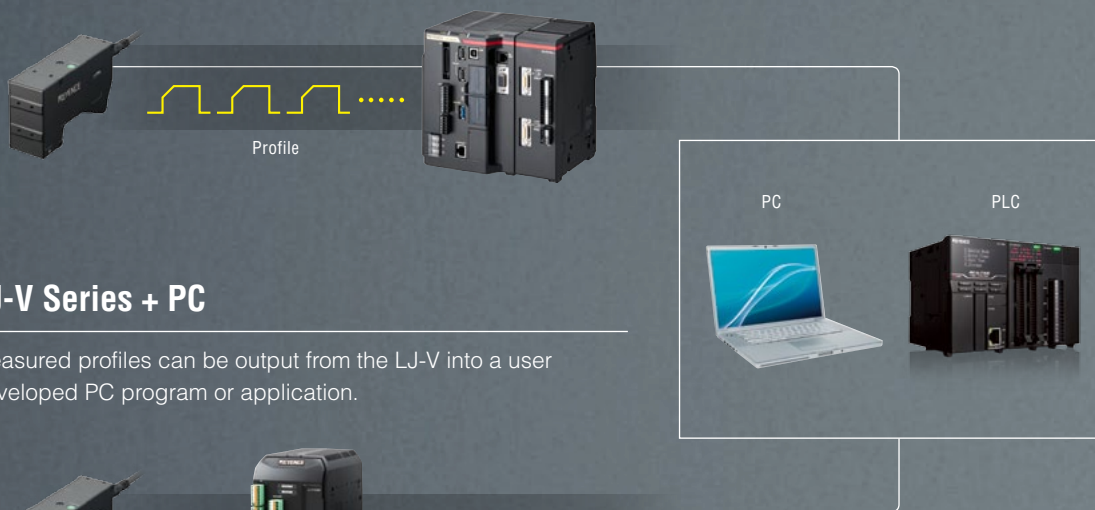
Extracting a desired cross-section for 3D data allows for measurement of height, horizontal distance, and angle.

INLINE 3D MEASUREMENT

TWO TYPES OF SELECTABLE 3D MEASUREMENT SYSTEMS

LJ-V Series + Image Processing System

By loading 2D profiles acquired by the LJ-V Series into the CV-X controller, it is possible to apply image processing to the created 3D image.



LJ-V Series + PC

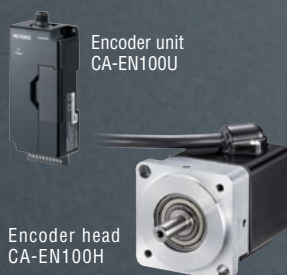
Measured profiles can be output from the LJ-V into a user developed PC program or application.



Usable with encoders

The number of pulses can be set arbitrarily, making it possible to install an encoder with unprecedented simplicity to best suit the imaging conditions (Support for 64 to 150000 pulses).

Unlike with conventional products, there's no need to select encoders based on aspects such as the rotation speed of the shaft, the roller diameter, or the field of view.



**High-resolution
and
high-speed output**

IP65-compatible

Support for up to 150000 pulses allow for high-resolution output at a minimum of 0.0024° (8.64 seconds). High-speed output is also possible at a maximum output frequency of 16 MHz.

Added consideration for environmental resistance has resulted in a design that is even more resistant to water and dust, making devices even easier to use in the worksite (This does not include the head or shaft areas).

* If there is a chance that the shaft through-hole area will be exposed to oil droplets, use a cover or take other necessary precautions.

LJ-V SERIES + IMAGE PROCESSING SYSTEM

Combining the advanced profiling capabilities of the LJ-V Series with the Image Processing System. Image processing can be performed on 3D measurement data to open new doors in the realm of quality inspection.

LJ-V7000 Series



Image Processing System

Measured Value Acquisition

The continuous profile data measured with the LJ-V Series is loaded into the Image Processing System.

3D DATA

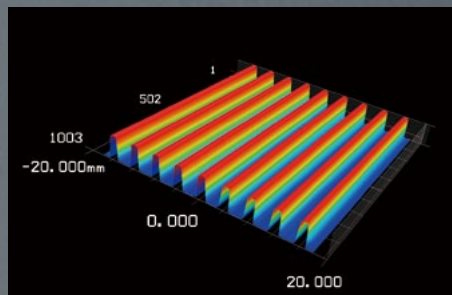
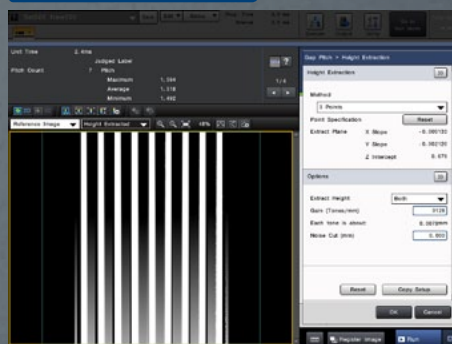


Image Processing

Within the Image Processing System, the height data is converted to a gray-scale image with 256 gradations.

The Image Processing System utilizes 21 built-in pre-processing filters, such as real-time gray-scale adjustment and a blob filter to obtain the optimum image for the inspection.

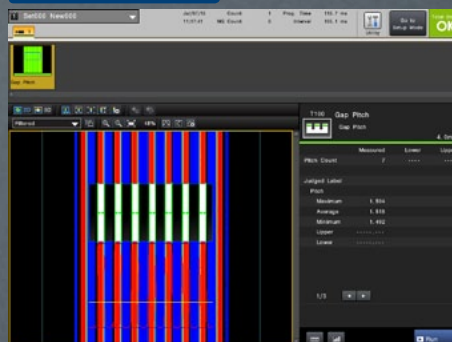
HEIGHT GRAY-SCALE PROCESSING



Inspection and Measurement

Performing image processing on height data makes a wide range of inspections possible. Not only can you perform accurate measurements utilizing surface planes such as measuring relative heights and volumes, but also detect defects such as scratches and chips on any surface.

IMAGE PROCESSING RESULT



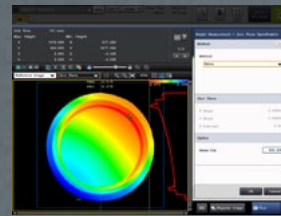
AS FAST AS
2 MS PER
INSPECTION!

MEASURING HEIGHT, AREA, AND VOLUME FROM 3D DATA

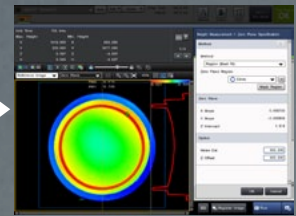
Zero Plane Specification

As the reference plane for height measurement, a “zero plane” can be specified separately for each workpiece. This always ensures stable measurement even if workpieces change their orientation. You can also specify a different reference plane for each measurement point. In addition, setting a free-form plane for zero plane specification is also possible. This allows for calculation of such properties as height and depth on a curved surface.

Before correction



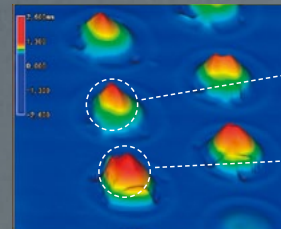
After correction



Even if a workpiece is inclined, the zero plane is automatically set according to the workpiece to obtain an accurate shape.

Area and Volume Measurement

Measures volumes in the range enclosed by the inspection region and the “zero plane”.



16-bit Pre-Processing Dedicated for Height Images

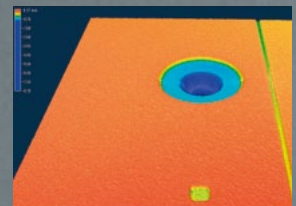
Pre-processing dedicated for height images is provided.

Five types of pre-processing are available: Median, Average, Gaussian, Smoothing, and Invalid Pixel Interpolation. This creates stable measurement for each workpiece.

Using pre-processing for grooves, which have largely varying luster, makes it possible to perform stable measurements.



Height image



Pre-processed image

TAKE FULL ADVANTAGE OF ALL THE FUNCTIONALITY FOUND IN CONVENTIONAL IMAGING EQUIPMENT

Height extraction

Based on 3D data, a grayscale image is automatically generated with emphasis on the height you want to check. This allows you to continuously use all conventional, established XG/CV-X functions. Targets hard to detect with conventional image processing can now be detected by combining, for example, free-form plane extraction and OCR.

Also supports difficult-to-detect workpieces by extracting concavities and convexities from free-form plane shapes

Area cameras cannot detect dents because images are shaded due to the influence of complex curves and surface irregularities. Inspection becomes possible by extracting height change of points based on the information of a free-form plane.

Workpiece photo



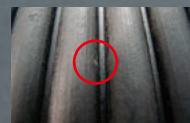
Height data



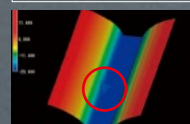
Height-extracted image (Free-form plane) + OCR



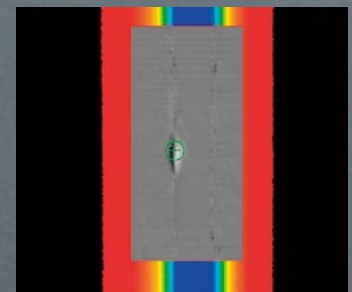
Workpiece photo



Height data



Detection image

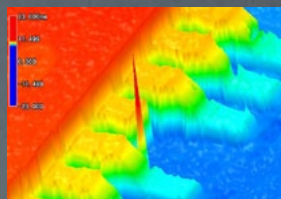


NEW FUNCTIONS FOR MORE STABLE 3D INSPECTION

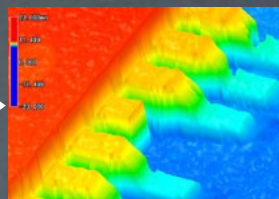
Projection Noise Removal

The LJ-V Series includes algorithms designed to exclude suddenly generated noise. Noise removal sizes can be individually specified for the X and Y directions, enabling support for a wide range of workpieces.

