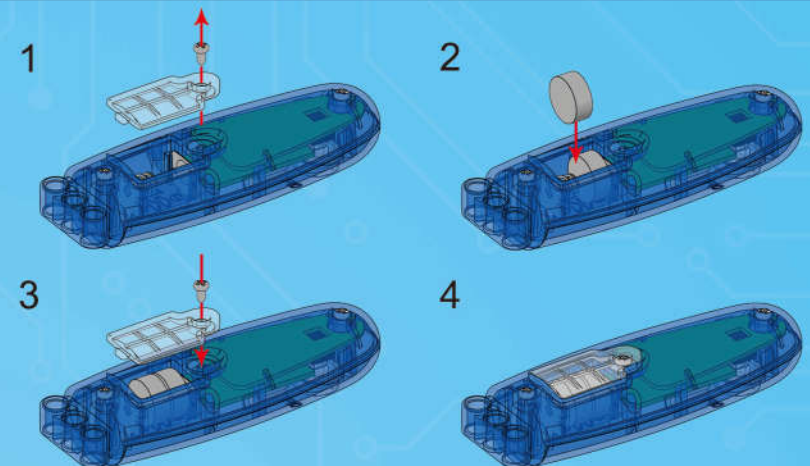
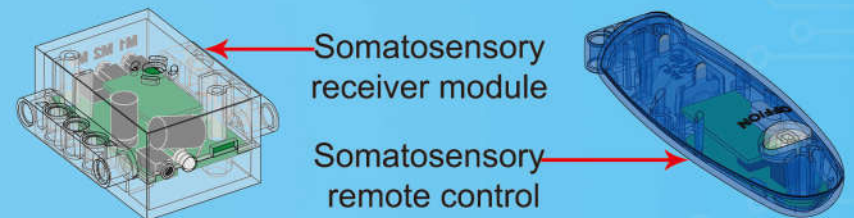


1.5V AA 1:1 ×6

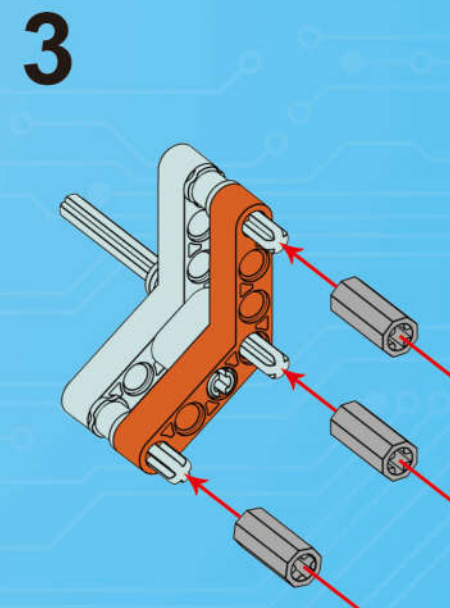
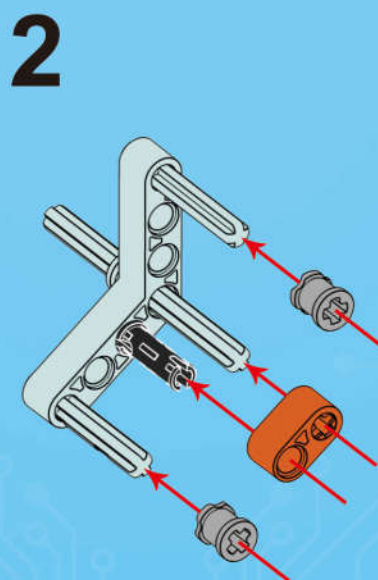
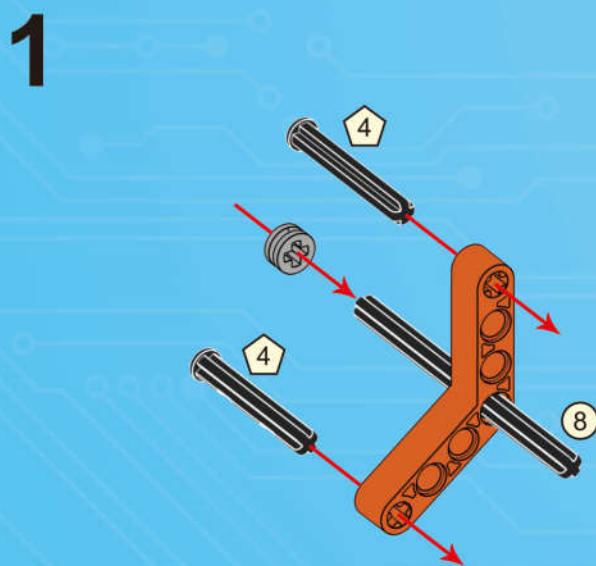
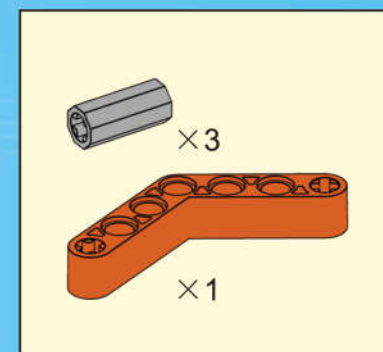
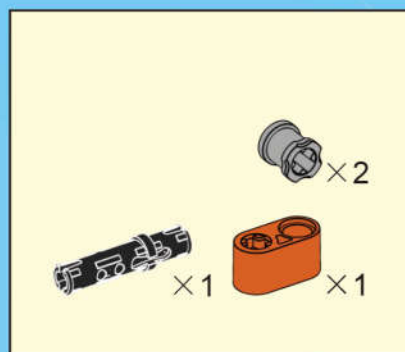
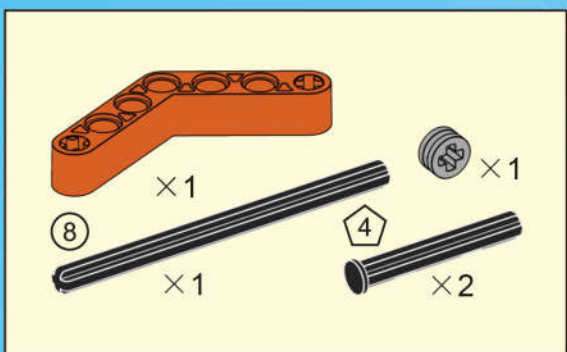
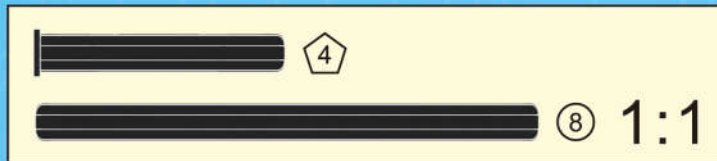
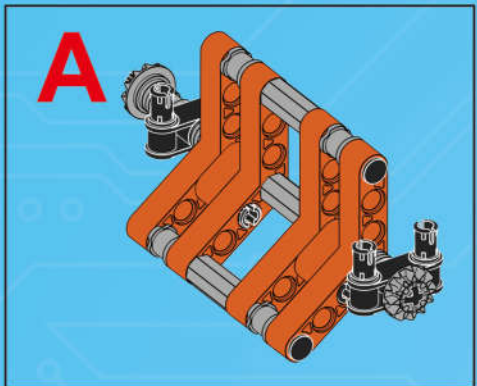


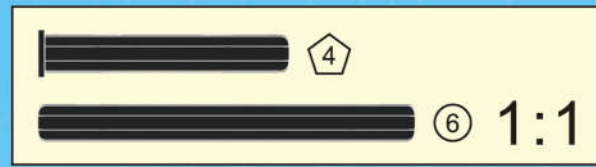
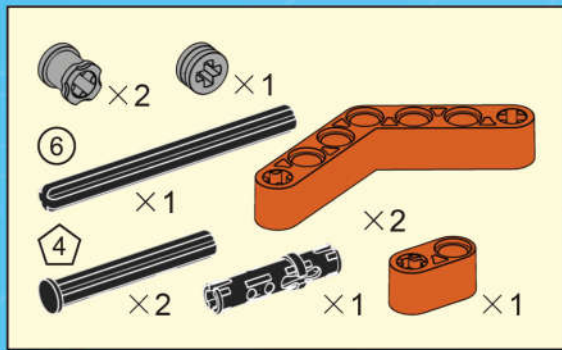
LR44 1:1 ×2



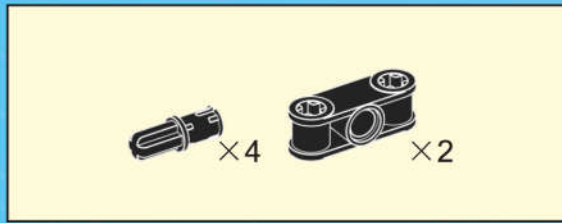
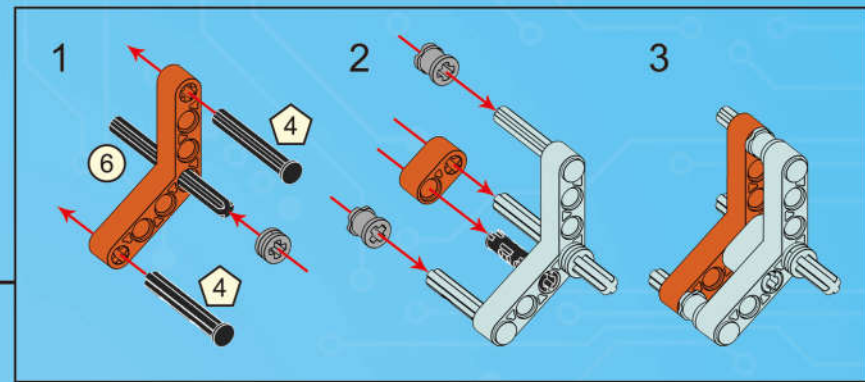
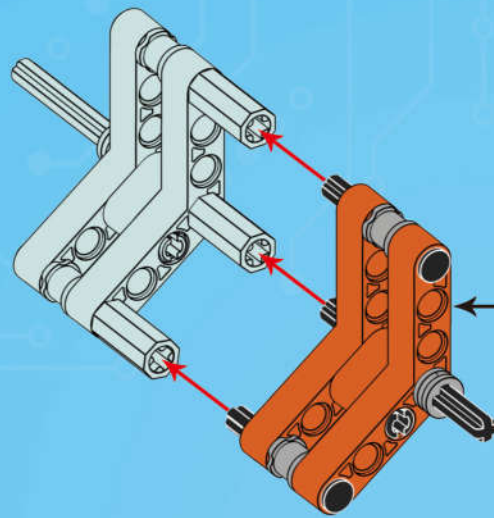
Cautions:

1. Make sure that the 130 high speed motor and the somatosensory receiver module, the 9V power supply module and the somatosensory receiver module are connected without error.
2. When matching the somatosensory remote control with the somatosensory receiver module, the 9V power switch should first be turned on. At this time, the somatosensory receiver module indicator lamps are red green alternating and fast flickering, press the switch of somatosensory remote control, two modules' green lamps are always bright, that is, the pairing is successful.
3. In the process of operation, if the somatosensory remote control or the somatosensory receiver module is turned off, the power supply of the other part should be turned off and re matched.
4. In the environment of strong electromagnetic interference, the receiving distance can be shortened or even uncontrolled.
5. When the power is too low (the remote control or receiver module indicator lamps are red, green alternating and flickering normally), it will lead to insensitivity of the transmitting and receiving or abnormal operation of the motor. Then replace the batteries.
6. Please turn off the power switch in time when you do not use it. Please take out the batteries when not used for a long time.

