| Recommended product technology | | Product example | For technical protective devices | Recommended use in safety circuits accord- ing to EN ISO 13849-1 up to Performance Level (PL) ¹⁾ | | | | | | |
|--|-------------|--|-------------------------------------|---|---|----------------|----|-----|--|--|
| sens:Control - safe control solutions | | | | а | b | с | d | е | | |
| Safety relays | | UE10 to UE48 | | De | | ding ice t | | | | |
| Safety controllers | | Flexi Soft, Flexi Classic | | | | | | | | |
| Safe sensor cascade | 5555 | Flexi Loop | | | | | | | | |
| Motion Control safety controllers | | Flexi Soft Drive Monitor, Speed Monitor, Standstill Monitor | | | | | | | | |
| Safety switches | | | | а | b | с | d | е | | |
| Safety switches with separate actuator ²⁾ | j 🐋 | i12S, i16S, i17S, i110S With second safety switch | | | | | 3) | | | |
| Safety locking devices ²⁾ | [| i10 Lock, i110 Lock, i14 Lock, i15 Lock, i200 Lock With second safety switch | | | | | | | | |
| Safety position devices ²⁾ | 1 | i10P, i10R, i110P, i110R With second safety switch | | | | | 3) | | | |
| Inductive safety switches | 🌮 🗞 | IN4000 Standard, IN4000 Direct IN3000 Direct | | | | | | | | |
| Transponder safety switches | | TR4 Direct, STR1 | | | | | | | | |
| Magnetic safety switches ²⁾ | % | RE1, RE2 | | | | | | | | |
| Safety command devices ²⁾ | | ES11, ES21, i110RP, i150RP, E100 | | | | | | | | |
| Safety encoders | | | | а | b | с | d | е | | |
| Safety encoders | ١ | DFS60S Pro | | | | | | | | |
| Standard sensors | | | | а | b | с | d | е | | |
| Photoelectric, magnetic and inductive sensors | 11 1 88 11 | W12, VS/VE-18-2, MZT8, IME12 | | No | | r per tecti | | nel | | |

¹⁾ The EN ISO 13849-1 standard and the information provided in the operating instructions are to be observed to achieve the required performance level. ²⁾ Performance Level d can be achieved with one switch only, if fault exclusion measures are taken. Please ask the experts from SICK about this. ³⁾ The Performance Level can only be achieved in combination with a suitable safety control solution.

| Safe control | ol and communication |
|--------------|--|
| | Safe control units for linking and evaluating a variet of input signals of the safety functions as well as fo generating output signals |
| Safe Motio | on Control |
| | Monitoring of motor standstill, speed and direction of a machine or a machine part movement Release of the locking devices of physical guards in the absence of a hazardous movement Safeguarding of automated guided vehicles in combination with opto-electronic protective devices Service mode with limited speed |
| Opto-elect | ronic protection |
| 3 | Assembly workplaces for small components Machine operator works very close to the hazardou point of the machine Machine stopping time is very short Safe detection of fingers with a detection capability of 14 mm |
| | Assembly/handling machines for big components Machine operator works close to the hazardous point of the machine Machine stopping time is very short Safe detection of hands with a detection capability up to 40 mm |
| | Interaction with the machine is regular, but not frequent Safe detection of persons with a detection capability up to 150 mm or multiple light beam systems |
| | Muting, entry/exit monitoring Application for machines with automatic material transport systems Safe detection of persons with a detection capability up to 150 mm or multiple light beam systems |
| | Interaction with the machine is regular, but not frequent Allows flexible access Safe detection of persons with multiple light beam systems |
| | Stationary hazardous area protection with person detection the hazardous area Interaction with the machine is regular, but not frequent View into the accessible hazardous area is limited Safe detection of legs with a detection capability up to 70 mm |
| 1 | Mobile hazardous area protection with person detection when approaching Protect persons while vehicles are moving Safe detection of legs with a detection capability up to 70 mm |

nterlocking and locking of physical guards



• Interlocking of physical guards without locking device (e.g., swing doors, flaps, sliding doors)



Locking of physical guards with temporary prevention of entry or access

- During operation, stopping, shutdown of a machine
 Machine function that presents a hazard takes too long to stop
- Manufacturing process should not be interrupted