Original image



After noise reduction

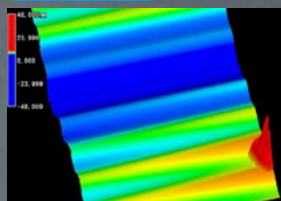


Vibration Compensation Filter

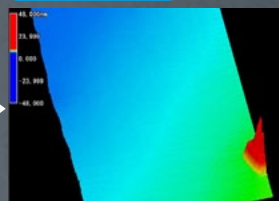
Stable detection is possible by suppressing noise caused by vibrations and eccentricity during conveyance. This allows for reduced fluctuations in data common bottlenecks with inline inspection.

Noise caused by vibration

Original image

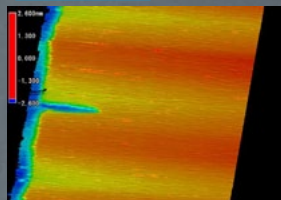


Processed image

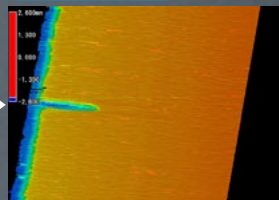


Noise caused by eccentricity

Original image



Processed image

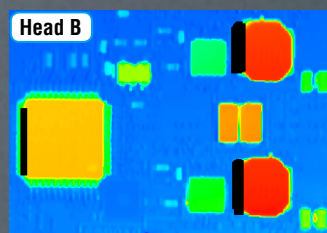
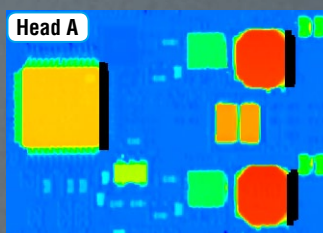


DUAL HEAD Dead Angle Removal Function

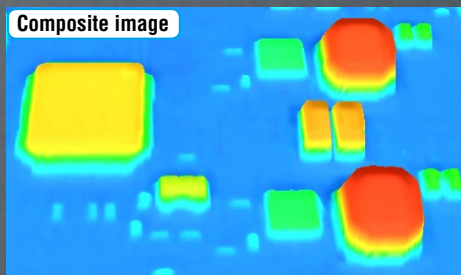
Profile data from two directions is combined in order to provide dead angle information that could not otherwise have been measured.



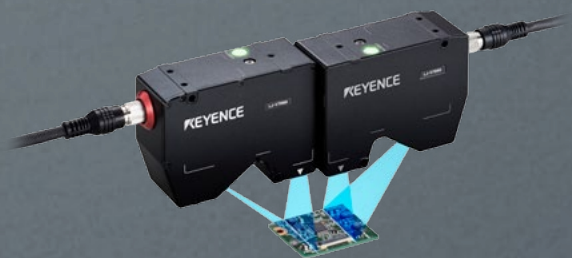
Data is missing because there is a dead angle in both images.



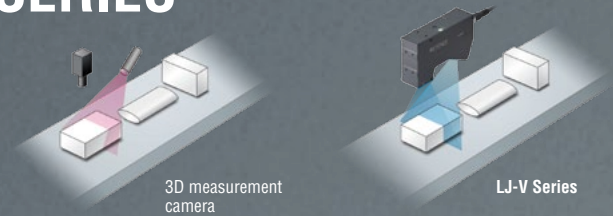
Composition



It is possible to create an image without any missing points by using the "Dual head dead angle removal function".

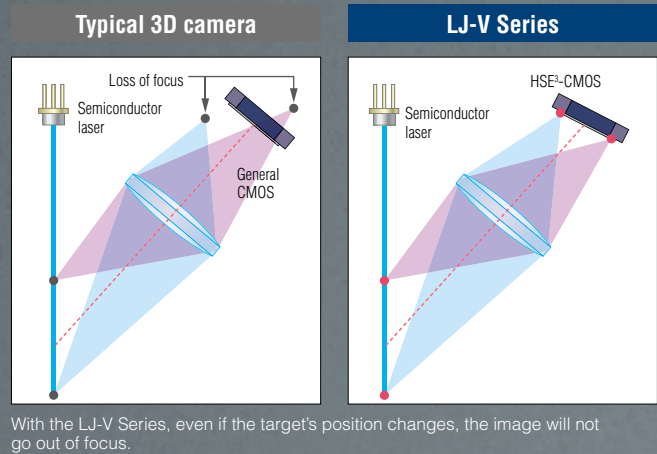
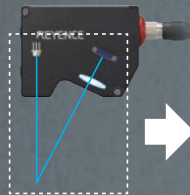


OPTICAL FOCUS AND DEPTH OF FIELD ADVANTAGES OF THE LJ-V SERIES



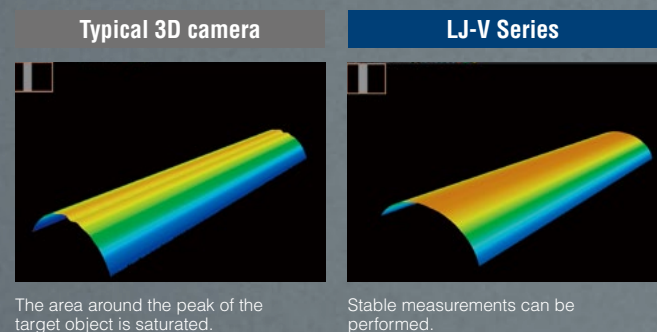
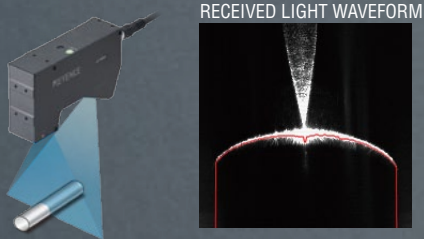
Better Optical Design

Cameras that are not equipped with auto focus or a similar technology have a set focus position which makes it impossible to obtain an accurate profile if the distance between the camera and target changes. The LJ-V Series uses a special optical system, which enables the LJ-V Series to always capture images that are in the measurement range.



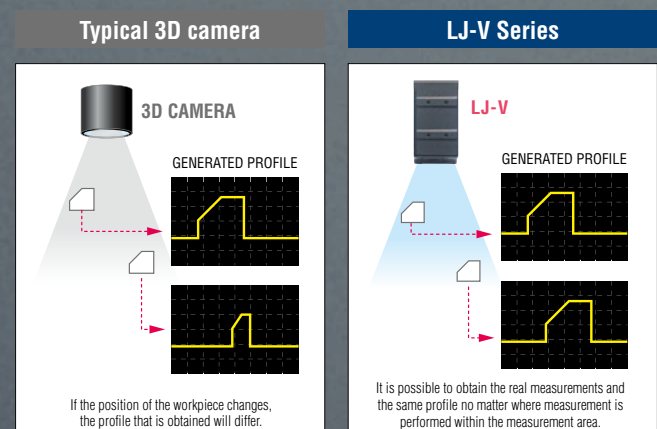
Better Dynamic Range

For general 3D cameras, the light receiving element has a narrow dynamic range leading to measurement errors caused by the amount of light reflected from the target. The LJ-V Series can perform stable measurements without light saturation even if the amount of reflected light is large.



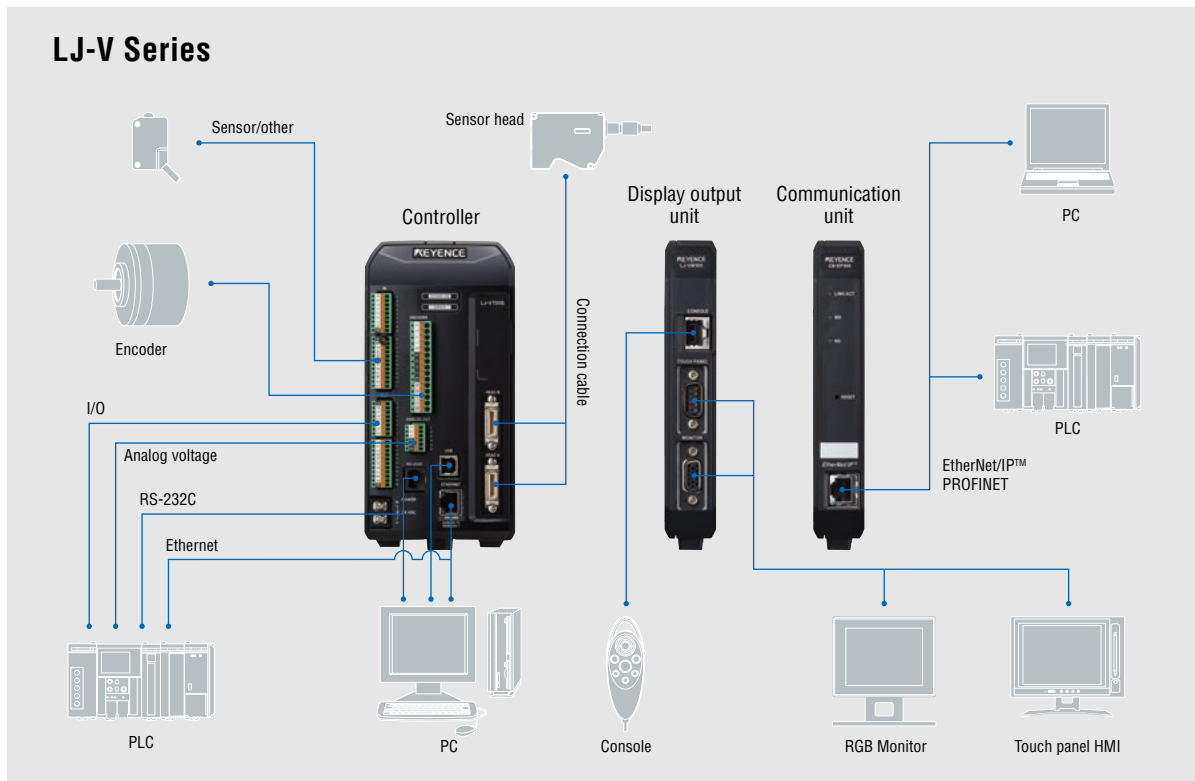
Better Ease of Use

When using a 3D camera, the height and width data of individual pixels differs due to the positional relationship of the laser light source and the receiver, so a calibration must be performed for each pixel. With the LJ-V Series, there is no need for the user to perform additional calibration.