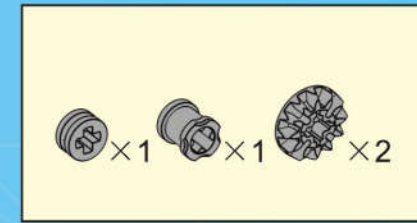
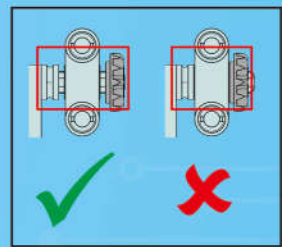
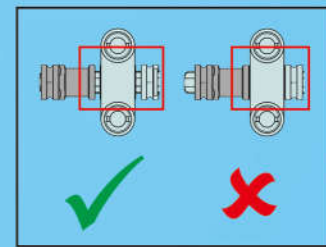
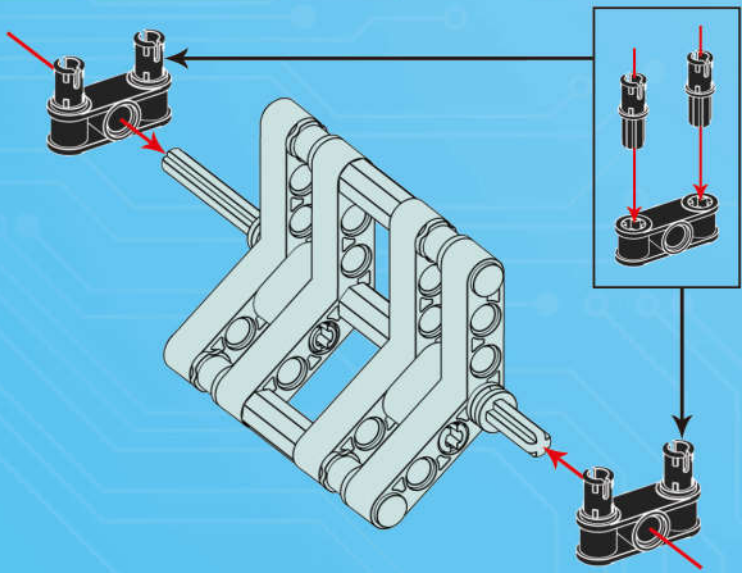




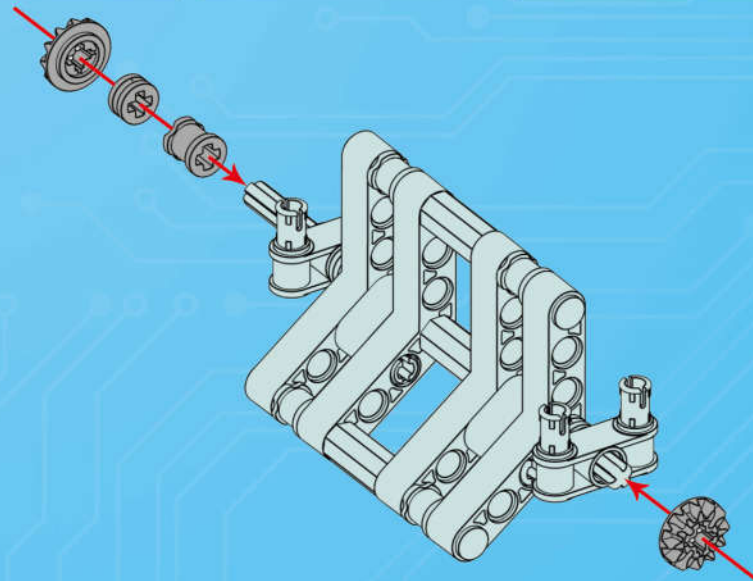
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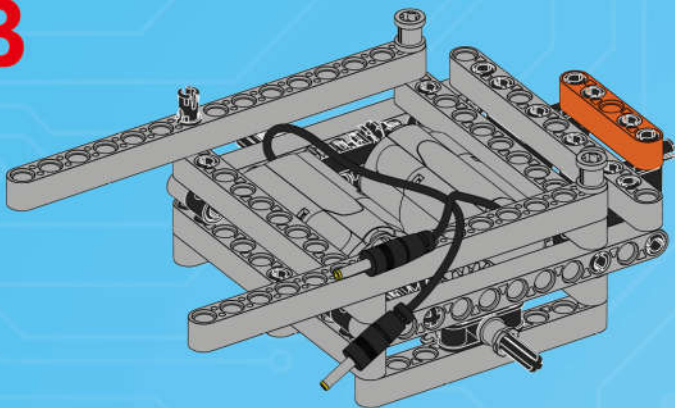
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6



B



9



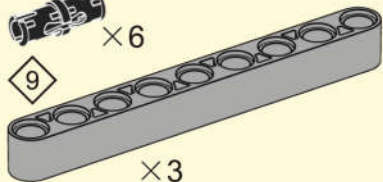
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1:1



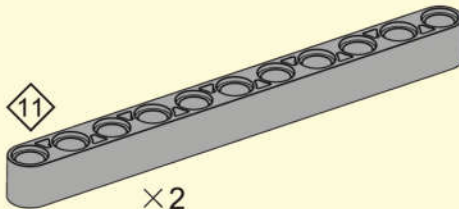
×6

9



×3

11

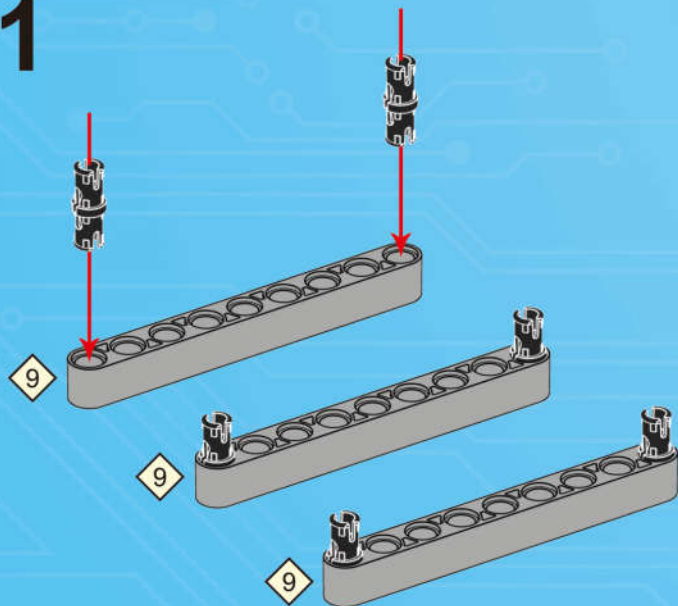


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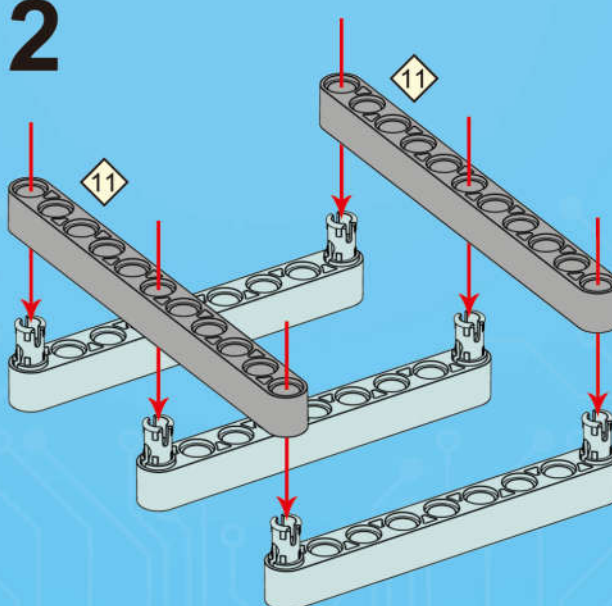


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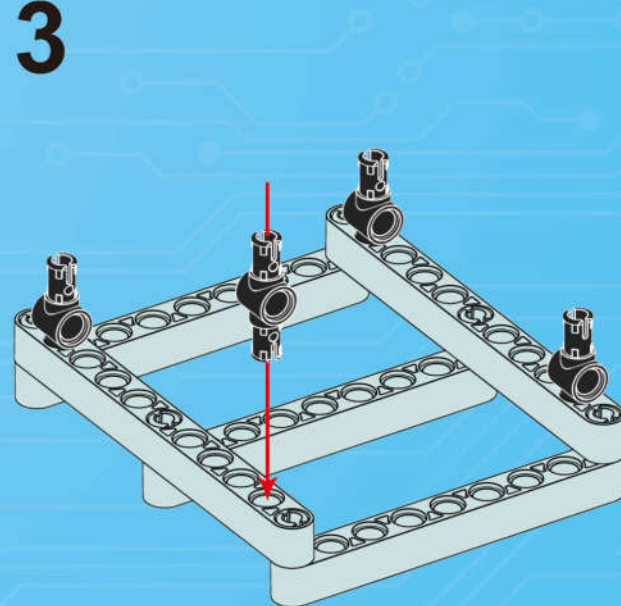
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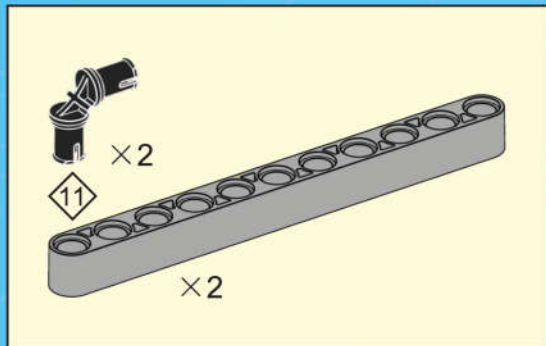


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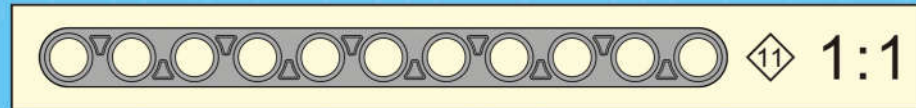


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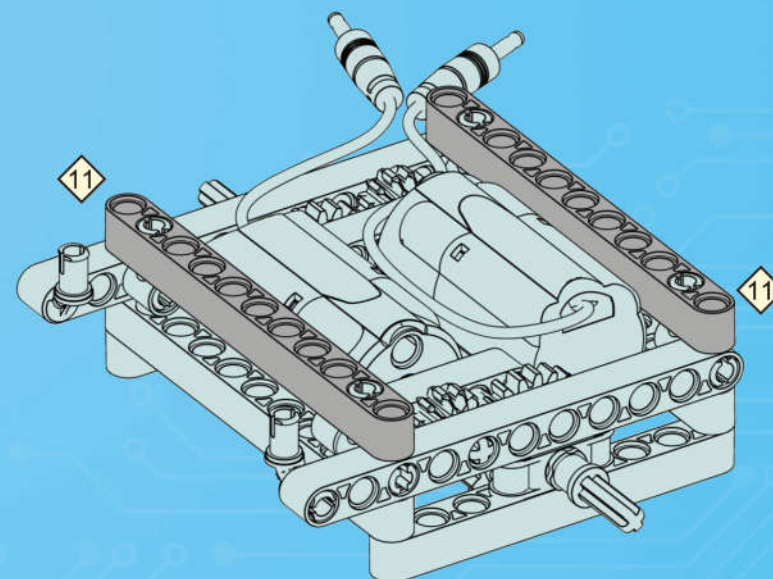
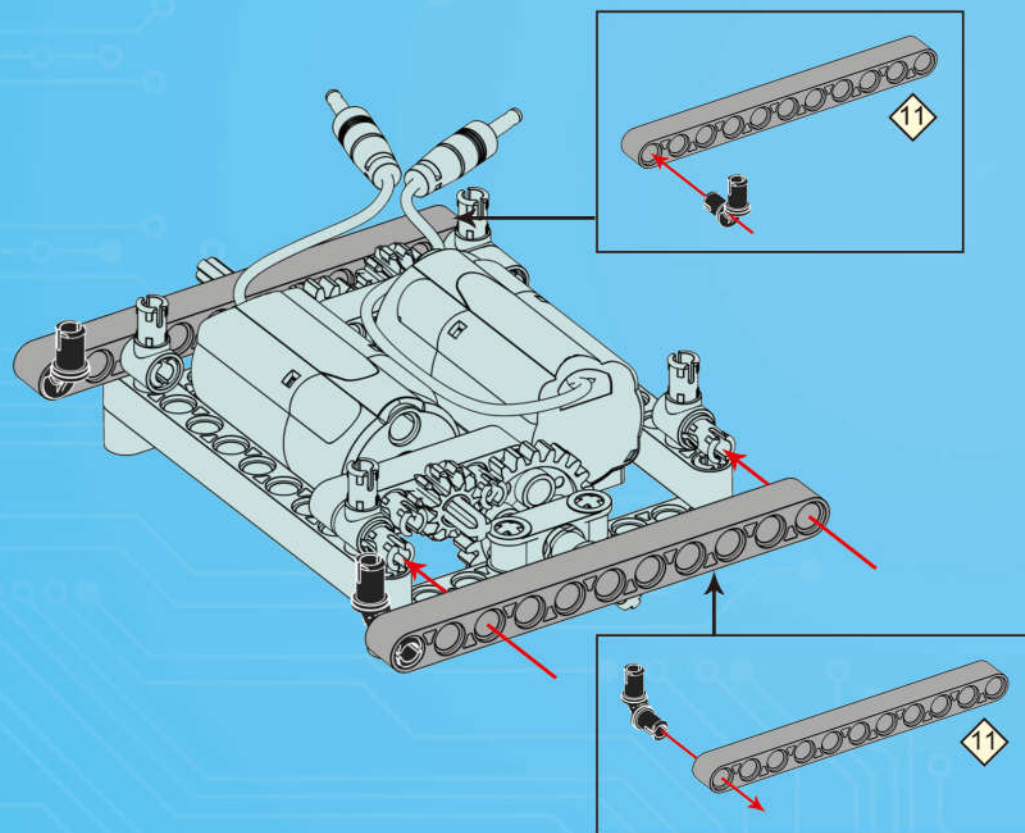
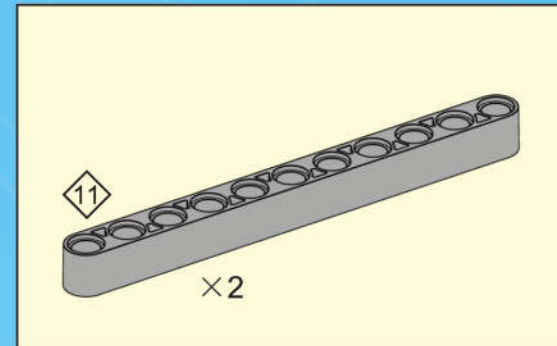