Safe position monitoring of machines and machine parts



• Safe monitoring of machine positions, e.g., for robots



Safe monitoring of machine end positions

 Safe position monitoring for steering axes and swivel arms, for example, to control monitoring fields of safety laser scanners on automated guided vehicles

Emergency stop, enable and reset



 Supplementary protective measures for risk reduction

Emergency stop

Manual and temporary disabling of safety functions to reduce risks for

Safe machine setup
 Machine maintenance

• Resetting the protective device



SAFETY PRODUCT NAVIGATOR

APPLICATION OF SAFETY PRODUCTS OVERVIEW







FROM YOUR SAFETY APPLICATION TO A SOLUTION FROM SICK

Safety solutions from SICK make it possible to implement safety functions on your machine. This Safety Product Navigator features the most important safety technology parameters and application recommendations.

With its services, SICK supports you as a design engineer, manufacturer or operator of machines and systems in fulfilling current regulations.



Download and further information at: www.sick-safetyplus.com



SICK's 130-page Guide for Safe Machinery has facilitated the construction of thousands of safe machines in six straightforward steps. The guide contains structured information on the following topics:

- Legal requirements for machines in the European Union and implementation
- Requirements for safe machinery in North America in the North American edition
- (number 708282)
- Safety-relevant European guidelines, directives and standards
- Selection and use of protective devices
- Examples of how to protect machines and persons against accidents
- Examples of how to apply the EN ISO 13849-1 and EN 62061 standards to determine PL or SIL
- Calculation of minimum distances between the hazardous point and the protective device



Risk graph for determining the required performance level in accordance with EN ISO 13849-1



¹⁾ The EN ISO 13849-1 standard and the information provided in the operating instructi ²⁾ Electro-sensitive protective devices with 1 or 2 beams are only allowed for personnel detection if permitted by the risk assessment and in combination with

additional measures

³⁾ The Type and the relation between the type and the performance level are described in the IEC 61496 series of standards.

Safety PLUS

| Product example | For technical protective devices | Recommended in safety circuits according to EN ISO 13849-1 up to Performan Level (PL) ¹⁾ | | iits 9-1 | | Detection capability | | | | | | | | | | | | | |
|---|----------------------------------|--|-------|-------------|-------------------------|-----------------------|-----------------|----|---|------|-----------------|------|----|----|----|-----------------|----|----|----|
| | | | | | | | Number of beams | | | | Resolution d/mm | | | | | | | | |
| | | а | b | с | d | е | 1 | 2 | 3 | 4-9 | 150 | 70 | 50 | 40 | 34 | 30 | 24 | 20 | 14 |
| S3000, S3000 PROFINET IO S300, S300 Mini, microScan3 | | | | | | | | | | | | | | | | | | | |
| V300 Work Station Extended | | | | | | | | | | | | | | | | | | | |
| deTec2 | | | | | | | | | | | | | | | | | | | |
| miniTwin2 | | | | | | | | | | | | | | | | | | | |
| deTec4 | | | | | | | | | | | | | | | | | | | |
| miniTwin4 | | | | | | | | | | | | | | | | | | | |
| C4000 | | | | | | | | | | | | | | | | | | | |
| C4000 Fusion | | | | | | | | | | | | | | | | | | | |
| M2000 | | | | | | | | | | | | | | | | | | | |
| M4000 | | | | | | | 2 | 2) | | | | | | | | | | | |
| L2000 | | | | | | | | | | r | | | | | | | | | |
| L4000, WSU/WEU26-3 | | | | | | | | | | l | | | | | | B | | | |
| ctions are to be observed to achieve the required performance level. nel detection if permitted by the risk assessment and in combination with | | Ty | ype 2 | 3) | Ту З, 4 | pe 4 ³⁾ | | | | Body | detec | tion | | | | nd de ger de | | | |

bes of protective devices for executing safety ons



- material transport systems
- Safe detection of persons with a detection capability up to 150 mm or multiple light beam systems



- Interaction with the machine is regular, but not frequent
- Allows flexible access
- Safe detection of persons with multiple light beam systems

Stationary hazardous area protection with person detection in the presence

- Interaction with the machine is regular, but not frequent
- View into the accessible hazardous area is limited
- Safe detection of legs with a detection capability up to 70 mm



Mobile hazardous area protection with person detection when approaching

• Protect persons while vehicles are moving • Safe detection of legs with a detection capability up to 70 mm