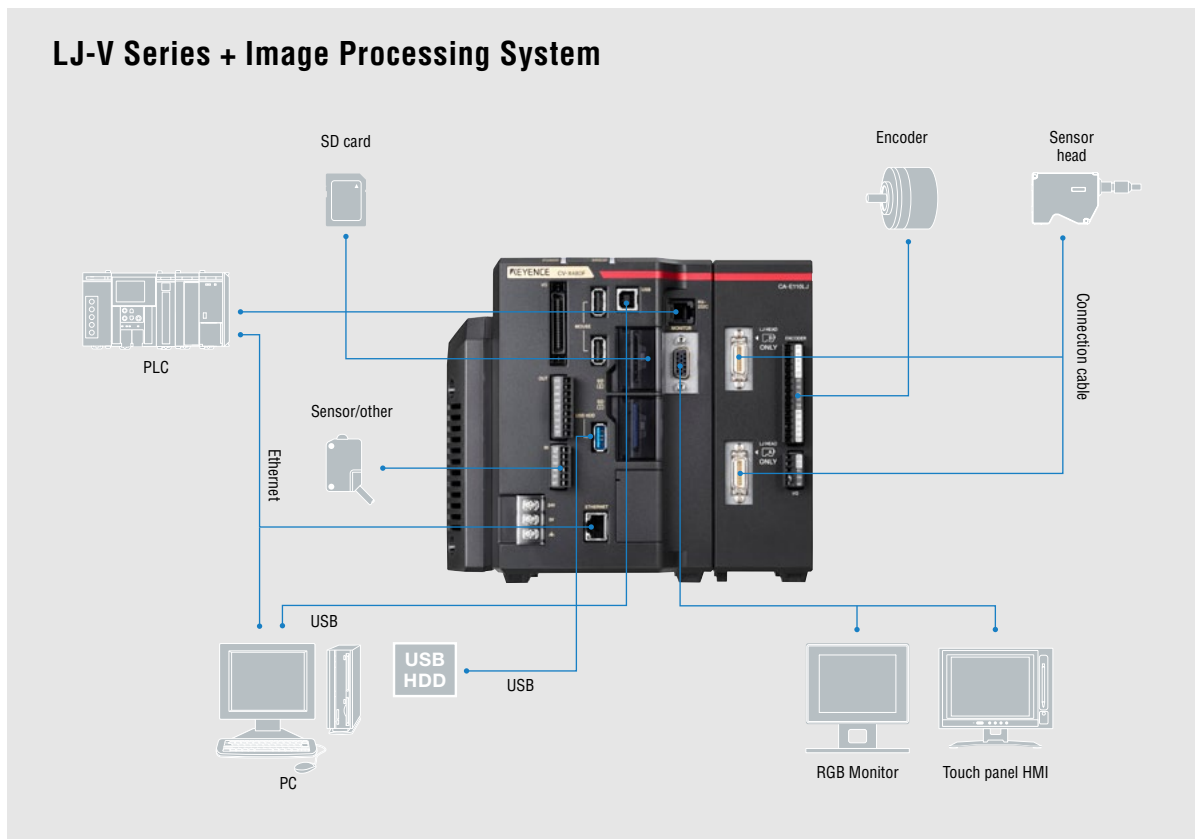


SYSTEM CONFIGURATION

LJ-V Series

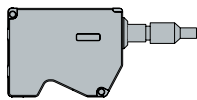
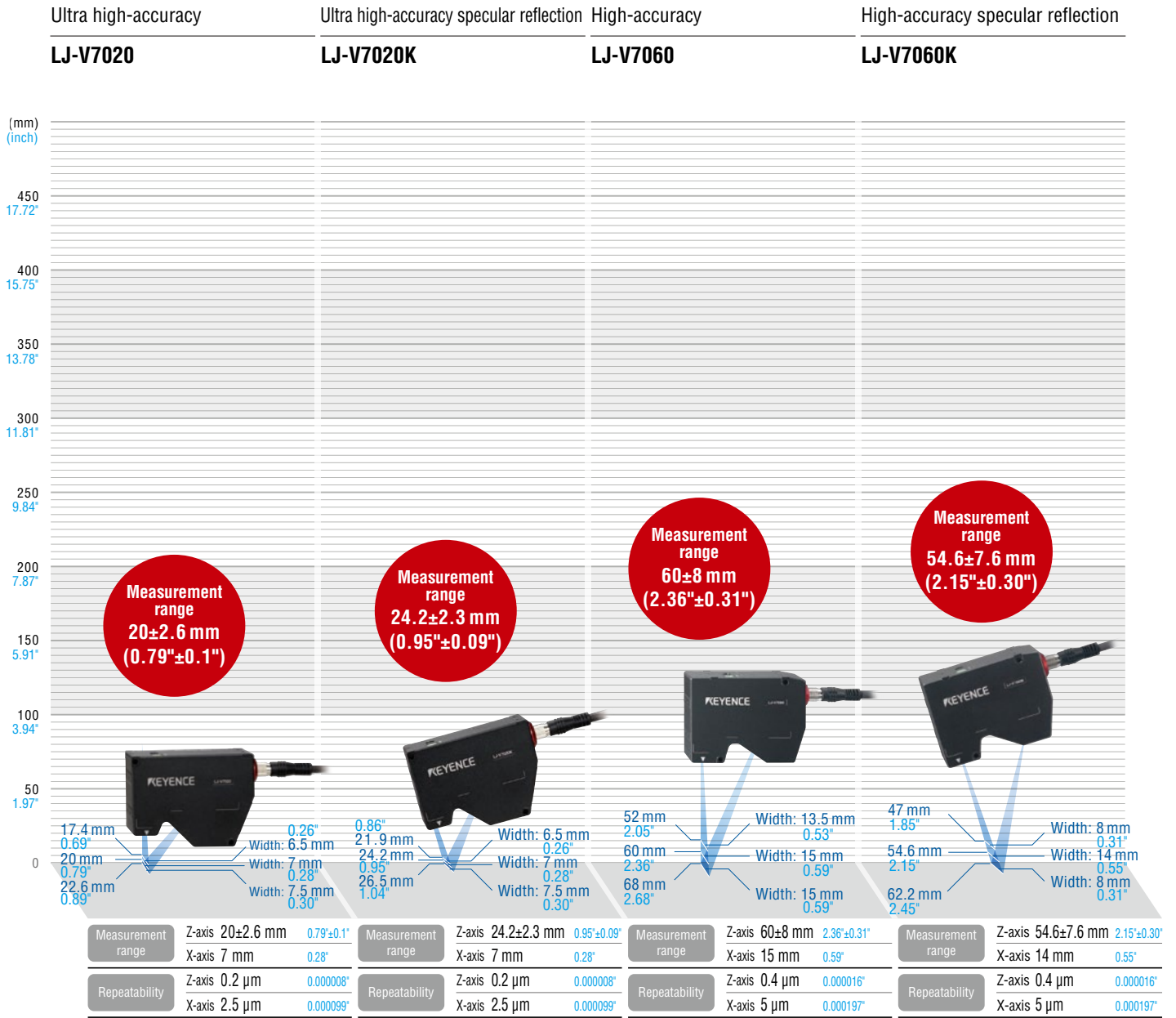


LJ-V Series + Image Processing System



COMPONENTS SELECTION GUIDE

SENSOR HEAD



Required



Head-to-controller cable
CB-B3 (3 m 9.8')
CB-B10 (10 m 32.8')



Extension cable
CB-B5E (5 m 16.4')
CB-B10E (10 m 32.8')
CB-B20E (20 m 65.6')

Required



Controller
LJ-V7000(P)

Controller variations

| | |
|-----------------|------------------|
| NPN output type | LJ-V7001 |
| PNP output type | LJ-V7001P |



Settings monitor software
LJ-H3



USB cable
OP-66844

* For total lengths of 30 m 98.4', up to 2 extension cables may be added. Select products as required.