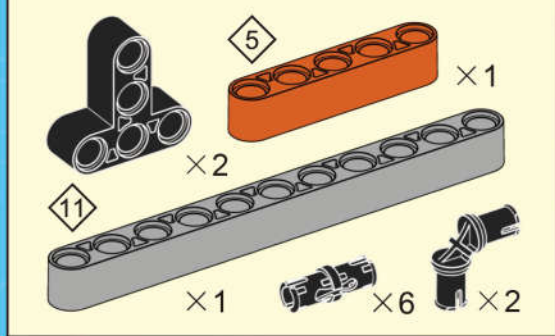


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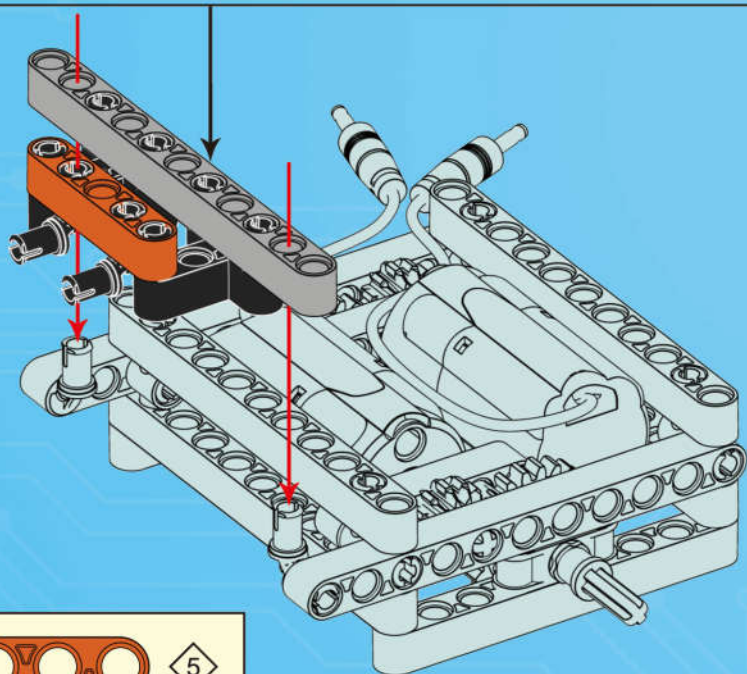
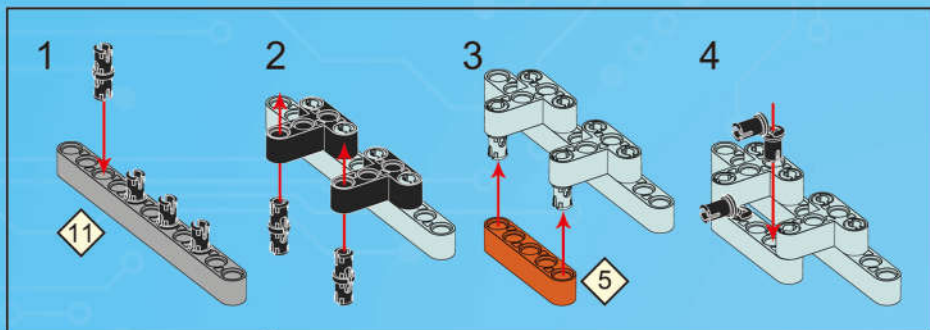


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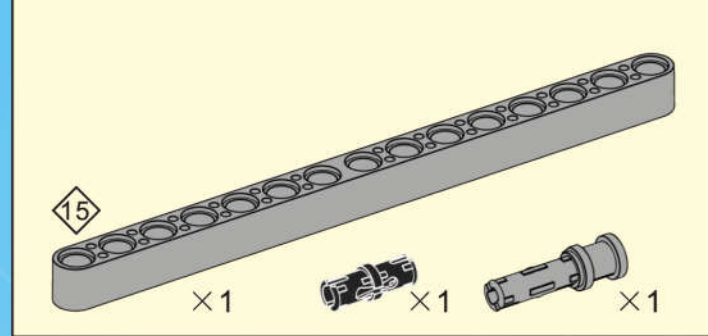




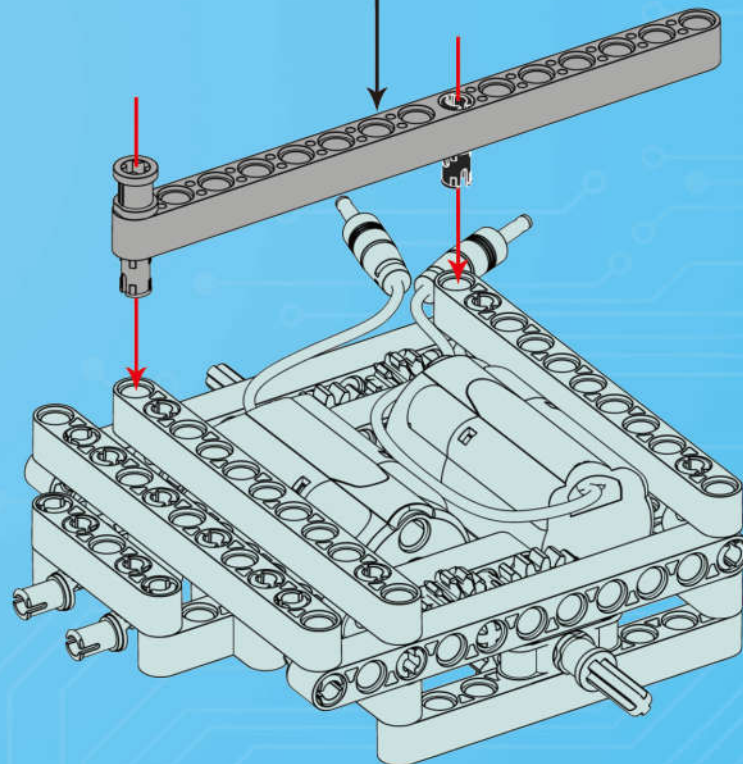
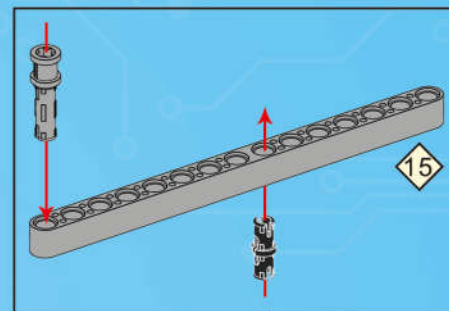
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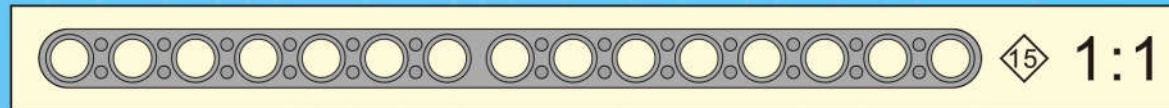
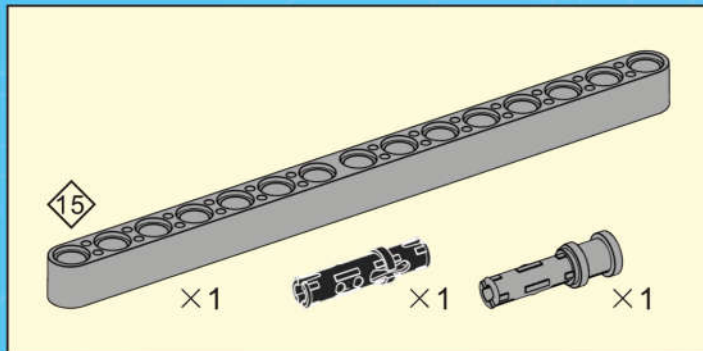


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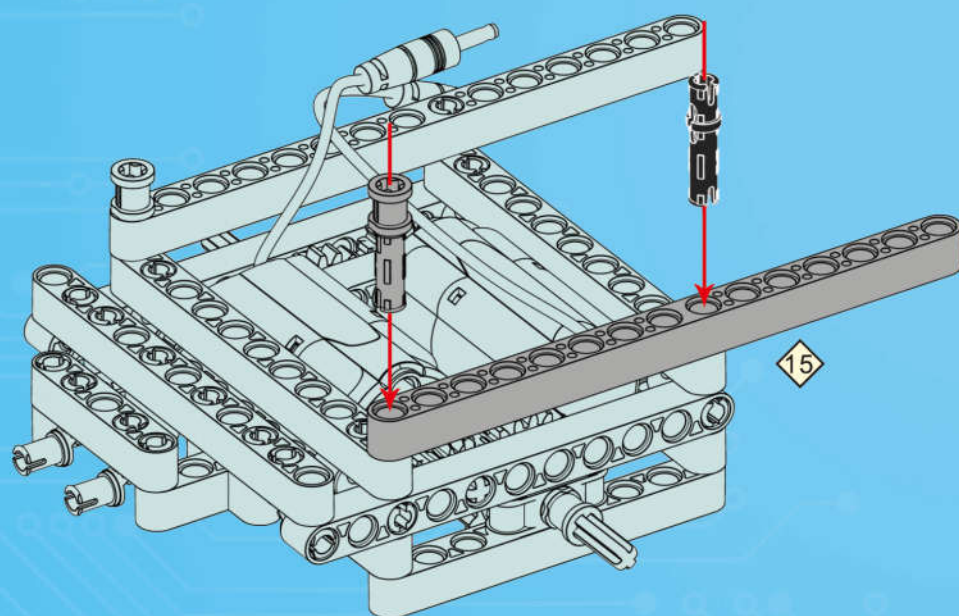


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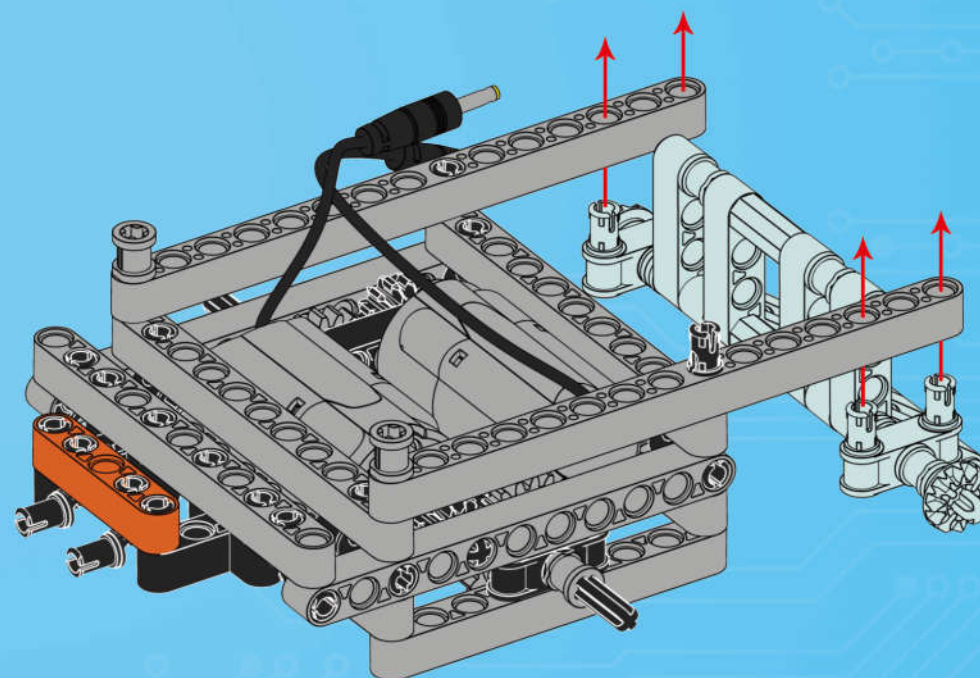


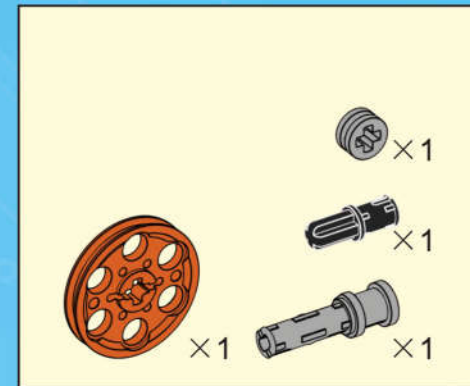
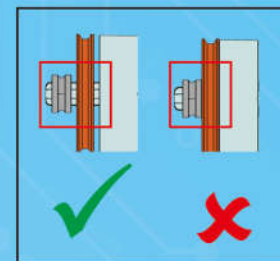
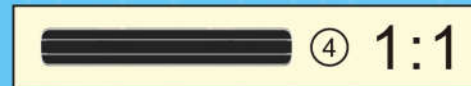
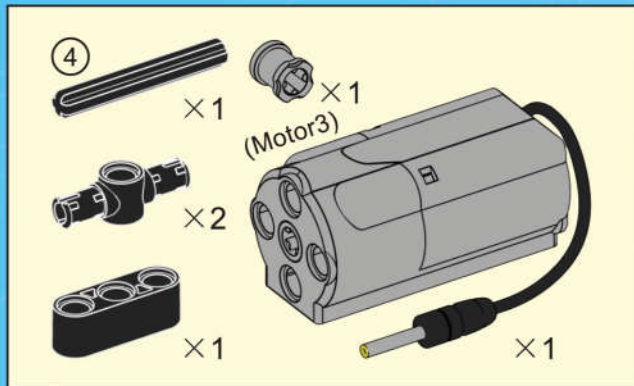


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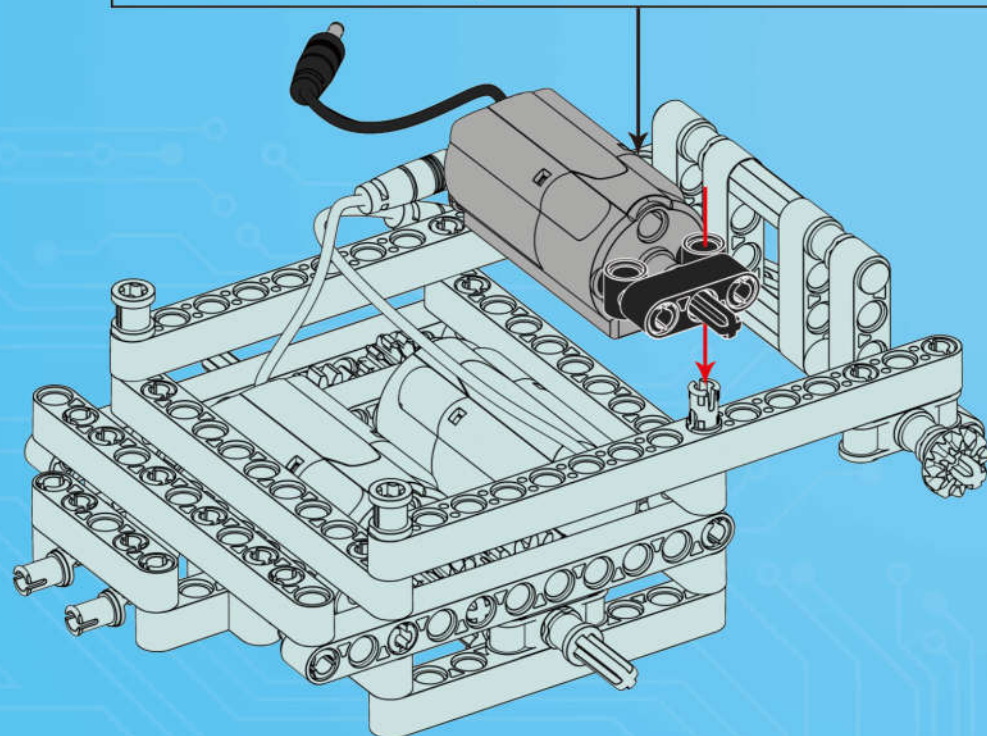
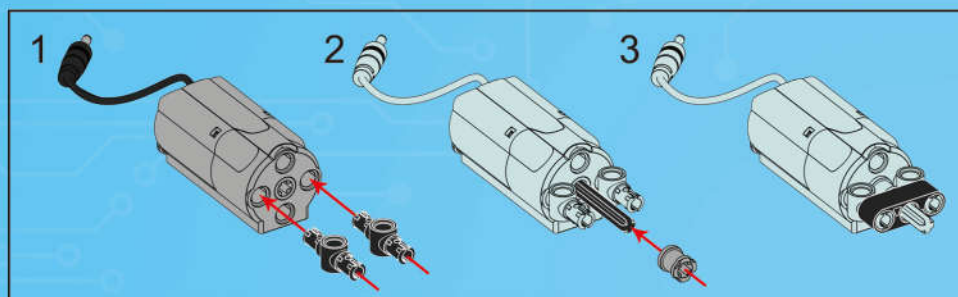


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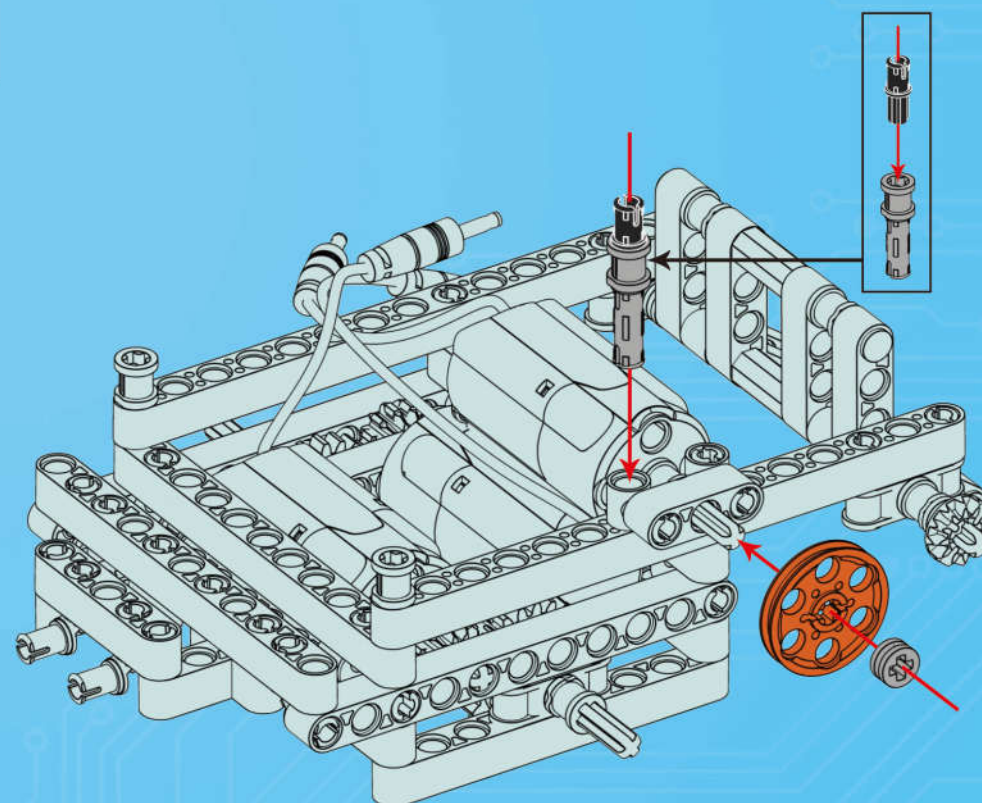




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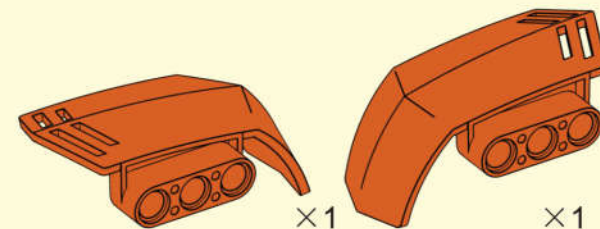
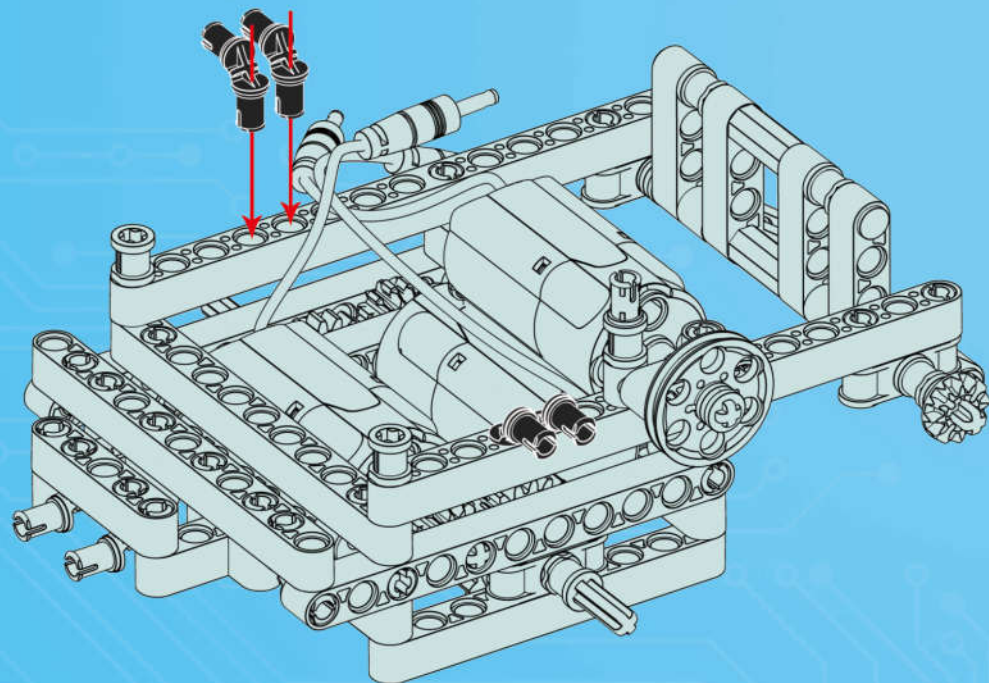


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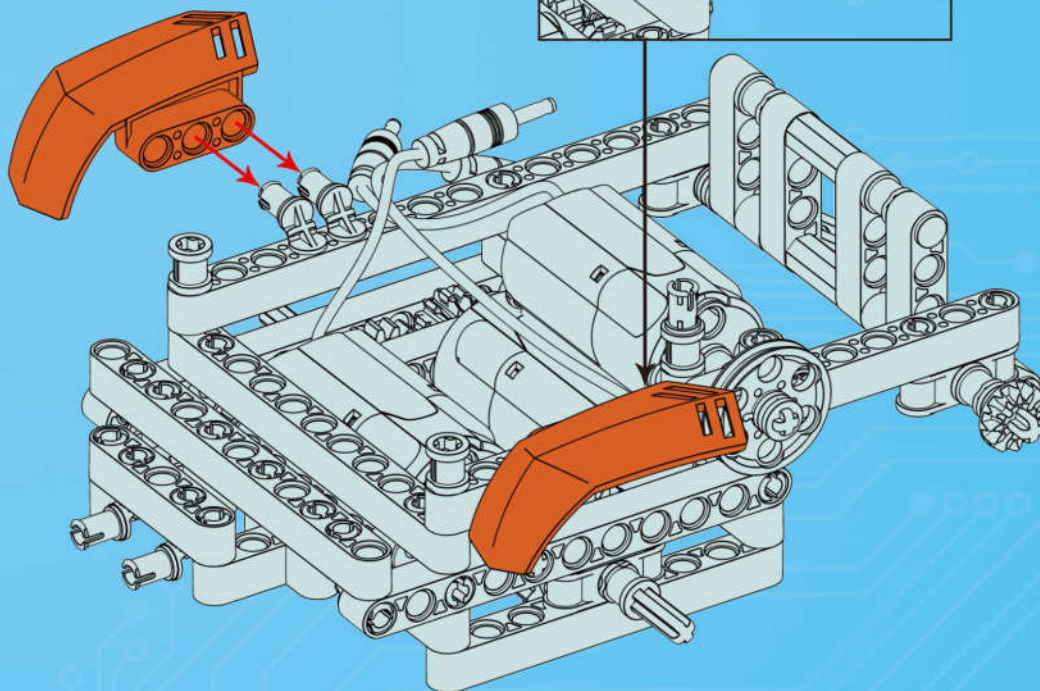


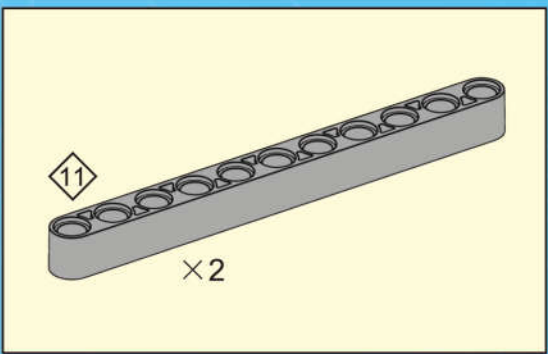
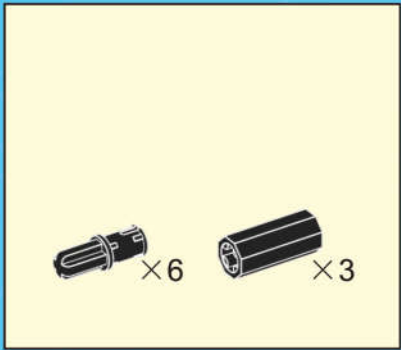
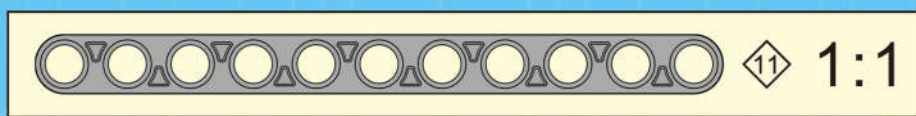


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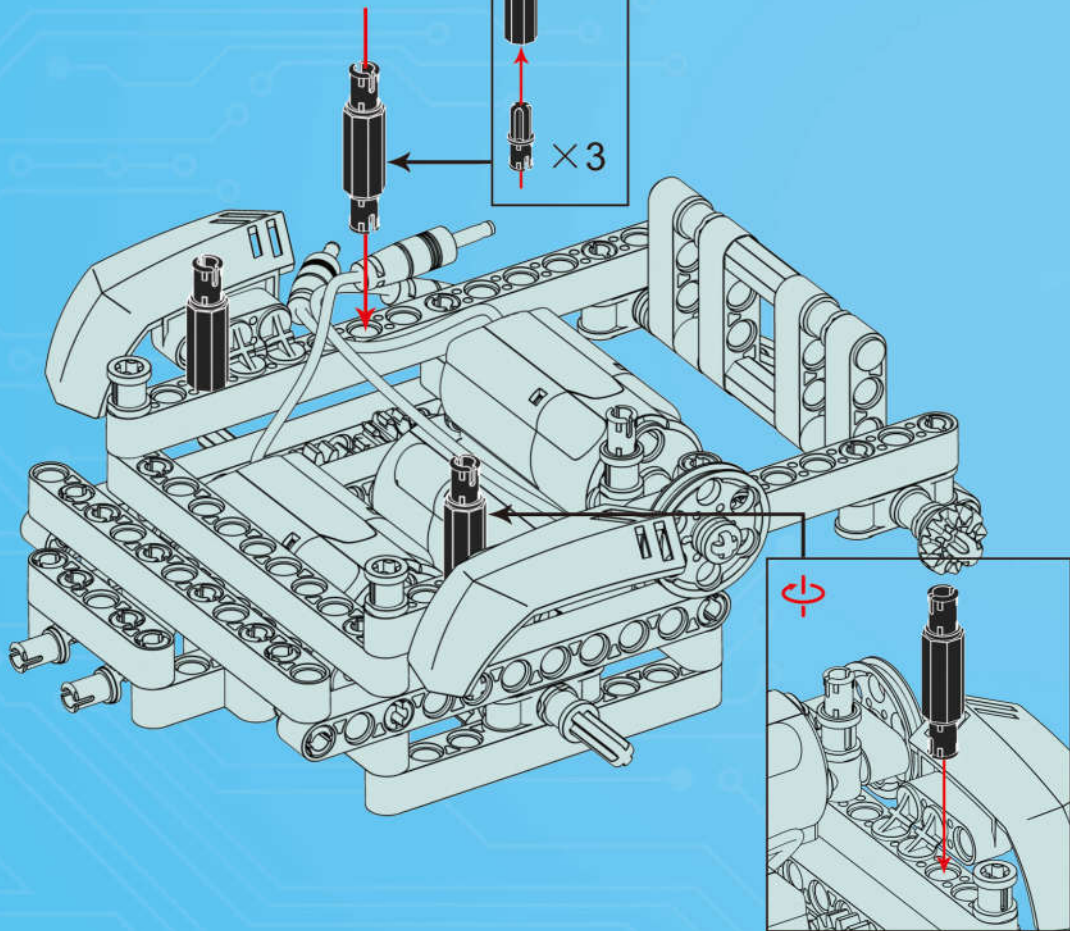
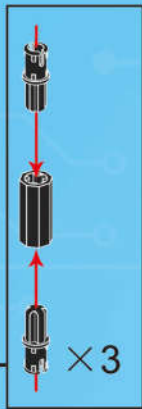