Units/Options



EtherNet/IP™ unit
CB-EP100
PROFINET unit
CB-PN100



Display output unit
LJ-VM100



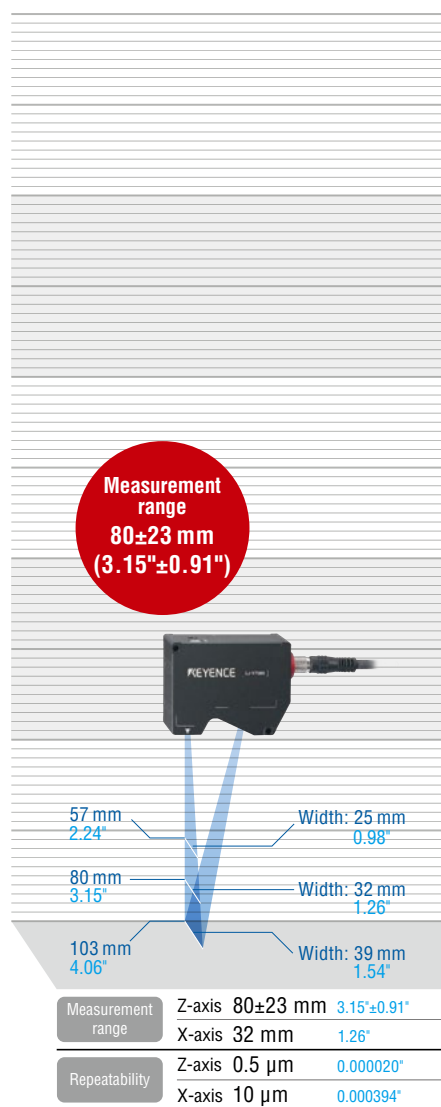
Monitor stand
OP-87262

Image stitching unit
CA-E100LJ/CA-E110LJ
Encoder unit
CA-EN100U
Encoder head
CA-EN100H
Encoder head cable
CA-EN5 (5 m 16.4')/CA-EN10 (10 m 32.8')

Ethernet cable
OP-87736 (2 m 6.6')
RS-232C cable
OP-96368 (2.5 m 8.2')
D-sub 9 pin connector
OP-26401

Middle range

LJ-V7080



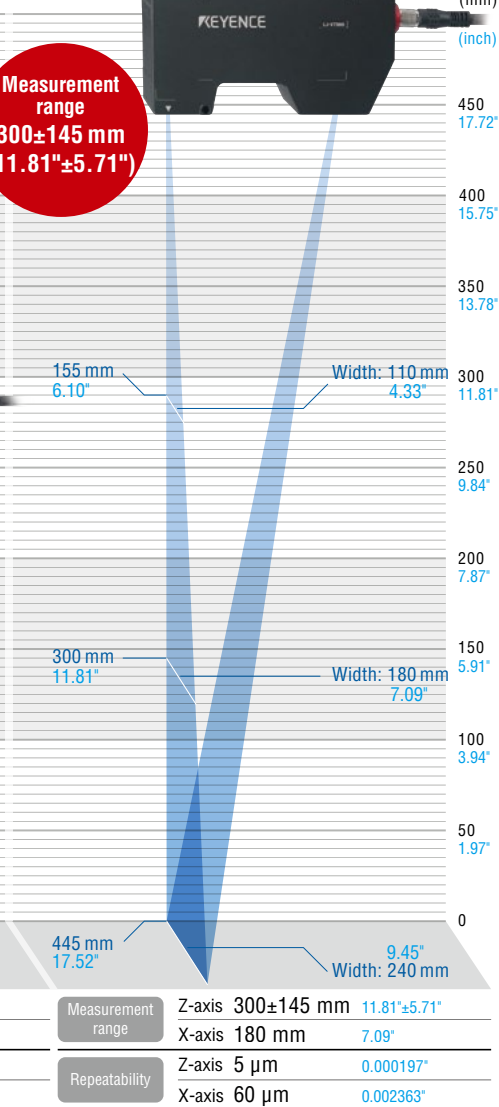
Long range

LJ-V7200



Ultra-long range

LJ-V7300

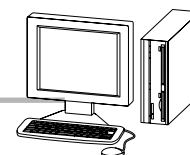


Connect to PC

Connect using the USB cable included with the PC software or an Ethernet cable.



USB cable
OP-66844



PC (not included)

Connect to colour monitor



Display output unit
LJ-VM100



Display monitor connection cable
OP-66842 (3 m 9.8')
OP-87055 (10 m 32.8')



Console
OP-87504



LCD colour monitor
CA-MP120

Connect to touch panel



Display output unit
LJ-VM100



Display monitor connection cable
OP-66842 (3 m 9.8')
OP-87055 (10 m 32.8')



Touch panel HMI extension cable
OP-87258 (3 m 9.8')
OP-87259 (10 m 32.8')



Touch panel HMI
CA-MP120T

SPECIFICATIONS



Controller

| Model | | LJ-V7001 | LJ-V7001P |
|----------------------------|-------------------------------|--|--|
| No. of connectable sensors | | Max. 2 units | |
| Display | Minimum display unit | 0.1 μm 0.000004° , 0.00001 mm², 0.01° | |
| | Maximum display range | ±9999.99 mm, ±9999.99 mm² | |
| Input terminal block | Laser remote interlock input | Non-voltage input | |
| | Encoder input | NPN open-collector output, voltage output (5 V/12 V/24 V), and line-driver output all supported | |
| | Trigger inputs | Non-voltage input | Voltage input |
| | Timing 1, 2 input | | |
| | Auto-zero1, 2 input | | |
| | Reset 1, 2 input | | |
| | Start measurement/stop input | | |
| | Start storage/stop input | | |
| | Clear memory input | | |
| | Laser OFF input | | |
| | Program switch input | Non-voltage input × 4 inputs | Voltage input × 4 inputs |
| Output terminal block | Analog voltage output | ±10 V × 2 outputs, Output impedance: 100 Ω | |
| | OUT comparator output | NPN open collector output × 12 outputs (Can freely assign 16 OUTs × 3 stage judgment results) | PNP open collector output × 12 outputs (Can freely assign 16 OUTs × 3 stage judgment results) |
| | Strobe output | NPN open collector output | PNP open collector output |
| | Disable trigger output | | |
| | Memory FULL output | | |
| | Ready output | | |
| | Error output | NPN open collector output (N.C.) | PNP open collector output (N.C.) |
| Ethernet interface | | 1000BASE-T/100BASE-TX | |
| USB Interface | | USB 2.0 high speed compliant (USB 1.1 Full-SPEED compatible) | |
| RS-232C interface | | Measurement data output and control I/O (Can select a baud rate of up to 115,200 bps) | |
| Rating | Voltage | 24 VDC, including ±10% ripple (P-P) | |
| | Maximum current consumption | 1.3 A or less when connected to 1 head/ 1.9 A or less when connected to 2 heads | |
| Environmental resistance | Operating ambient temperature | 0 to +50°C 32 to 122°F | |
| | Operating ambient humidity | 20 to 85% RH (No condensation) | |
| Weight | | Approx. 1500 g | |

- The rating for NPN open-collector output is up to 50 mA (40 V or less), residual voltage of up to 1 V
- The rating for PNP open-collector output is up to 50 mA (30 V or less), residual voltage of up to 1 V
- The rating for non-voltage input is up to 1 V for ON voltage and up to 0.6 mA for OFF current
- The rating for voltage input is a maximum input voltage of 26.4 V, a minimum ON voltage of 10.8 V, and up to 0.6 mA for OFF current



Display output unit

| Model | | LJ-VM100 |
|--------------------------|-------------------------------|--|
| Monitor output | | Analog RGB XGA (1024 × 768) Touch panel monitor (CA-MP120T), specialized connector included |
| Voltage | | Supplied from the controller |
| Power consumption | | 2.5 W or less |
| Environmental resistance | Operating ambient temperature | 0 to +50°C 32 to 122°F |
| | Operating ambient humidity | 20 to 85% RH (No condensation) |
| Weight | | Approx. 400 g |

LJ-H3 (LJ-Navigator 2) operation system environment

| Item | | Minimum system requirements |
|-------------------------|----------|---|
| PC interface | Ethernet | 1000BASE-T/100BASE-TX |
| | USB*5 | USB 2.0 high speed compliant (USB 1.1 Full-SPEED compatible) |
| Supported OS | | Windows 10*1 Windows 7 (SP1 or later)*2 Windows Vista (SP2 or later)*3 Windows XP (SP3 or later)*4 |
| Supported languages | | English, Japanese, German, French, Simplified Chinese, Traditional Chinese |
| CPU | | Core i3 2.3 GHz or higher |
| Memory capacity | | 2 GB or more |
| 2D cache memory | | 2 MB or more |
| Free space on hard disk | | 10 GB or more |
| Display resolution | | XGA (1024 × 768) or higher |
| Weight | | Approx. 400 g |

*1 Home, Pro, and Enterprise editions are supported.

*2 Home Premium, Professional, and Ultimate editions are supported.

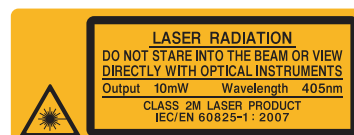
*3 Ultimate, Business, Home Premium, and Home Basic editions are supported.

*4 Professional and Home editions are supported.

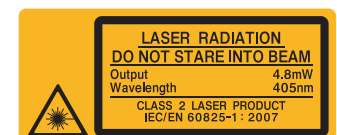
*5 Connection through a USB hub is not included in the guarantee.