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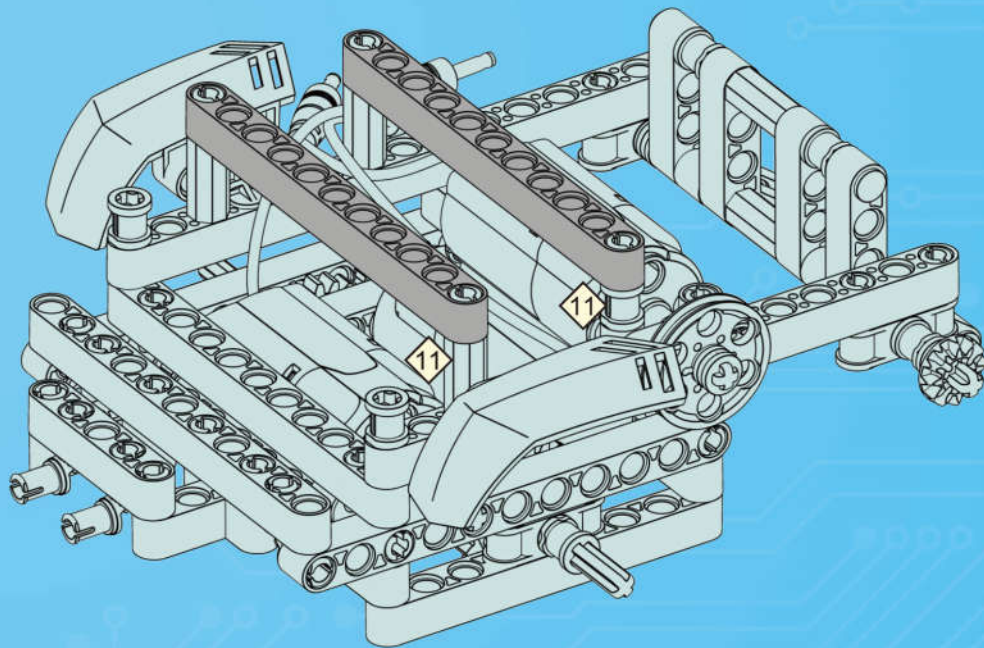




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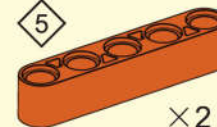
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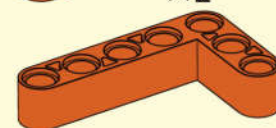


5 1:1

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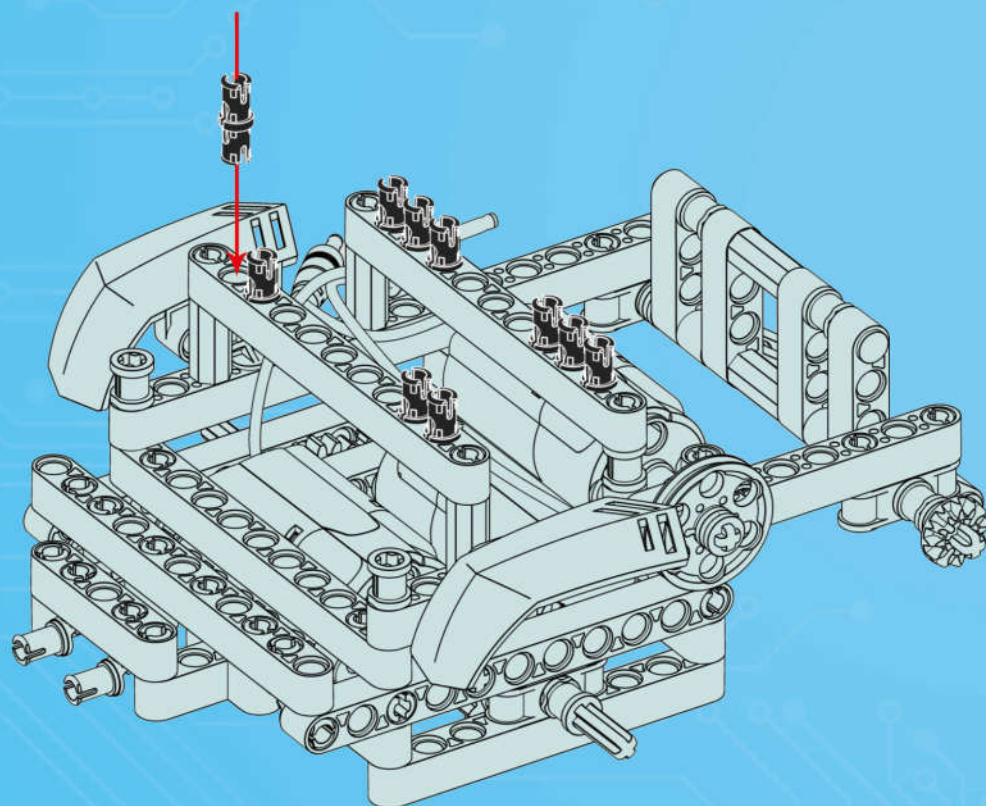


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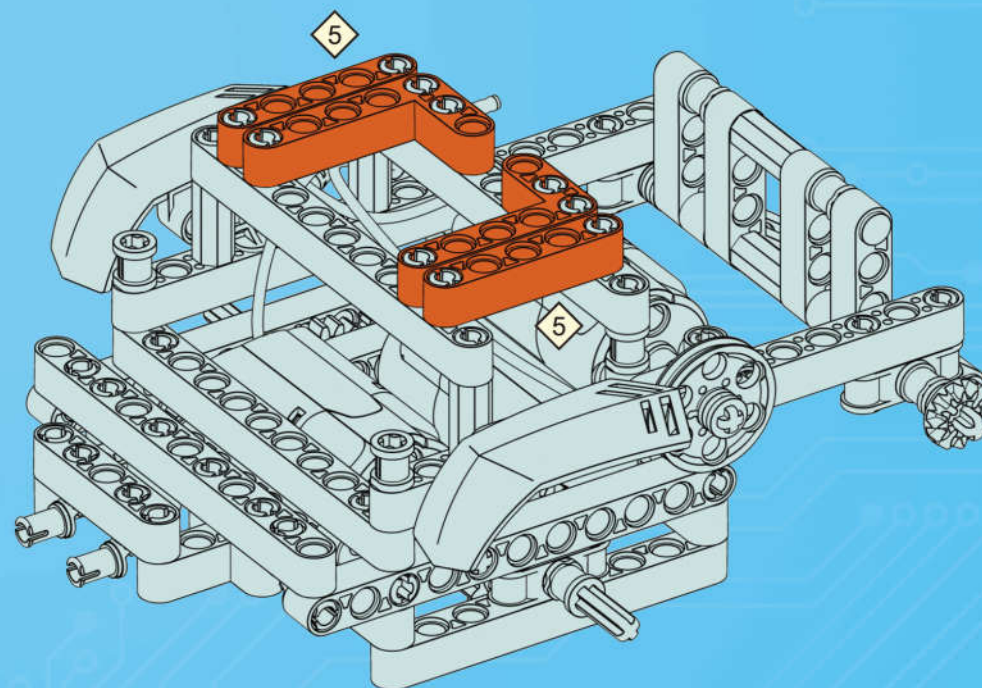


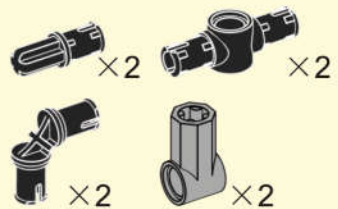
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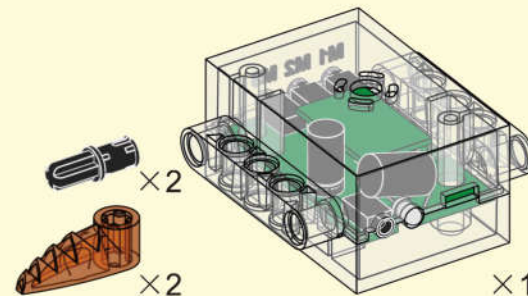
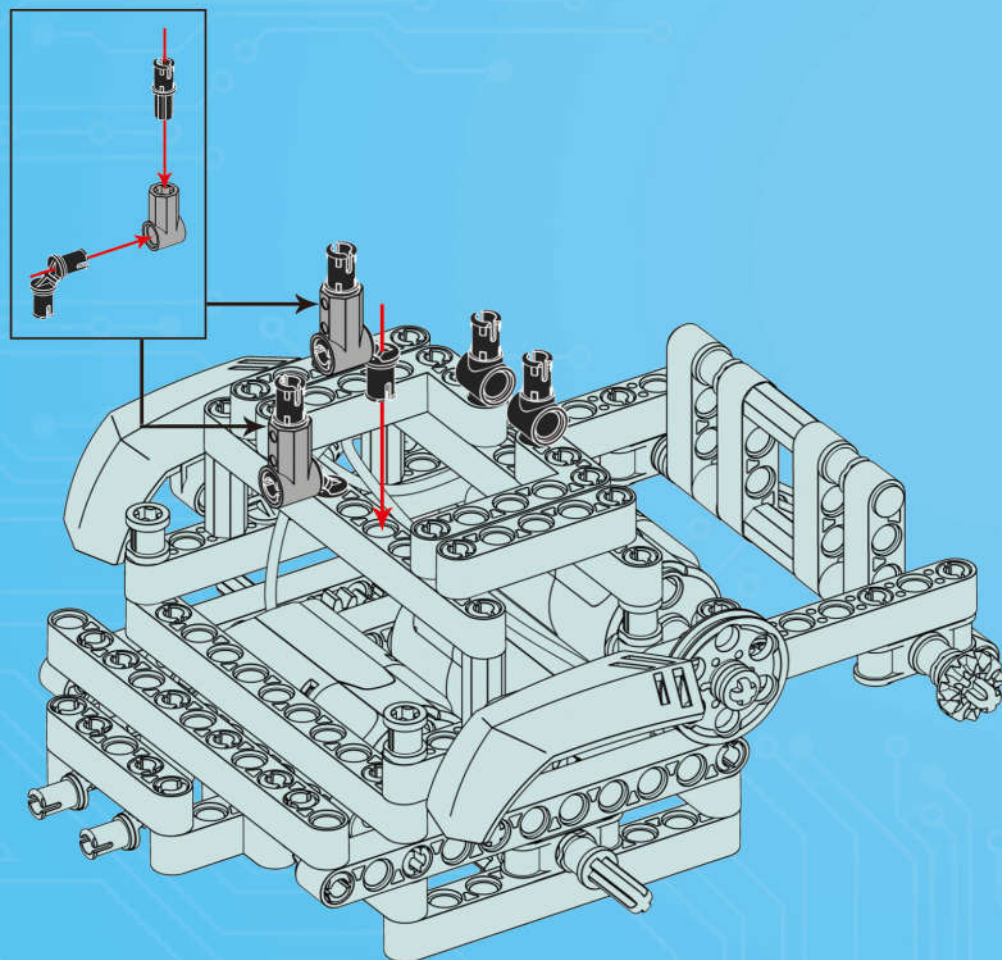