LASER WARNING/EXPLANATORY LABEL

LJ-V7020, LJ-V7020K, LJ-V7060



LJ-V7060K, LJ-V7080, LJ-V7200, LJ-V7300



PROFINET unit

| Model | CB-PN100 |
|----------------------|---|
| Compatible network | PROFINET IO communication |
| Ethernet | Compliant standards |
| | IEEE 802.3u*1 |
| | Transmission speed |
| | 100 Mbps, full duplex (100BASE-TX) |
| PROFINET IO | Transmission media |
| | STP or Category 5e or higher UTP |
| | Maximum cable length |
| | 100 m 328.1' |
| PROFINET IO | Supported functions |
| | Data I/O communication |
| | Record data communication |
| | Number of connectable PROFINET IO controllers |
| | 1 |
| | Update time |
| | 2 ms to 2048 ms |
| | GSDML |
| PROFINET IO | Version 2.25 |
| | Conformance class |
| | Conformance Class A compliant |
| | Conformance test version |
| | Based on Version 2.2.4 |
| PROFINET IO | Applicable protocol |
| | LLDP, DCP |
| Power supply voltage | 24 V ±10% (supplied from the controller unit of the laser scanner) |
| Power consumption | 0.12 A max. |
| Weight | Approx. 470 g |

*1 Although this unit conforms to IEEE 802.3u and can establish 100 Mbps full duplex communication using AutoNegotiation function, it does not have AutoCrossOver and AutoPolarity functions that are normally required for the PROFINET IO standard. Select a straight or cross cable according to the Ethernet port of the device to be connected.

EtherNet/IP™ unit

| Model | CB-EP100 |
|--------------------------|--|
| Compatible network | EtherNet/IP™ and displacement sensor-specific protocols (socket communication) |
| Ethernet | Compliant standards |
| | IEEE 802.3 (10BASE-T), IEEE 802.3u (100BASE-TX) |
| | Transmission speed |
| | 10 Mbps (10BASE-T), 100 Mbps (100BASE-TX) |
| Ethernet | Transmission media |
| | STP or Category 3 or higher UTP (10BASE-T), STP or Category 5 or higher UTP (100BASE-TX) |
| | Maximum cable length |
| | 100 m 328.1' (Distance between the unit and Ethernet switch) |
| Ethernet | Maximum number of connectable hubs*1 |
| | 4 hubs (10BASE-T), 2 hubs (100BASE-TX) |
| EtherNet/IP™ | Supported functions |
| | Cyclic communication (Implicit messaging), Message communication (Explicit messaging), Compatible with UCM and Class 3 |
| | Number of connections |
| | 64 |
| | RPI |
| | 0.5 ms to 10000 ms (in 0.5 ms) |
| | Tolerable communication bandwidth for cyclic communication |
| | 6000 pps |
| EtherNet/IP™ | Message communication |
| | UCMM, Class 3 |
| EtherNet/IP™ | Conformance test |
| | Compatible with Version A9 |
| Power supply voltage | 24 VDC, including ±10% ripple (P-P) (supplied from the controller unit of the laser scanner) |
| Power consumption | 0.12 A max. |
| Environmental resistance | Operating ambient temperature |
| | 0 to +50°C 32 to 122°F |
| Environmental resistance | Operating ambient humidity |
| | 20 to 85% RH (No condensation) |
| Weight | Approx. 470 g |

*1 The number of connectable hubs is not limited when using a switching hub.

Sensor head unit

| Model | | | LJ-V7020K*11 | LJ-V7020*11 | LJ-V7060K | LJ-V7060 | LJ-V7080 | LJ-V7200 | LJ-V7300 |
|-------------------------------------|---|--------------------|--|--------------------------------------|--|-----------------------------------|--|--|--|
| Mounting conditions | | | Specular reflection | Diffuse reflection | Specular reflection | Diffuse reflection | | | |
| Reference distance | | | 24.2 mm 0.95" | 20 mm 0.79" | 54.6 mm 2.15" | 60 mm 2.36" | 80 mm 3.15" | 200 mm 7.87" | 300 mm 11.81" |
| Measurement range | Z-axis (height) | | ±2.3 mm 0.09" (F.S.=4.6 mm 0.18") | ±2.6 mm 0.10" (F.S.=5.2 mm 0.20") | ±7.6 mm 0.30" (F.S.=15.2 mm 0.60") | ±8 mm 0.31" (F.S.=16 mm 0.63") | ±23 mm 0.91" (F.S.=46 mm 1.81") | ±48 mm 1.89" (F.S.=96 mm 3.78") | ±145 mm 5.71" (F.S.=290 mm 11.42") |
| | X-axis (width) | NEAR side | 6.5 mm 0.26" | 6.5 mm 0.26" | 8 mm 0.31" | 13.5 mm 0.53" | 25 mm 0.98" | 51 mm 2.01" | 110 mm 4.33" |
| | | Reference distance | 7 mm 0.28" | 7 mm 0.28" | 14 mm 0.55" | 15 mm 0.59" | 32 mm 1.26" | 62 mm 2.44" | 180 mm 7.09" |
| | | Far side | 7.5 mm 0.30" | 7.5 mm 0.30" | 8 mm 0.31" | 15 mm 0.59" | 39 mm 1.54" | 73 mm 2.87" | 240 mm 9.45" |
| | | | Blue semiconductor laser | | | | | | |
| Light source | | | 405 nm (visible beam) | | | | | | |
| | Wavelength | | | | | | | | |
| | Laser class (IEC60825-1 FDA(CDRH) Part 1040.10*1) | | Class 2M Laser Product*12 | | Class 2 Laser Product | Class 2M Laser Product*12 | Class 2 Laser Product | | |
| | Output | | 10 mW | | 4.8 mW | 10 mW | 4.8 mW | | |
| Spot size (reference distance) | | | Approx. 14 mm × 35 μm 0.55" × 0.001378" | | Approx. 21 mm × 45 μm 0.83" × 0.001772" | | Approx. 48 mm × 48 μm 1.89" × 0.001890" | Approx. 90 mm × 85 μm 3.54" × 0.003543" | Approx. 240 mm × 610 μm 9.45" × 0.024016" |
| Repeatability*2 | Z-axis (height)*3 | 0.2 μm 0.000008" | | 0.4 μm 0.000016" | | 0.5 μm 0.000020" | | 1 μm 0.000040" | 5 μm 0.000197" |
| | X-axis (width)*4 | 2.5 μm 0.000099" | | 5 μm 0.000197" | | 10 μm 0.000394" | | 20 μm 0.000788" | 60 μm 0.002363" |
| Linearity | Z-axis (height)*5 | ±0.1% of F.S. | | | | ±0.05 to ±0.15% of F.S.*6 | | | |
| Profile Data interval | X-axis (width) | 10 μm 0.0004" | | 20 μm 0.0008" | | 50 μm 0.002" | | 100 μm 0.004" | 300 μm 0.012" |
| Sampling cycle (trigger interval)*7 | | | Top speed: 16 μs (high-speed mode) Top speed: 32 μs (advanced function mode) | | | | | | |
| Temperature characteristics | | | 0.01% of F.S./°C | | | | | | |
| Environmental resistance | Enclosure rating*8 | | IP67 (IEC60529) | | | | | | |
| | Ambient operating illuminance*9 | | Incandescent lamp: 10000 lux max. | | | | | | |
| | Ambient temperature*10 | | 0 to +45°C 32 to 113°F | | | | | | |
| | Operating Ambient humidity | | 20 to 85% RH (No condensation) | | | | | | |
| | Vibration resistance | | 10 to 57 Hz, 1.5 mm 0.06" double amplitude in X, Y, and Z directions, 3 hours respectively | | | | | | |
| | Impact resistance | | 15 G/6 msec | | | | | | |
| Material | | | Aluminum | | | | | | |
| Weight | | | Approx. 410 g | | Approx. 450 g | | Approx. 400 g | Approx. 550 g | Approx. 1000 g |

*1 The laser classification for FDA(CDRH) is implemented based on IEC60825-1 in accordance with the requirements of Laser Notice No. 50.

*2 This value is from a case in which measurement has been performed with a reference distance with 4,096 times of averaging.

*3 The measurement targets are KEYENCE standard targets. This value is from a case in which the average height of the default setting area has been measured in height mode. All other settings are default.

*4 The measurement target is a pin gauge. This value is from a case in which the position of the intersection between the rounded surface of the pin gauge and the edge level has been measured in position mode. All other settings are default.

*5 The measurement targets are KEYENCE standard targets. The profile data is from a case in which measurement has been performed with 64 times of smoothing and 8 times of averaging. All other settings are default.

*6 The linearity will differ depending on the measurement area. (See the diagram on the right.)

*7 For high-speed mode, when the measurement area is at its minimum, binning is ON, image capture mode is set to standard, and parallel image capture is ON. All other settings are default. For advanced function mode, when the measurement area is at its minimum, binning is ON and image capture mode is set to standard. All other settings are default.

8 This value is from a case in which the sensor head cable (CB-B) or extension cable (CB-B*E) has been connected.

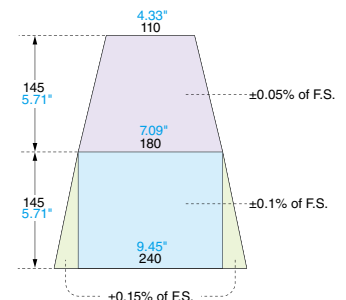
*9 This is the illuminance for the light-receiving surface of the sensor head during white paper measurement when light has been shined onto the white paper.

*10 The sensor head must be mounted on a metal plate for use.

*11 The double polarization function cannot be used.

*12 Do not look into the beam directly using any optical instruments (such as eye loupes, magnifiers, microscopes, telescopes, or binoculars).

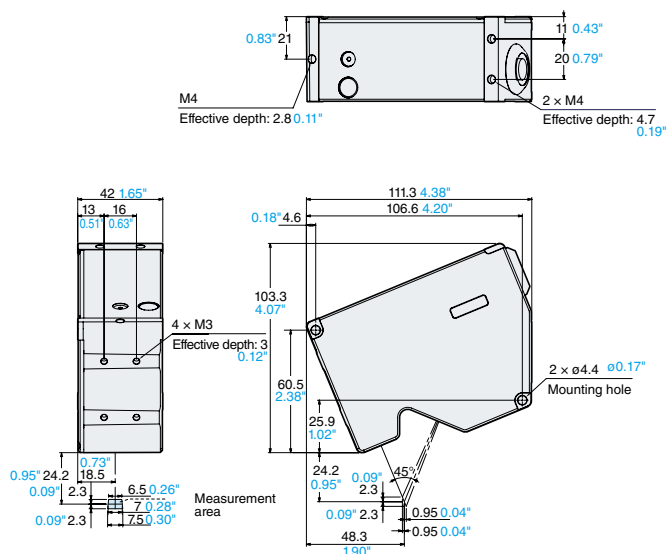
Viewing the laser output with an optical instrument may pose an eye hazard.



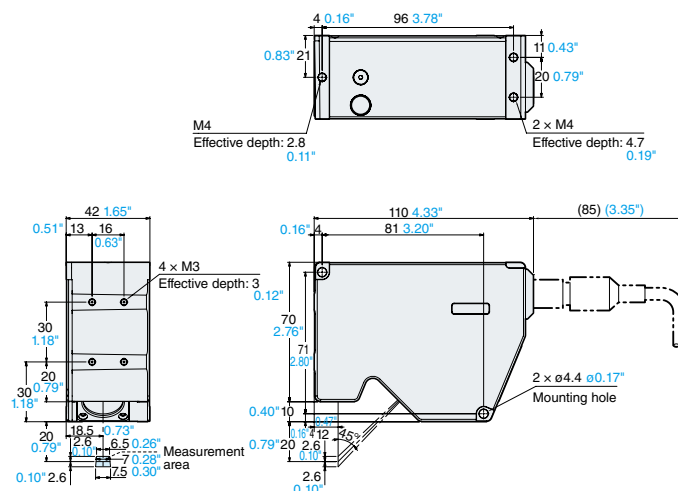
DIMENSIONS

Sensor head

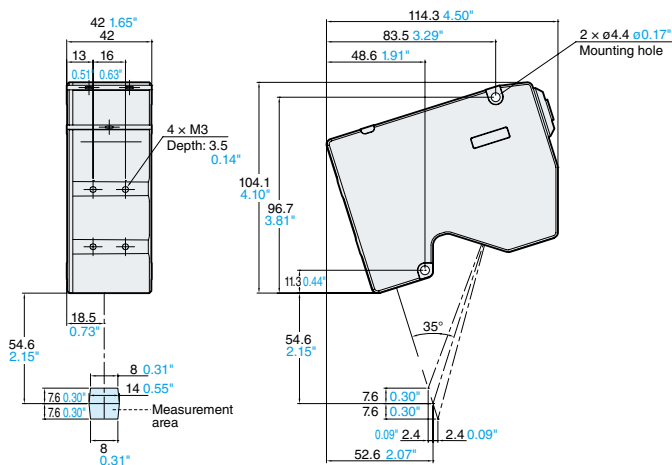
Ultra high-accuracy specular reflection model
LJ-V7020K



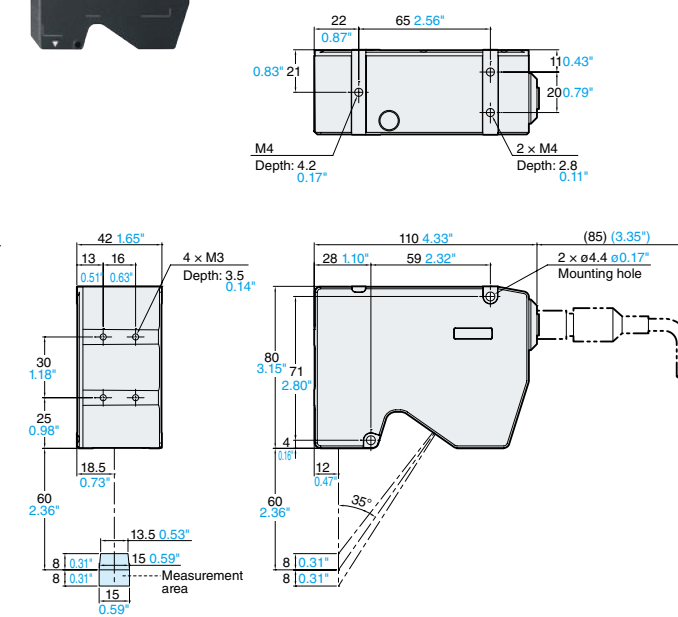
Ultra high-accuracy model
LJ-V7020



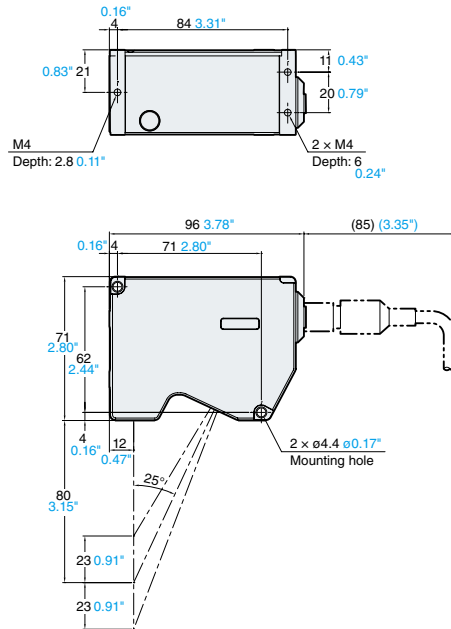
High-accuracy specular reflection model
LJ-V7060K