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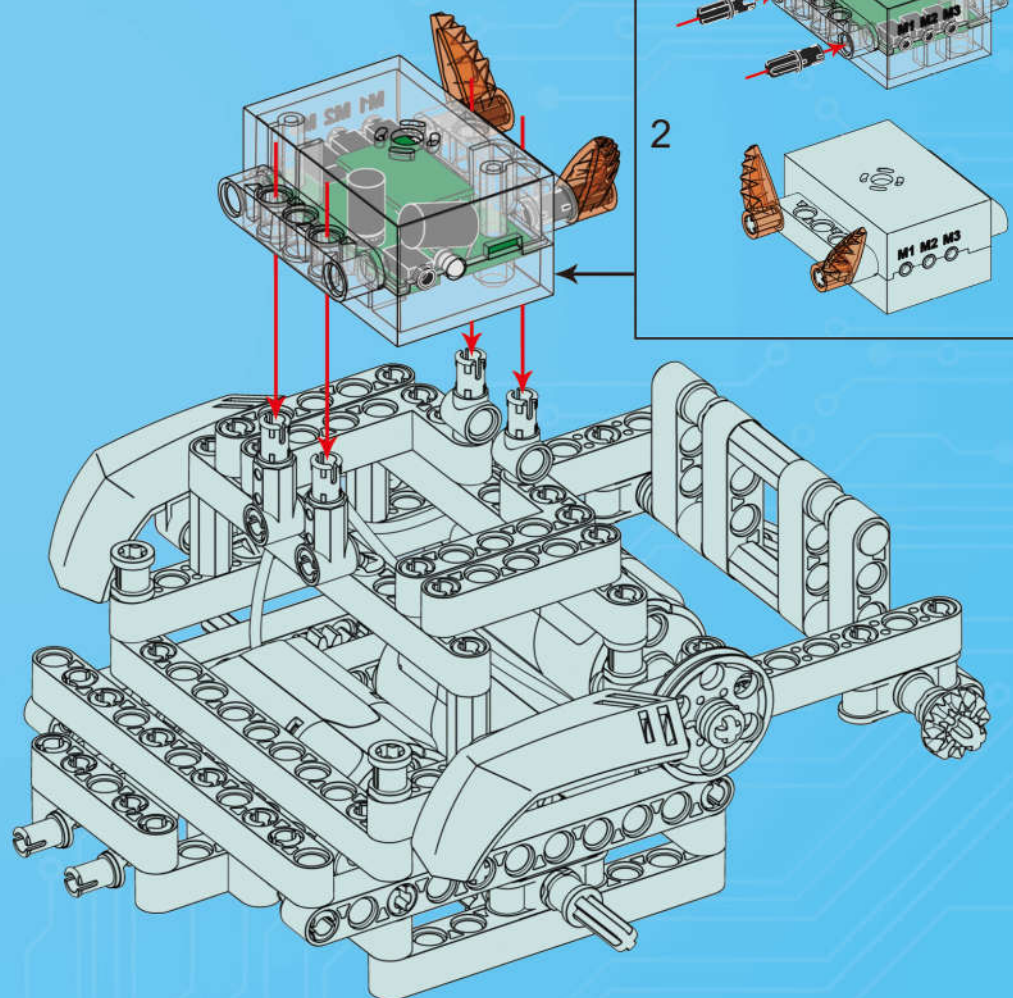


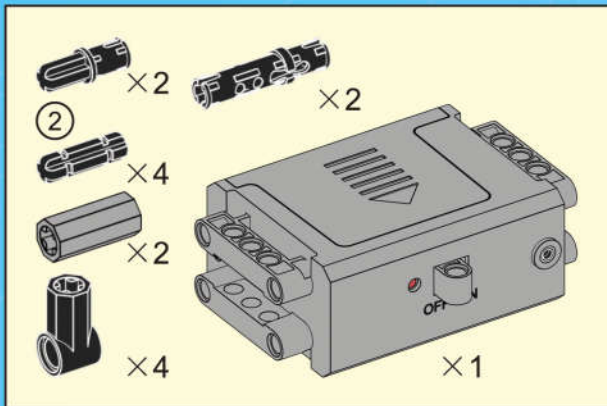


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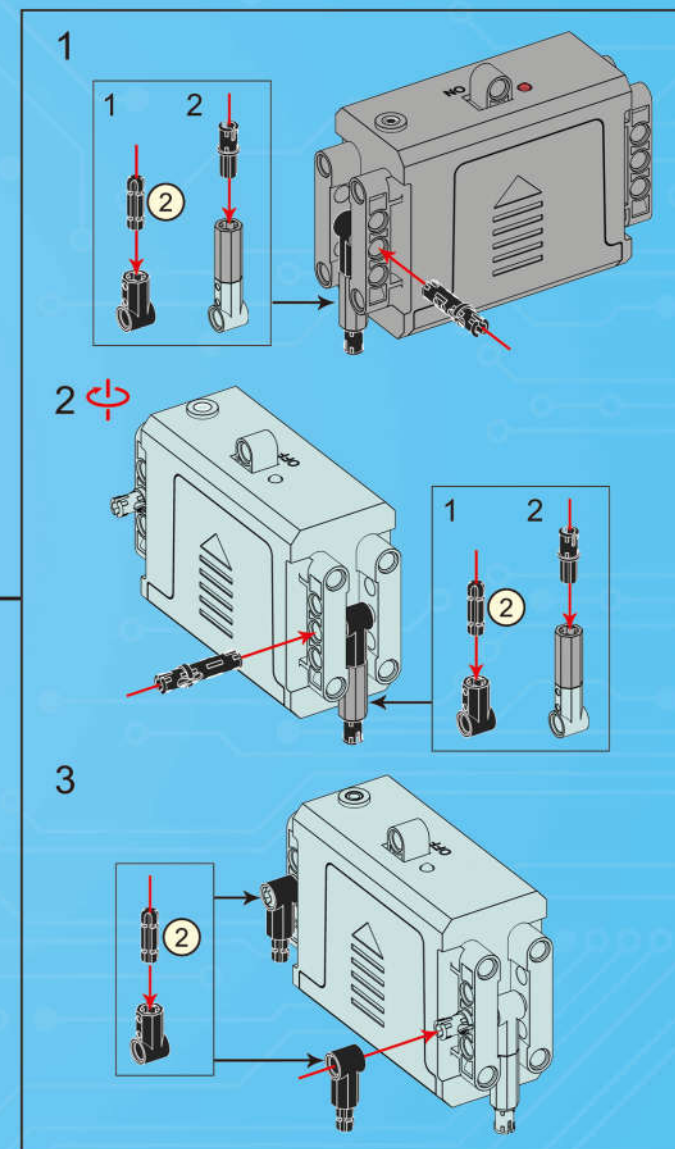
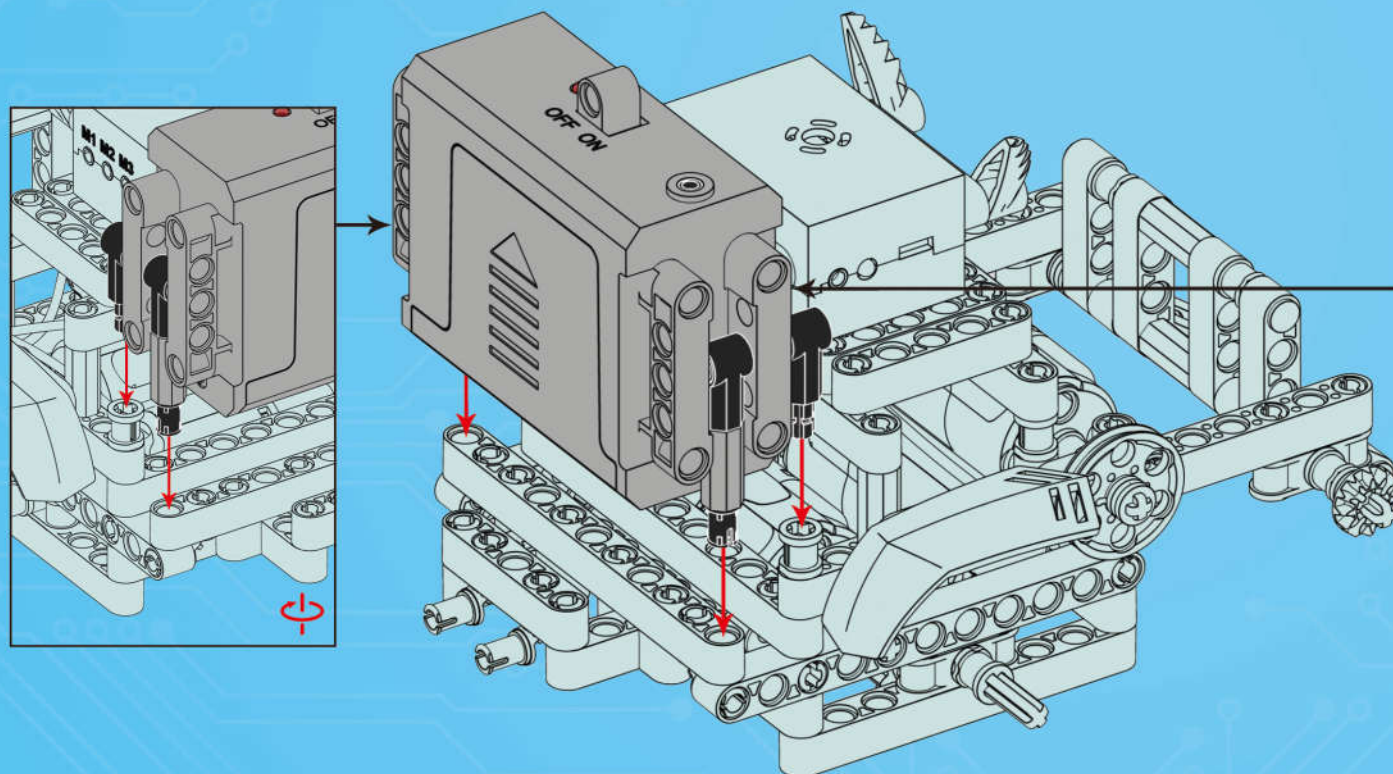


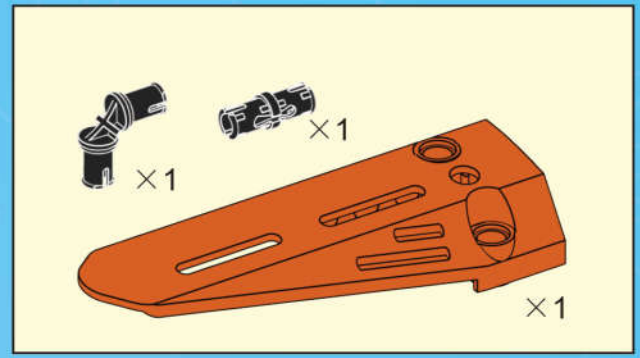
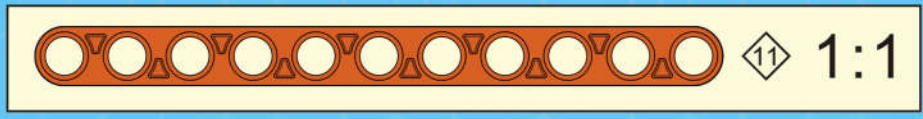
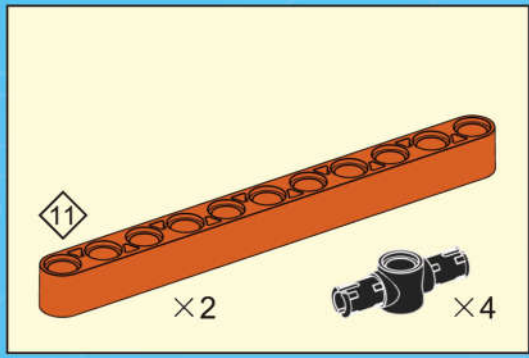
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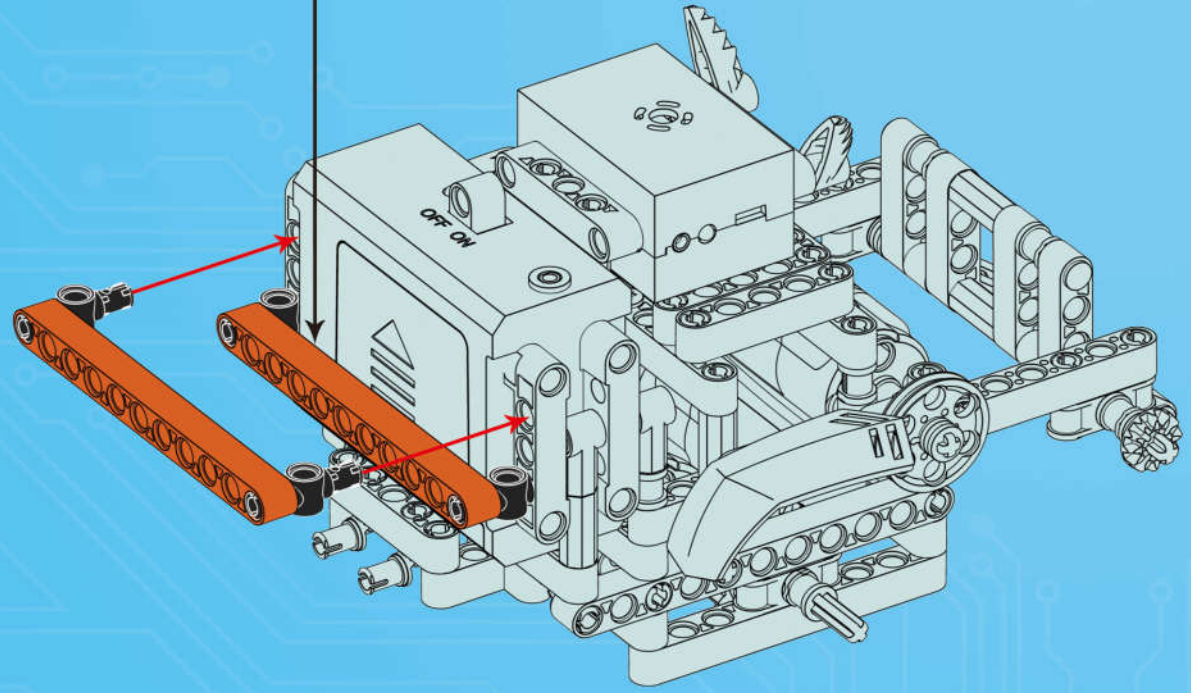
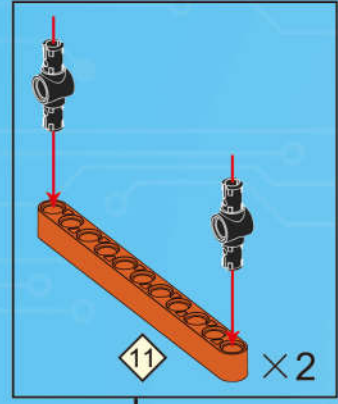