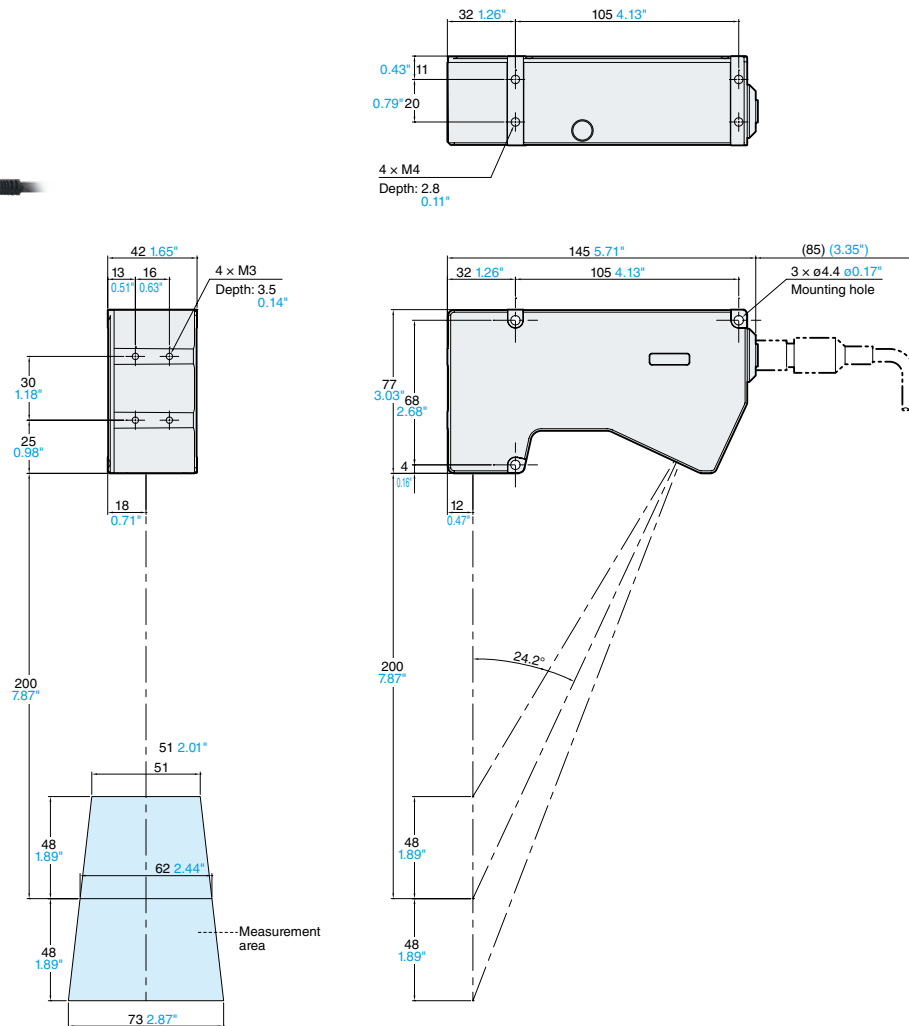
High-accuracy model
LJ-V7060



Middle-range model
LJ-V7080



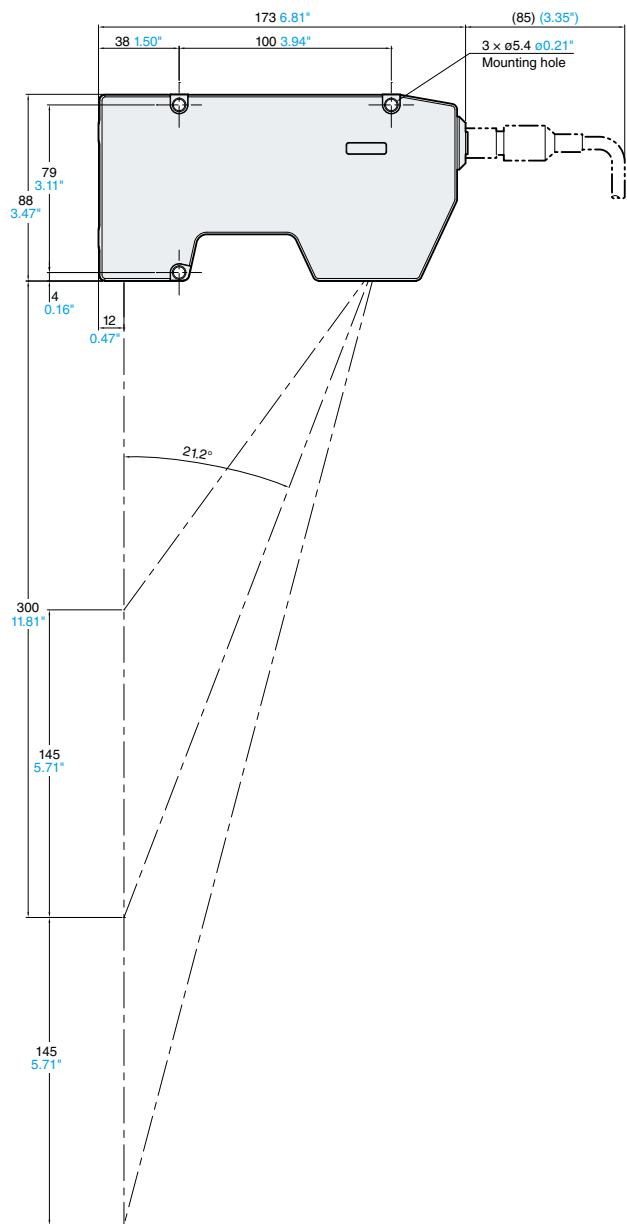
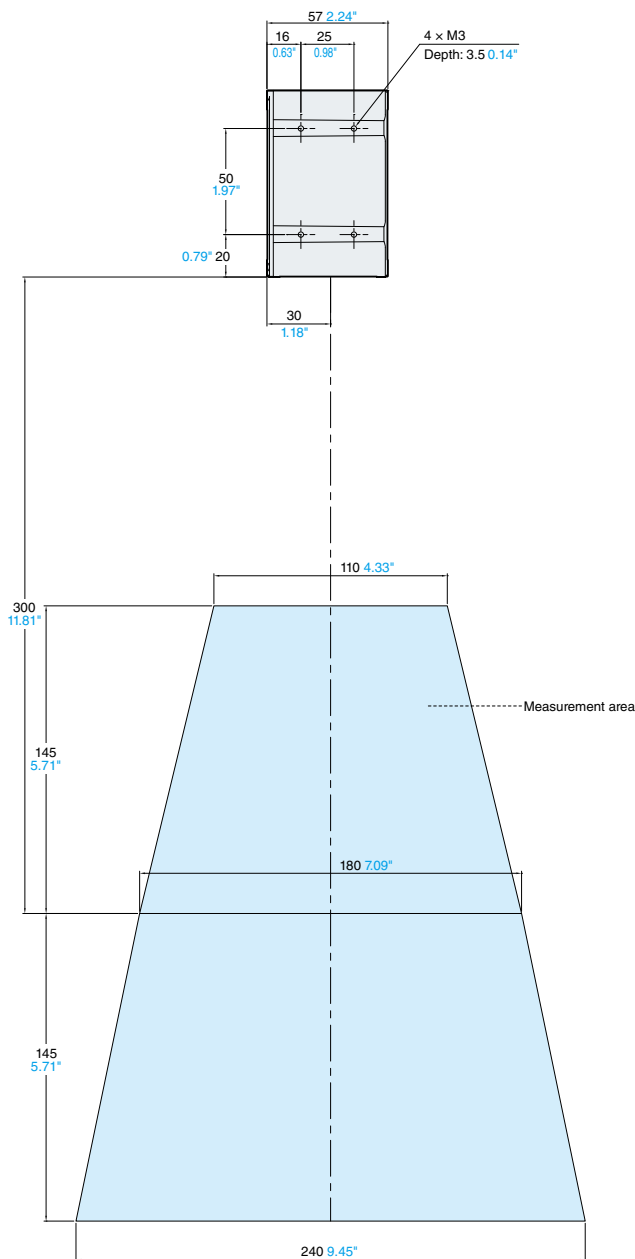
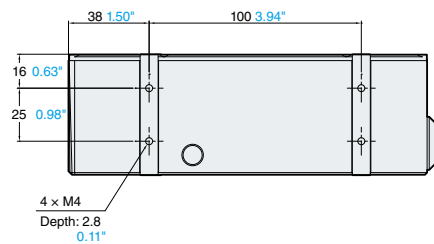
Long-range model
LJ-V7200



DIMENSIONS

Sensor head

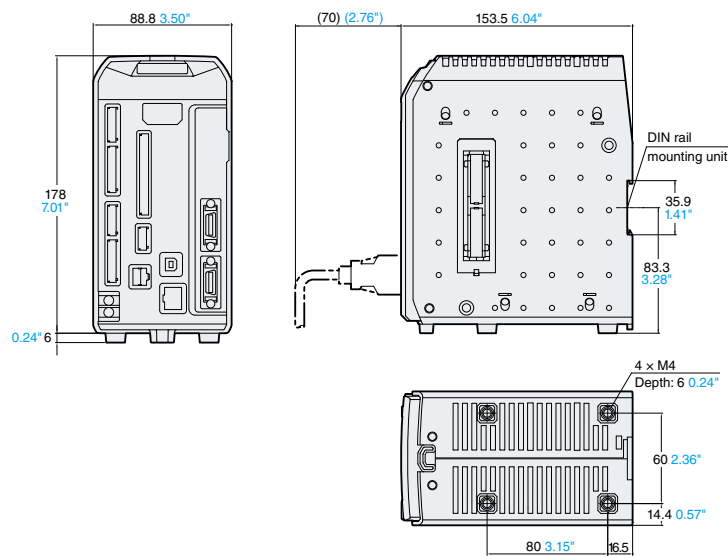
Ultra-long range model
LJ-V7300



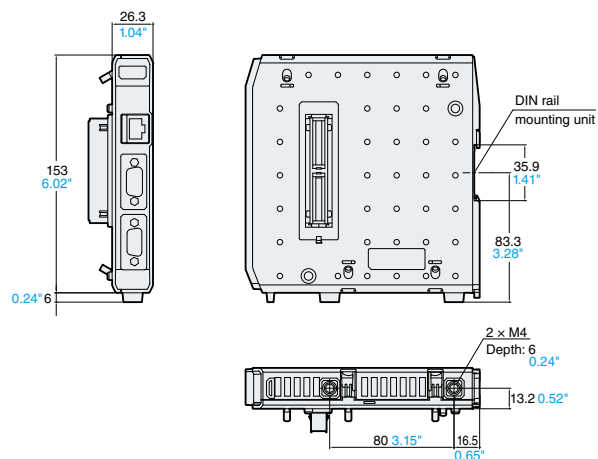
Controller/Cable/Monitor



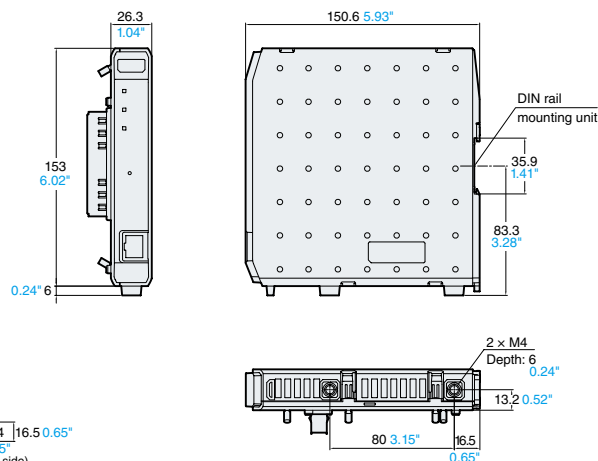
Multi-function controller
LJ-V7001(P)



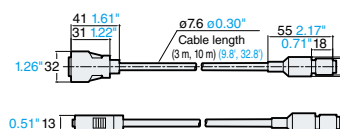
Display output unit
LJ-VM100



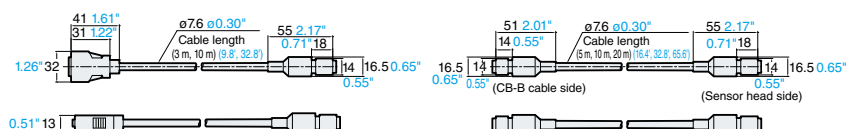
EtherNet/IP™ unit **CB-EP100**
PROFINET unit **CB-PN100**