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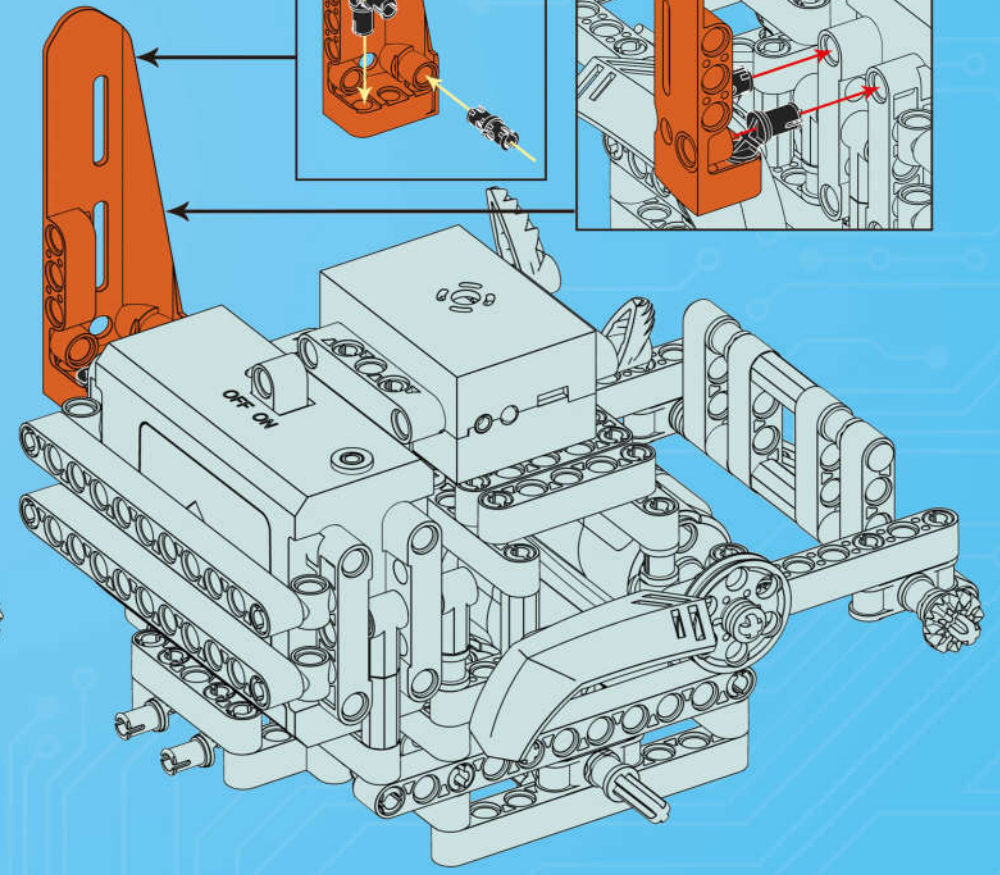
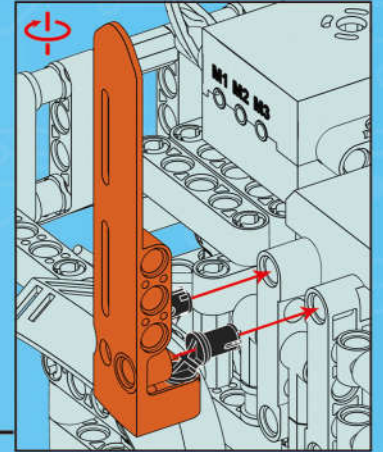
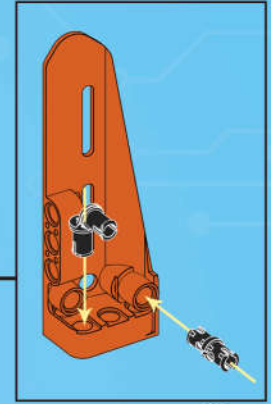


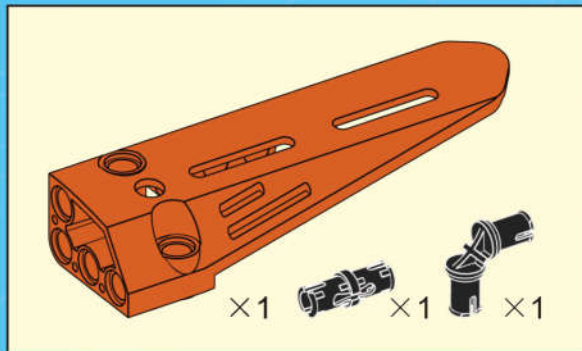


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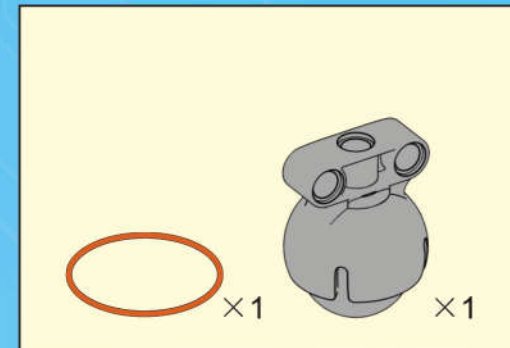
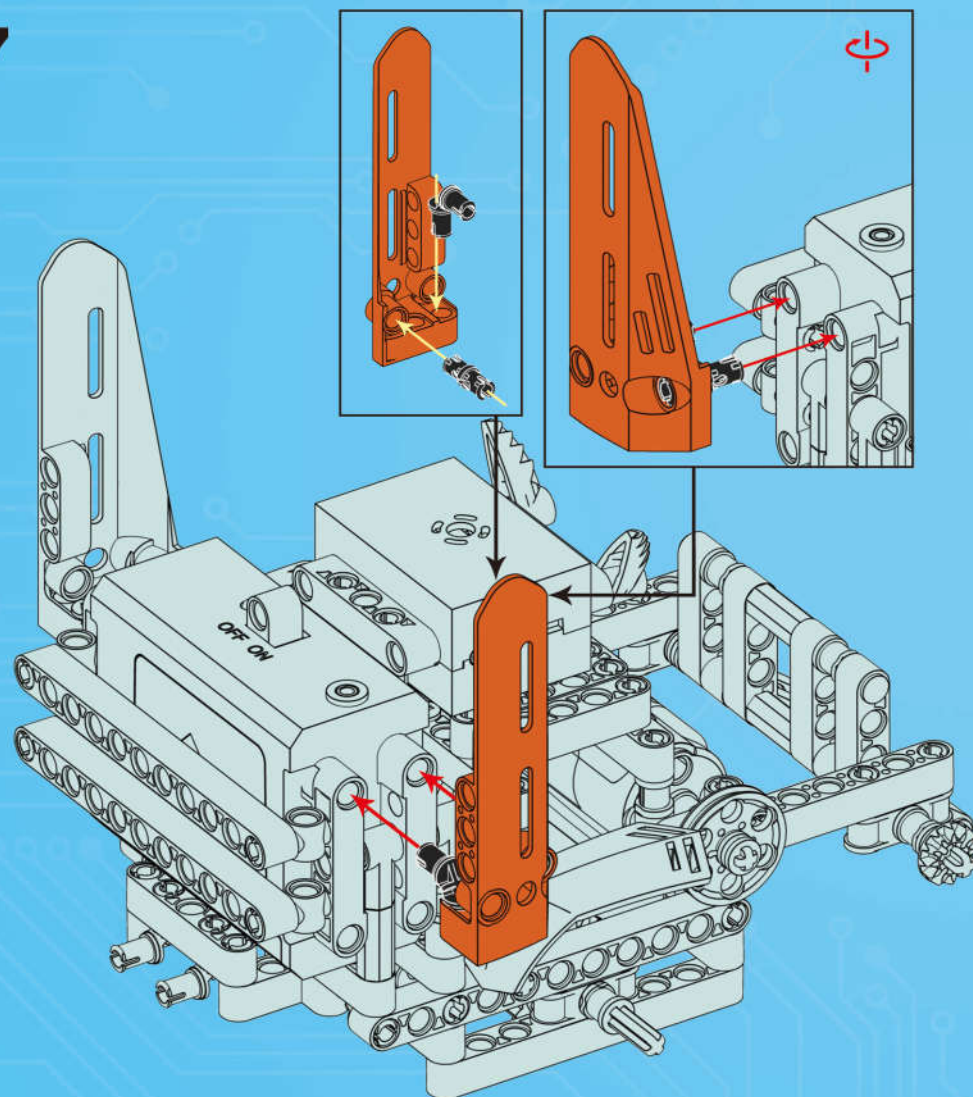


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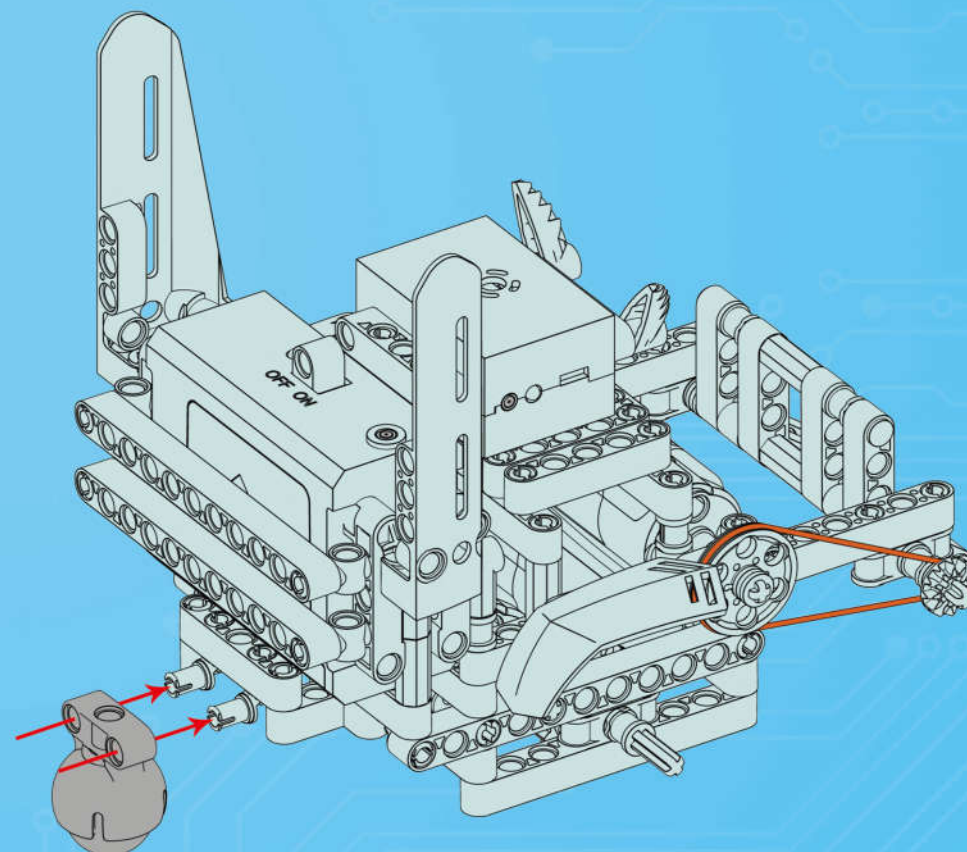