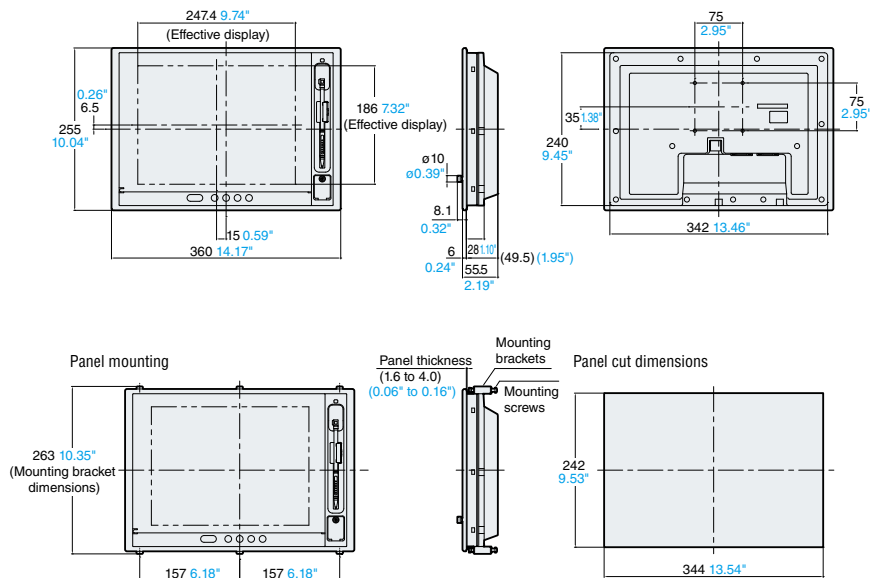
Head-to-controller cable
CB-B3/CB-B10



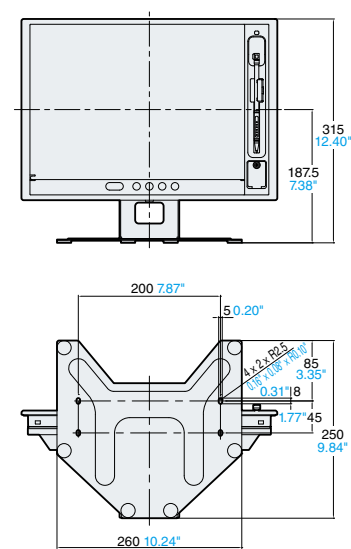
Extension cable
CB-B5E/CB-B10E/CB-B20E



Touch panel HMI
CA-MP120T

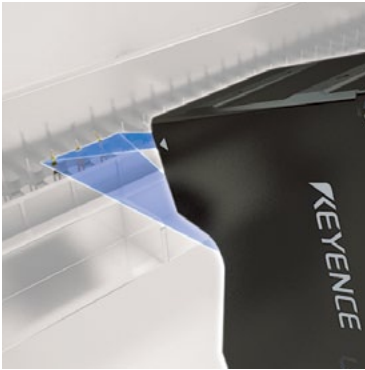


Specialized monitor stand
OP-87262

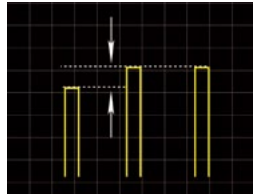


2D MEASUREMENT

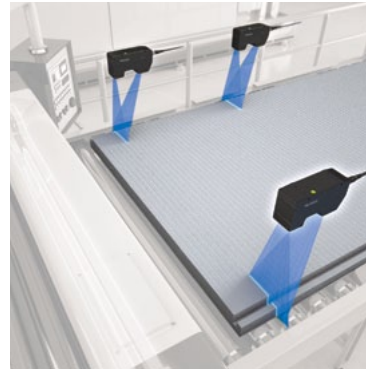
HEIGHT AND STEP DIFFERENCE



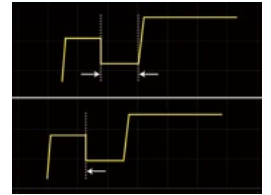
Pin height and step height measurement



WIDTH AND POSITION



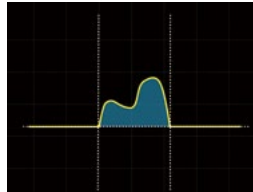
Building material board positioning



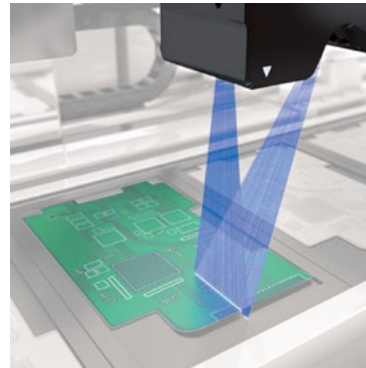
PROFILE AND CROSS SECTION



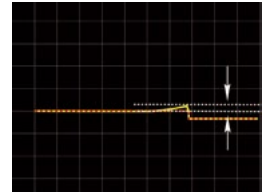
Sealant inspection



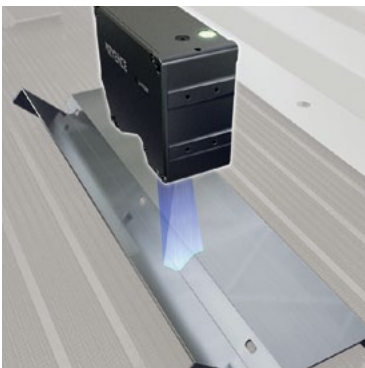
WARPAGE AND FLATNESS



Warpage measurement of PCBs



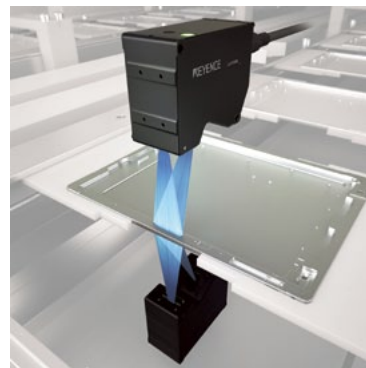
ANGLE AND RADIUS



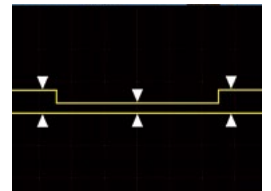
Angle measurement of processed products



THICKNESS MEASUREMENT



Case thickness measurement



3D MEASUREMENT (IMAGE PROCESSING)

SOLDERING BRIDGE AND VOLUME INSPECTION

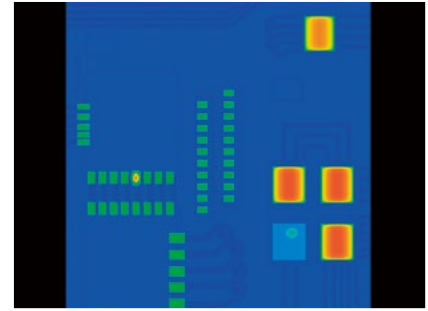
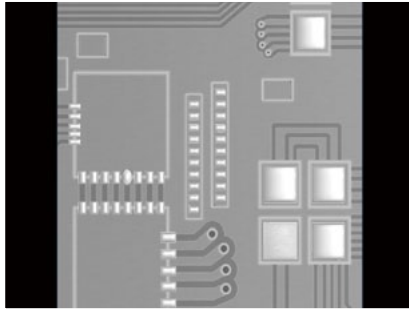


Traditional cameras

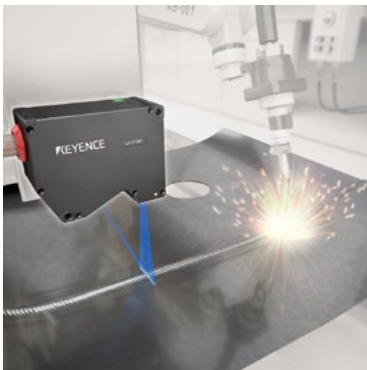
Inspection is difficult due to influence from PCB patterns and solder surface conditions.

LJ-V + Image processing

Inspections including solder presence, bridging, and volume can be performed.



TAILORED BLANK WELDING APPEARANCE INSPECTION

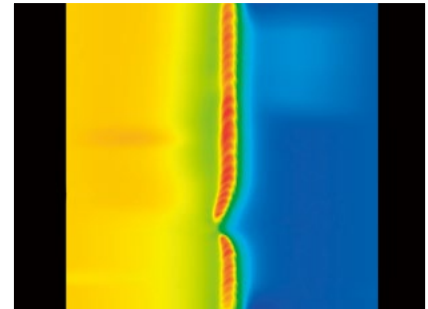
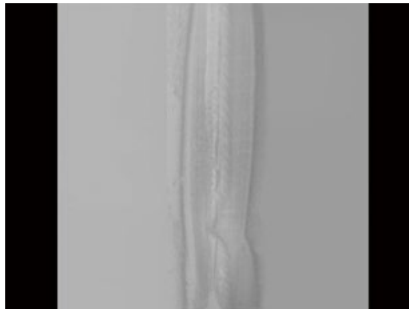


Traditional cameras

Inspection using the camera is difficult because the surface conditions of the workpiece are not stable.

LJ-V + Image processing

Stable inspection is possible regardless of the workpiece surface.



CARD NUMBER CHARACTER RECOGNITION (OCR)

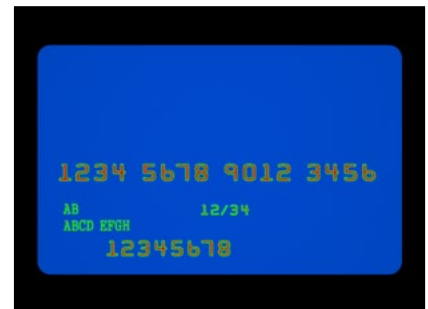


Traditional cameras

Detection is difficult due to influence from the background.

LJ-V + Image processing

Reliable character recognition (OCR) is possible no matter what kind of card is being used.



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SAFETY INFORMATION

Please read the instruction manual carefully in order to safely operate any KEYENCE product.

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LJV-KA-C6-US 1126-2 [611C88]