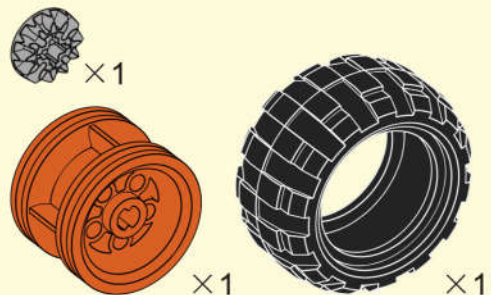


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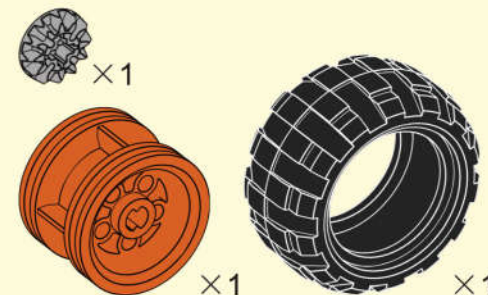
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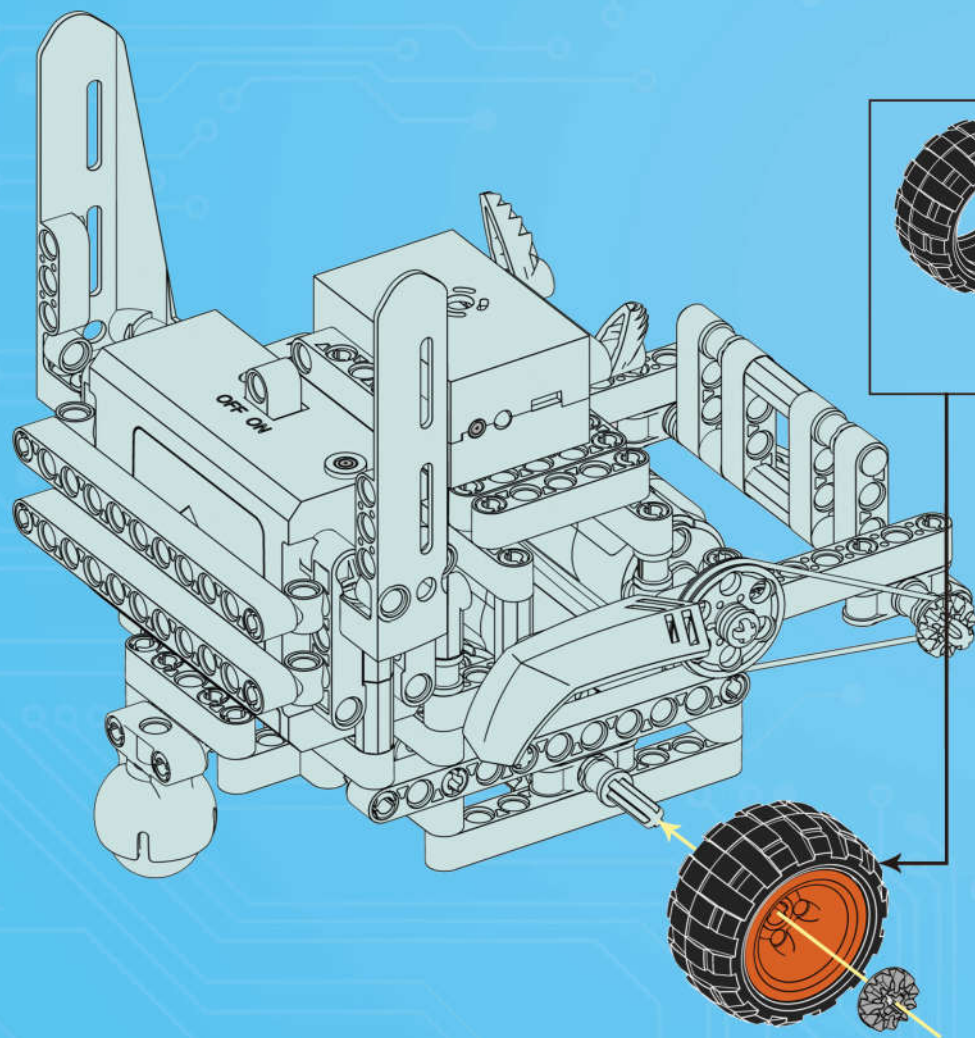


Tips:

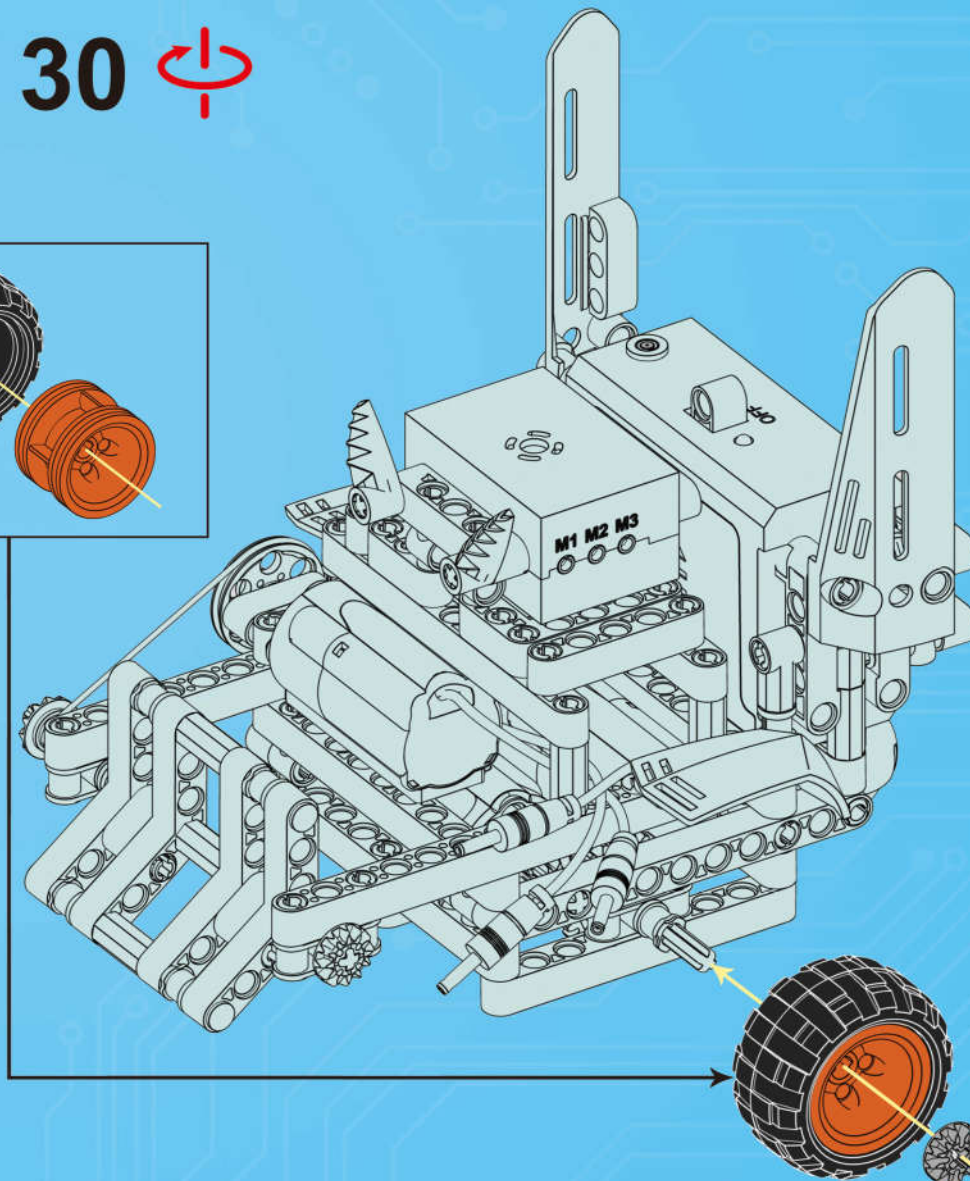
When the wheel is inserted into the cross axis, the robot can be turned upside down, Shored up the cross axis from the robot's inside by hand, so as to prevent the cross axis sliding inwards.



29

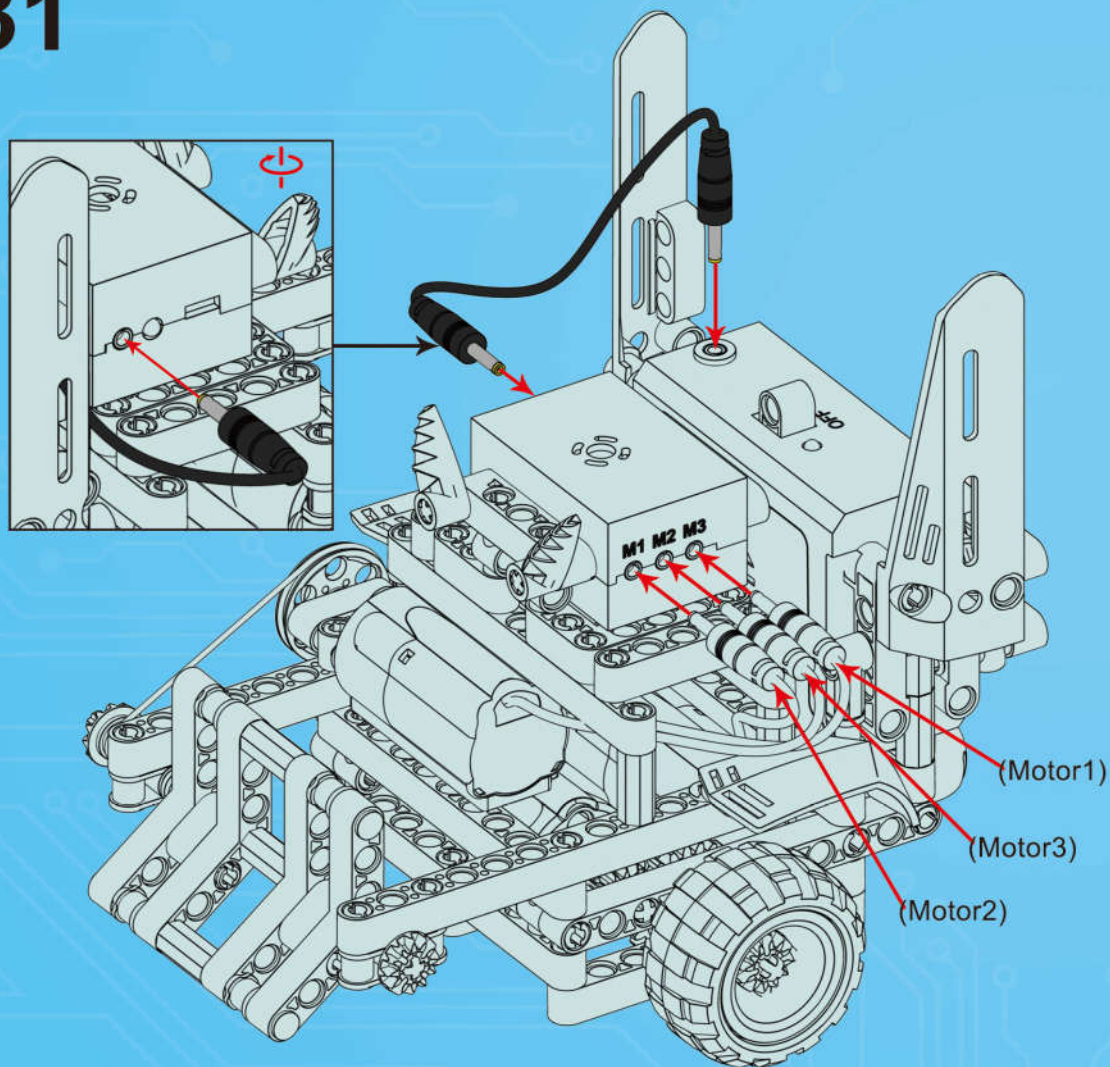


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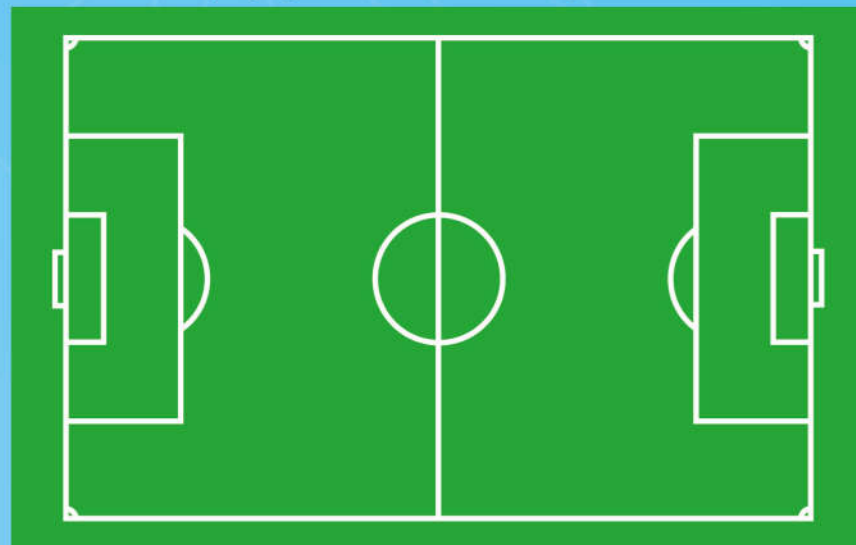


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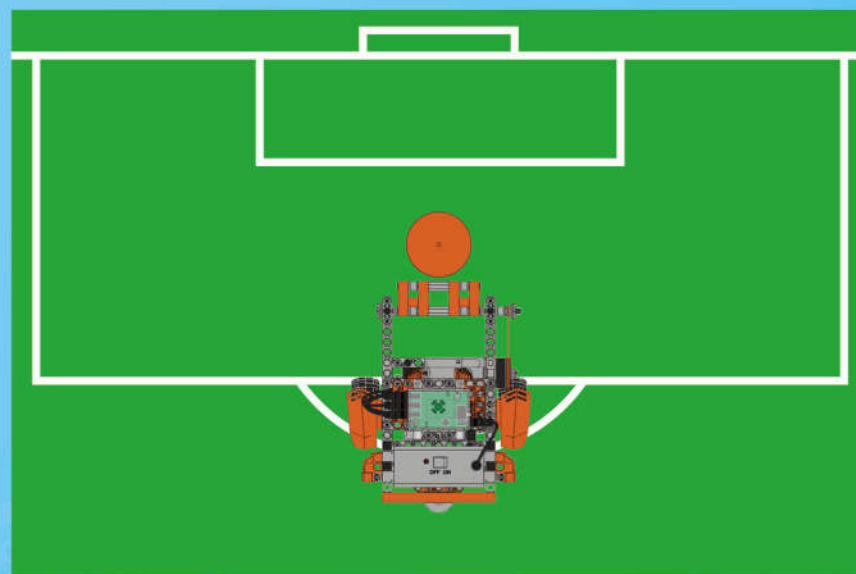


Kindly reminder:

This product can simulate a football match. The following figure is a simulation of the playing field, for reference only.



A simulation of the playing field



When organize a soccer game of somatosensory remote control robots, if a robot is in driving mode, it can simulate the dribbling movement of a football player. If switches to hit mode, It can do the movement of penalty kick.